

CS 134:
Operating Systems
Computer Hardware
Synchronization

2013-05-17 CS34

CS 134:
Operating Systems
Computer Hardware
Synchronization

Overview

Administrivia

Hardware

Overview

I/O Hardware

Interrupts

Synchronization

Critical Sections

Hardware Support

Higher-Level Mechanisms

Dining Philosophers

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Higher-Level Mechanisms

Dining Philosophers

A Bit on OS/161 & Homeworks

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└ Administrivia

└ A Bit on OS/161 & Homeworks

A Bit on OS/161 & Homeworks

Status: I'm working on it; initial setup takes a bit of time
- So when I post homework, plan for that time!

First assignment will be "get going"

You should have your group formed by now

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In the Meantime...

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└ In the Meantime...

In the Meantime...

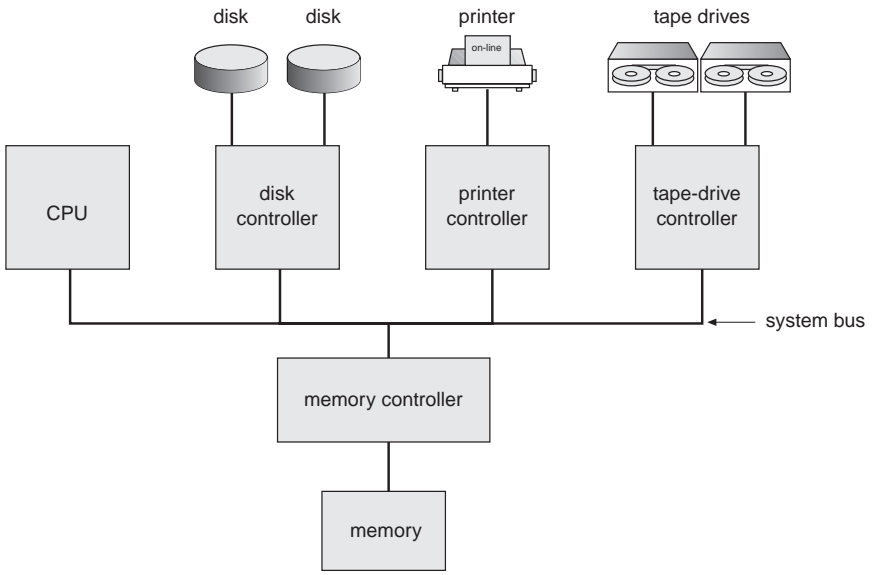
Activities to do before Thursday:

- Find out about system calls
 - Read manual pages on `getpid`, `stime`, `readdir`
 - About how many system calls does Linux have? (Hint: manual pages live in `/usr/share/man`)
 - Run `strace` (on Knuth or other Linux) on a simple program such as `true`, `echo`, or `ls`

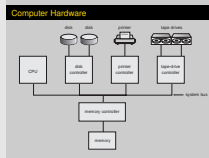
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Computer Hardware



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Computer Hardware



Computer Hardware—CPU & Memory

Need to perform computation!



- ▶ Memory contains program instructions and program data
- ▶ Processor registers maintain processor state. Registers include:
 - ▶ General purpose (address & data) registers
 - ▶ Instruction pointer (aka program counter)
 - ▶ Stack pointer(s)
 - ▶ Control and status registers

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│ └── Computer Hardware—CPU & Memory

Computer Hardware—CPU & Memory

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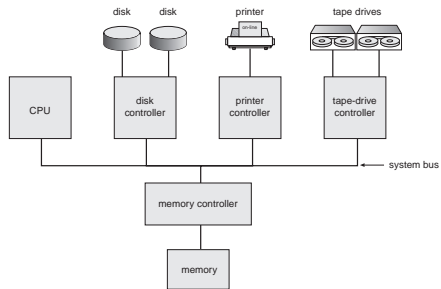


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Computer Hardware—I/O Devices

Need to communicate with the world!

- ▶ I/O devices and CPU execute concurrently
- ▶ Devices have hardware controllers
 - ▶ Handles devices of a particular device type
 - ▶ Some level of autonomy
 - ▶ Local buffer
- ▶ I/O is from the device to local buffer of controller



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 - I/O Hardware
 - Computer Hardware—I/O Devices

Computer Hardware—I/O Devices

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Programmed I/O

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│ ├── I/O Hardware
│ └── Programmed I/O

Programmed I/O

After I/O starts, control returns to user program only on I/O completion

- ▶ CPU waits until I/O completes.
- ▶ At most one I/O request is outstanding at a time
- ▶ No simultaneous I/O processing

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Polled I/O

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 └─ Polled I/O

Polled I/O

Polled I/O == Querying the I/O device
Separate I/O into two parts:
- Initiation
- Polling
Advantages?

Polling == Querying the I/O device

Separate I/O into two parts:

- ▶ Initiation
- ▶ Polling

Advantages?

Interrupt-Driven I/O

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 └─ I/O Hardware
 └─ Interrupt-Driven I/O

Interrupt-Driven I/O

Separate I/O into two parts:
▶ Initiation
▶ Asynchronous notification

Separate I/O into two parts:

- ▶ Initiation
- ▶ Asynchronous notification

I/O in User-Level Code

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 - I/O in User-Level Code

I/O in User-Level Code

User-level code almost always uses “programmed I/O”
(e.g. `read` and `write` on a file)

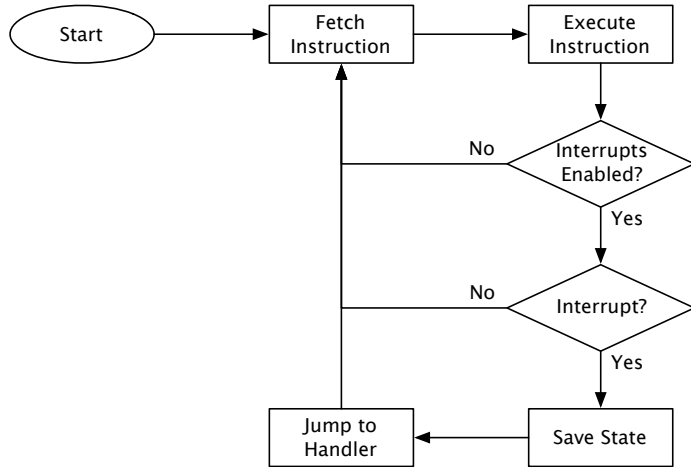
Why?

User-level code almost always uses “programmed I/O”
(e.g. `read` and `write` on a file)

Why?

Computer Hardware—CPU with Interrupts

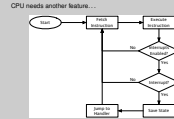
CPU needs another feature. . .



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│ └── Interrupts
│ └── Computer Hardware—CPU with Interrupts

Computer Hardware—CPU with Interrupts



Handling an Interrupt

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 └─ Interrupts
 └─ Handling an Interrupt

Handling an Interrupt

What needs to happen:

- Save state
 - All registers
 - Switch stacks?
- Find out what interrupt was ...
 - Polling
 - Vectored interrupts

What needs to happen:

- ▶ Save state
 - ▶ All registers
 - ▶ Switch stacks?
- ▶ Find out what interrupt was. . .
 - ▶ Polling
 - ▶ Vectored interrupts

Types of Interrupts

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│ └── Interrupts
│ └── Types of Interrupts

Types of Interrupts

Various types

- ▶ Software exception (also called a trap)
- ▶ Timer
- ▶ I/O
- ▶ Hardware failure

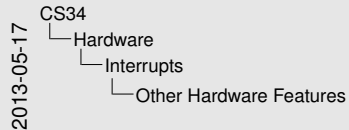
A modern operating system is interrupt driven

Various types

- ▶ Software exception (also called a trap)
- ▶ Timer
- ▶ I/O
- ▶ Hardware failure

A modern operating system is *interrupt driven*

Other Hardware Features



Other Hardware Features

We've covered interrupts, but hardware has other cool features, including:

- ▶ Caches
- ▶ Memory management
- ▶ Protection

We'll come back to hardware as we address these topics.

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Recap

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 └─ Recap

Recap

Solution to I/O waiting was:

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Recap

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Recap

Solution to I/O waiting was:

- ▶ Do something else during I/O!

But doing two (or more) things at once introduces headaches!

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Synchronization

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Synchronization

Uncontrolled access to shared data
⇒ Race conditions

Uncontrolled access to shared data

⇒ *Race conditions*

Example: The Bounded-Buffer Problem

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└ Example: The Bounded-Buffer Problem

Example: The Bounded-Buffer Problem

Two threads:

- **Producer:** Creates data items
- **Consumer:** Uses them up

We'll look at the problem using a shared array...

Two threads:

- ▶ **Producer:** Creates data items
- ▶ **Consumer:** Uses them up

We'll look at the problem using a shared array...

Okay?

```
enum { N = 128};           // maximum buffer capacity
volatile item buffer[N];  // the buffer itself
volatile int in = 0;      // buffer in cursor (moved by producer)
volatile int out = 0;     // buffer out cursor (moved by consumer)
```

```
void producer() {
    item made_item;
    for ( ; ; ) {
        made_item = make_item();
        while ((in + 1) % N == out) {
            /* buffer full---wait */
        }
        buffer[in] = made_item;
        in = (in + 1) % N;
    }
}
```

```
void consumer() {
    item usable_item;
    for ( ; ; ) {
        while ( in == out) {
            /* buffer empty---wait */
        }
        usable_item = buffer[out];
        out = (out + 1) % N;
        use_item(usable_item);
    }
}
```

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Okay?

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}
```

Okay?

```
enum { N = 128 };           // maximum capacity of the buffer
volatile item buffer[N];   // the buffer itself
volatile int count = 0;    // how many things are in the buffer
```

```
void producer() {
    int in = 0;
    item made_item;

    for ( ; ; ) {
        made_item = make_item();
        while (count == N) {
            /* buffer full---wait */
        }
        buffer[in] = made_item;
        in = (in + 1) \% N;
        ++count;
    }
}
```

```
void consumer() {
    int out = 0;
    item usable_item;

    for ( ; ; ) {
        while ( count == 0) {
            /* buffer empty---wait */
        }
        usable_item = buffer[out];
        out = (out + 1) \% N;
        --count;
        use_item(usable_item);
    }
}
```

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        --count;
        use_item(usable_item);
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}
```

Atomicity

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└─ Synchronization
 └─ Atomicity

Atomicity

The MIPS code for ++count is as follows

```
lw      $2, count
nop
addu   $2, $2, 1
sw     $2, count
```

```
lw      $2, count
nop
addu   $2, $2, 1
sw     $2, count
```

Critical-Section Problem

The critical section problem exists where $n > 1$ processes all compete to use some shared data

- ▶ But not always—certain other conditions apply
 - ▶ Roughly, different processes see conflicting data
- ▶ Code that accesses shared data = **critical section**
- ▶ Must ensure mutual exclusion for critical sections

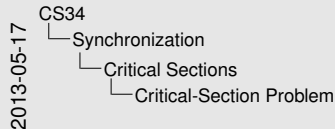
Generic Example:

```

/* Shared data... */
void foo()
{
    for ( ; ; ) {
        /* enter critical section */
        foo_cs_actions();
        /* leave critical section */
        foo_other_actions();
    }
}

void bar()
{
    for ( ; ; ) {
        /* enter critical section */
        bar_cs_actions();
        /* leave critical section */
        bar_other_actions();
    }
}

```



Critical-Section Problem

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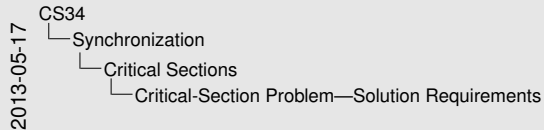
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Critical-Section Problem—Solution Requirements



Critical-Section Problem—Solution Requirements

Must satisfy the following requirements:

- Mutual Exclusion
- Progress
- Bounded Waiting (also known as No Starvation)

(Assume processes don't hang/die inside the critical section.)
(Can't assume anything about execution speeds or number of CPUs.)

Must satisfy the following requirements:

- ▶ **Mutual Exclusion**
- ▶ **Progress**
- ▶ **Bounded Waiting** (also known as **No Starvation**)

(Assume processes don't hang/die inside the critical section.)

(Can't assume anything about execution speeds or number of CPUs.)

Mutual exclusion: If a process is executing in its critical section, then no other processes can be executing in their critical sections.

Progress: If no process is executing in its critical section and there exist some processes that wish to enter their critical section, then the selection of the process that will enter its critical section next cannot be postponed indefinitely.

Bounded waiting: A bound must exist on the number of times that other processes are allowed to enter their critical sections after a process has asked to enter its critical section.

Critical-Section Problem—Solution?

```
/* Shared data---Whose turn it is */
volatile enum { Foo, Bar } turn = Foo;
```

```
void foo()
{
    for ( ; ; ) {
        while (turn != Foo) {
            /* let bar take its turn */
        }
        foo_cs_actions();
        turn = Bar;
        foo_other_actions();
    }
}

void bar()
{
    for ( ; ; ) {
        while (turn != Bar) {
            /* let foo take its turn */
        }
        bar_cs_actions();
        turn = Foo;
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Synchronization

Critical Sections

Critical-Section Problem—Solution?

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Critical-Section Problem—Solution?

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    }
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void bar()
{
    for ( ; ; ) {
        while (turn != Bar) {
            /* let foo take its turn */
        }
        bar_cs_actions();
        turn = Foo;
        bar_other_actions();
    }
}
```

Does this code satisfy our requirements?

Critical-Section Problem—Solution?

```
/* Shared data---Who is busy? */
volatile bool foo_busy = false;
volatile bool bar_busy = false;
```

```
void foo()
{
  for ( ; ; ) {
    foo_busy = true;
    while (bar_busy == true) {
      /* let bar finish */
    }
    foo_cs_actions();
    foo_busy = false;
    foo_other_actions();
  }
}
```

```
void bar()
{
  for ( ; ; ) {
    bar_busy = true;
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    bar_cs_actions();
    bar_busy = false;
    bar_other_actions();
  }
}
```

Critical-Section Problem—Solution?

How about this version?

```
void task(const int i)
{
    for ( ; ; ) {
        splhigh();
        cs_actions(i);
        spl0();
        other_actions(i);
    }
}
```

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└ Synchronization

└ Hardware Support

└ Critical-Section Problem—Solution?

Critical-Section Problem—Solution?

How about this version?

```
void task(const int i)
{
    for ( ; ; ) {
        splhigh();
        cs_actions(i);
        spl0();
        other_actions(i);
    }
}
```

Critical-Section Problem—Solution?

Or this one?

```
/* Shared data */
bool lock = false; // shared mutual exclusion lock

void task(const int i)
{
    for ( ; ; ) {
        while (test_and_set(lock)) {
            /* do nothing---wait for lock to be
               released */
        }
        cs_actions(i);
        lock = false;
        other_actions(i);
    }
}
```

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└─ Synchronization

└─ Hardware Support

└─ Critical-Section Problem—Solution?

Critical-Section Problem—Solution?

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}
```

Semaphores

You've seen 'em in 105:

```
void task(const int i) {
    for ( ; ; ) {
        P(oursem);
        cs_actions(i);
        V(oursem);
        other_actions(i);
    }
}
```

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- CS34
 - Synchronization
 - Higher-Level Mechanisms
 - Semaphores

Semaphores

```
You've seen 'em in 105:
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Semaphores

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└─ Synchronization
 └─ Higher-Level Mechanisms
 └─ Semaphores

Semaphores

Two fundamental operations

P *proberen* down dec wait Try to grab the semaphore

V *verhogen* up inc signal Release the semaphore

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This slide has animations

Semaphores

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- CS34
 - Synchronization
 - Higher-Level Mechanisms
 - Semaphores

Semaphores

Two fundamental operations
 P *proberen* down dec wait Try to grab the semaphore
 V *verhogen* up inc signal Release the semaphore

Semaphores have an associated count!

- ▶ P—Sleep until count is nonzero; once positive, decrement count
- ▶ V—Increment count, wake any sleepers

Two fundamental operations

P *proberen* down dec wait Try to grab the semaphore
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This slide has animations

Bounded Buffer with Semaphores

```
enum { N = 128 };           // maximum capacity of the buffer
volatile item buffer[N];   // the buffer itself
struct sem *empty_slot;    // any free slots? (initialized to N)
struct sem *filled_slot;   // any filled slots? (initialized to 0)
```

```
void producer()
{
    int in = 0;
    item made_item;

    for ( ; ; ) {
        made_item = make_item();
        P(empty_slot)
        buffer[in] = made_item;
        in = (in + 1) % N;
        V(filled_slot);
    }
}
```

```
void consumer()
{
    int out = 0;
    item usable_item;

    for ( ; ; ) {
        P(filled_slot);
        usable_item = buffer[out];
        out = (out + 1) % N;
        V(empty_slot);
        use_item(usable_item);
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Synchronization

Higher-Level Mechanisms

Bounded Buffer with Semaphores

Bounded Buffer with Semaphores

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void producer()           void consumer()
{
    int in = 0;           int out = 0;
    item made_item;      item usable_item;

    for ( ; ; ) {
        made_item = make_item();
        P(empty_slot);
        buffer[in] = made_item;
        in = (in + 1) % N;
        V(filled_slot);
    }
}

for ( i = 0; i < N; i++)
    P(filled_slot);
for ( i = 0; i < N; i++)
    V(empty_slot);
```


Bounded Buffer with Semaphores

```
enum { N = 128 };           // maximum capacity of the buffer
item_queue buffer;         // the buffer itself
struct sem *empty_slot;    // any free slots? (initialized to N)
struct sem *filled_slot;   // any filled slots? (initialized to 0)
struct sem *mutex;         // protection for the buffer (initialized to 1)
```

```
void producer()
{
    item made_item;

    for ( ; ; ) {
        made_item = make_item();
        P(empty_slot)
        P(mutex);
        put_item(buffer, made_item);
        V(mutex);
        V(filled_slot);
    }
}

void consumer()
{
    item usable_item;

    for ( ; ; ) {
        P(filled_slot);
        P(mutex);
        usable_item = get_item(buffer);
        V(mutex);
        V(empty_slot);
        use_item(usable_item);
    }
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```

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 - Synchronization
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Bounded Buffer with Semaphores

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        V(empty_slot);
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}
```

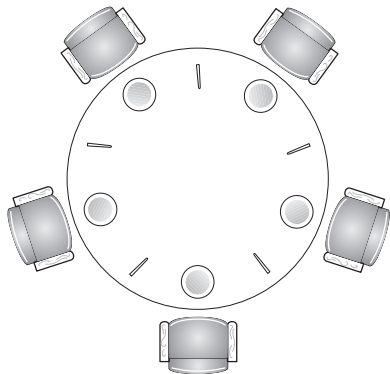
Dining Philosophers

Each philosopher alternates between periods of

- ▶ Thinking
- ▶ Eating

Each philosopher

- ▶ Shares chopsticks with neighbors
- ▶ Must not starve



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└ Dining Philosophers

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This slide has animations

Dining Philosophers

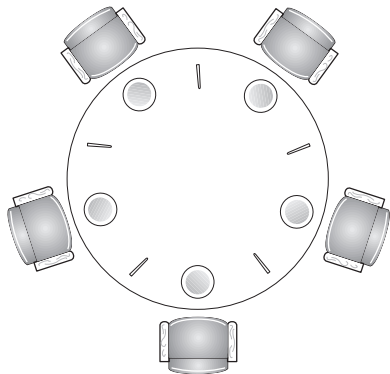
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Philosophers also must not deadlock



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This slide has animations

Philosophers with Semaphores

```
enum { N = 5 };          // five philosophers
enum { HUNGRY, THINKING, EATING } state[N]; // everyone's state
struct sem mutex = 1; // mutual exclusion for critical regions
struct sem s[N];       // one semaphore per philosopher
```

```
void philosopher(int i)
{
    for ( ; ; ) {
        think();          // philosopher is thinking
        take_chopsticks(i); // acquire chopsticks (block if need be)
        eat();            // yum-yum
        put_chopsticks(i);
    }
}
```

```
void test(int i)
{
    if (state[i] == HUNGRY && state[left(i)] != EATING
        && state[right(i)] != EATING) {
        state[i] = EATING;
        V(s[i]); // let philosopher i eat!
    }
}
```

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Dining Philosophers

Philosophers with Semaphores

Philosophers with Semaphores

```
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void philosopher(int i)
{
    for ( ; ; ) {
        think();          // philosopher is thinking
        take_chopsticks(i); // acquire chopsticks (block if need be)
        eat();            // yum-yum
        put_chopsticks(i);
    }
}

void main(int argc, char **argv)
{
    if (argc[1] == "HUNGRY" && argc[2][0] != '\0')
        state[atoi(argv[1])] = HUNGRY;
    state[0] = EATING;
    V(s[0]); // let philosopher 0 eat!
}
```

Dining Philosophers: With Semaphores (cont'd)

```

void take_chopsticks(int i)
{
    P(mutex); // enter critical region
    state[i] = HUNGRY;
    test(i); // try to acquire 2 chopsticks
    V(mutex); // exit critical region
    P(s[i]); // block if chopsticks were not acquired
}

void put_chopsticks(int i)
{
    P(mutex); // enter critical region
    state[i] = THINKING;
    test(left(i)); // see if left neighbor can now eat
    test(right(i)); // see if right neighbor can now eat
    V(mutex); // exit critical region
}

```

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└ Dining Philosophers

└ Dining Philosophers: With Semaphores (cont'd)

Dining Philosophers: With Semaphores (cont'd)

```

void take_chopsticks(int i)
{
    P(mutex); // enter critical region
    state[i] = HUNGRY;
    test(i); // try to acquire 2 chopsticks
    P(mutex); // exit critical region
    P(s[i]); // block if chopsticks were not acquired
}

void put_chopsticks(int i)
{
    P(mutex); // enter critical region
    state[i] = THINKING;
    test(left(i)); // see if left neighbor can now eat
    test(right(i)); // see if right neighbor can now eat
    V(mutex); // exit critical region
}

```