

CS 105  
Malloc Lab: Writing a Dynamic Storage Allocator  
See Web page for due date

## 1 Introduction

In this lab you will be writing a dynamic storage allocator for C programs, i.e., your own version of the `malloc`, `free` and `realloc` routines. You are encouraged to explore the design space creatively and implement an allocator that is correct, efficient and fast.

## 2 Logistics

As usual, you must work in pairs. Any clarifications and revisions to the assignment will be e-mailed to the class list or posted on the course Web page.

## 3 Handout Instructions

Start by downloading `malloclab-handout.tar` from the Web page to a protected directory in which you plan to do your work. Then give the command: `tar xvf malloclab-handout.tar`. This will cause a number of files to be unpacked into the directory. The only file you will be modifying and handing in is `mm.c`. The `mdriver.c` program is a driver program that allows you to evaluate the performance of your solution. Use the command `make` to generate the driver code and run it with the command `./mdriver -V`. (The `-V` flag displays helpful summary information.)

As with other labs, `mm.c` contains a C structure named `team`, which you should fill in with information about your programming team. **Do this right away so you don't forget.**

When you have completed the lab, you will submit only one file (`mm.c`), which contains your solution.

## 4 Getting a Low Score

The malloc lab is by far the most difficult lab in CS 105. The primary reason students have problems is that they follow poor programming practices. Here are some good ways to make the lab a disaster:

- *Don't read the hints at the end of this handout.* Just start work right away using the information on page 1.
- *Don't put any effort into the heap checker.* Writing a thorough heap checker is difficult and requires careful thinking. Never mind that the time invested pays off tenfold; just go straight to the lab.
- *Be sloppy and take shortcuts.* Convince yourself that you'll fix your sloppiness later. Take hasty approaches because you don't want to waste time writing a correct helper function. Slap in temporary code of the "Hey, why don't we try adding 4?" variety to see if it fixes your bug, and then just leave it there while you get distracted by the next problem.
- *Only call the heap checker once.* It slows your code down; besides, it keeps crashing your program with an error message you don't understand. Better to just turn it off.
- *Don't use paper to diagram your ideas.* It's easy to keep track of all those pointer manipulations in your head, right? Why kill trees drawing them out to make sure you understand what's going on?

On the other hand, if you want to make this lab a breeze, start with diagrams, design a heap checker that can handle all of the conditions listed below, and be maniacal about neatness.

## 5 How to Work on the Lab

Your dynamic storage allocator will consist of the following four functions, which are declared in `mm.h` and defined in `mm.c`.

```
int    mm_init(void);
void *mm_malloc(size_t size);
void  mm_free(void *ptr);
void *mm_realloc(void *ptr, size_t size);
```

The `mm.c` file we have given you implements the simplest but still functionally correct malloc package that we could think of. Using this as a starting place, modify these functions (and possibly define other private static functions), so that they obey the following semantics:

- `mm_init`: Before calling `mm_malloc` `mm_realloc` or `mm_free`, the application program (i.e., the trace-driven driver program that you will use to evaluate your implementation) calls `mm_init` to perform any necessary initialization, such as allocating the initial heap area. The return value should be 0 if all was OK, and -1 if there was a problem during initialization.

**Note:** `mm_init` may be called more than once by the driver. It should not remember any external state, and should not assume that it is only called once. Each call to `mm_init` should reset the allocator, forgetting everything that has gone before.

- `mm_malloc`: The `mm_malloc` routine returns a pointer to an allocated block of at least `size` bytes. The entire allocated block should lie within the heap region and should not overlap with any other allocated chunk. Note that the returned value should point to the “payload”—the area available for use by the caller—rather than to whatever header you might choose to put on the block.

We will compare your implementation to the version of `malloc` supplied in the standard C library (`libc`). The `libc malloc` always returns payload pointers that are aligned to 8 bytes, which is excessive on Linux; your `malloc` implementation can gain a few utilization points by aligning only to 4 bytes.

In the Linux specification, it is legal to allocate 0 bytes; your implementation should behave gracefully in this case. It is up to you whether to return `NULL` or to return a non-`NULL` pointer that can legally be passed to `mm_free`.

- `mm_free`: The `mm_free` routine frees the block pointed to by `ptr`. It returns nothing. This routine is only guaranteed to work when the passed pointer (`ptr`) was returned by an earlier call to `mm_malloc` or `mm_realloc` and has not yet been freed.

In the Linux specification, `NULL` can be passed to `free`. You can write `mm_free` to accept `NULL` pointers, but the test driver will never exercise this case.

- `mm_realloc`: The `mm_realloc` routine returns a pointer to an allocated region of at least `size` bytes with the following constraints.

- If `ptr` is `NULL`, the call is equivalent to `mm_malloc(size)`;
- If `size` is equal to zero, the call is equivalent to `mm_free(ptr)`;
- If `ptr` is not `NULL`, it must have been returned by an earlier call to either `mm_malloc` or `mm_realloc`. The call to `mm_realloc` changes the size of the memory block pointed to by `ptr` (the *old block*) to `size` bytes and returns the address of the new block. Notice that the address of the new block might be the same as the old block, or it might be different, depending on your implementation, the amount of internal fragmentation in the old block, and the size of the `realloc` request.

The contents of the new block are the same as those of the old `ptr` block, up to the minimum of the old and new sizes. Everything else is uninitialized. For example, if the old block is 8 bytes and the new block is 12 bytes, then the first 8 bytes of the new block are identical to the first 8 bytes of the old block and the last 4 bytes are uninitialized. Similarly, if the old block is 8 bytes and the new block is 4 bytes, then the contents of the new block are identical to the first 4 bytes of the old block.

These semantics match the semantics of the corresponding `libc malloc`, `realloc`, and `free` routines. Type `man malloc` to the shell for complete documentation.

## 6 Some Notes on the Textbook

The sample code in the textbook, while useful as an overview, should not be followed slavishly. In particular, the `GET`, `PUT`, `NEXT_BLK`, and `PREV_BLK` macros given on page 746 are an extremely bad idea that will

get you into trouble and lead to much lost debugging time. The `MAX`, `PACK`, `GET_SIZE`, and `GET_ALLOC` macros are the only sensible ones on that page (and even they would be better done as inline functions). Otherwise, you should follow the example in the provided `mm.c`, which uses a C structure to describe the block header, and then uses well defined inline functions to convert payload pointers into header pointers and vice versa. (By the way, `CHUNKSIZE` is an acceptable idea, though it is commented incorrectly.)

Also, the code for `extend_heap` on page 746 is incorrect. Since `extend_heap` returns `-1` on failure, and since many valid pointers are negative when cast to `int`, the test on line 8 should check for equality to `-1`:

```
if ((int)(bp = mem_sbrk(size)) == -1)
```

Actually, good style would break this into two much more readable lines:

```
bp = mem_sbrk(size);
if ((int)bp == -1)
```

## 7 Heap Consistency Checker

Dynamic memory allocators are notoriously tricky beasts to program correctly and efficiently. They are difficult to program correctly because they involve a lot of untyped pointer manipulation. You will find it very helpful to write a heap checker that scans the heap and checks it for consistency.

Some examples of what a heap checker might check are:

- Is every block in the free list marked as free?
- Are there any contiguous free blocks that somehow escaped coalescing?
- Is every free block actually in the free list?
- If you use an explicit free list, do the pointers in the free list point to valid free blocks?
- Do any allocated blocks overlap?
- Do the pointers in a heap block point to valid heap addresses?

Note that some of the above checks will require extra support in your data structures. For example, you might need a “marked” bit in the header.

Your heap checker will consist of the function `int mm_check(void)` in `mm.c`. It will check any invariants or consistency conditions you consider prudent. If a problem is discovered, it should print out a message and **abort the program immediately**. You are not limited to the listed suggestions nor are you required to check all of them.

This consistency checker is for your own debugging during development. Since it will slow your allocator down, you should make it easy to disable the checker. The easiest way to do that is with a preprocessor macro:

```
#if 1
#define MM_CHECK() mm_check()
#else
#define MM_CHECK()
#endif
```

Then, use `MM_CHECK()` whenever you want to call the consistency checker. This way, changing the “1” to a “0” in the `#if` will remove all `mm_check` calls from your code. When you submit `mm.c`, make sure to make that change, so that you will get full performance credit.

## 8 Support Routines

The `memlib.c` package simulates the memory system for your dynamic memory allocator. You can invoke the following functions in `memlib.c`:

- `void *mem_sbrk(int incr)`: Expands the heap by `incr` bytes, where `incr` is a positive non-zero integer, and returns a generic pointer to the first byte of the newly allocated heap area. The semantics are identical to the Unix `sbrk` function, except that `mem_sbrk` accepts only a positive non-zero integer argument. **Note:** your allocator should *not* assume that the memory returned by `mem_sbrk` has any particular contents. Specifically, the memory might not be initialized to zero.
- `void *mem_heap_lo(void)`: Returns a generic pointer to the first byte in the heap.
- `void *mem_heap_hi(void)`: Returns a generic pointer to the last byte in the heap.
- `size_t mem_heapsize(void)`: Returns the current size of the heap in bytes.
- `size_t mem_pagesize(void)`: Returns the system’s page size in bytes (4K on Linux systems).

## 9 The Trace-driven Driver Program

The driver program `mdriver.c` in the `malloclab-handout.tar` distribution tests your `mm.c` package for correctness, space utilization, and throughput. The driver program is controlled by a set of *trace files* that are included in the `malloclab-handout.tar` distribution. Each trace file contains a sequence of `allocate`, `reallocate`, and `free` commands that instruct the driver to call your `mm_malloc`, `mm_realloc`, and `mm_free` routines in some sequence. The driver and the trace files are the same ones we will use when we grade your submission `mm.c` file.

The driver `mdriver.c` accepts the following command line arguments:

- `-t <tracedir>`: Look for the default trace files in directory `tracedir` instead of the default directory compiled into the program.
- `-f <tracefile>`: Use one particular `tracefile` for testing instead of the default set of trace files.

- `-h`: Print a summary of the command line arguments.
- `-l`: Run and measure `libc` malloc in addition to your own malloc package.
- `-v`: Verbose output. Print a performance breakdown for each trace file in a compact table.
- `-V`: More verbose output. Prints additional diagnostic information as each trace file is processed. Useful during debugging for determining which trace file is causing your malloc package to fail.

## 10 Programming Rules

- You should not change any of the interfaces in `mm.c`.
- You should not invoke any memory-management-related library calls or system calls. This excludes the use of `malloc`, `calloc`, `free`, `realloc`, `sbrk`, `brk`, `mmap`, or any variants of these calls in your code.
- You *are* allowed to define global or `static` scalar or compound data structures, such as integers, arrays, structs, trees, or lists in your `mm.c` program. (However, note that variable-sized structures, such as trees and lists, inherently can't be defined as `static` objects.)
- Your allocator must always return pointers that are aligned to 4-byte boundaries. The driver will enforce this requirement for you.

## 11 Evaluation

You will receive **zero points** if you break any of the rules or your code is buggy and crashes the driver. Otherwise, your grade will be calculated as follows:

- *Correctness (20 points)*. You will receive full points if your solution passes the correctness tests performed by the driver program. You will receive partial credit for each correct trace.
- *Performance (35 points)*. Two performance metrics will be used to evaluate your solution:
  - *Space utilization*: The peak ratio between the aggregate amount of memory used by the driver (i.e., allocated via `mm_malloc` or `mm_realloc` but not yet freed via `mm_free`) and the size of the heap used by your allocator. The optimal ratio equals to 1. You should find good policies to minimize fragmentation in order to make this ratio as close as possible to the optimal.
  - *Throughput*: The average number of operations completed per second.

The driver program summarizes the performance of your allocator by computing a *performance index*,  $P$ , which is a weighted sum of the space utilization and throughput

$$P = wU + (1 - w) \min \left( 1, \frac{T}{T_{std}} \right)$$

where  $w = 0.6$ ,  $U$  is your space utilization,  $T$  is your throughput, and  $T_{std}$  is the estimated throughput that a standard allocator should be able to get on your system using the default traces.<sup>1</sup> The purpose of the min is to keep you from going overboard in trying to outperform the benchmark allocator. Note that the performance index favors space utilization over throughput, since  $w > 0.5$ .

Since both memory and CPU cycles are expensive system resources, we adopted this formula to encourage balanced optimization. Ideally, the performance index would reach 1.0 or 100%, **though that figure is unachievable in practice**. Since each metric will contribute at most  $w$  and  $1 - w$ , respectively, to the performance index, you should not go to extremes to optimize either memory utilization or throughput at the expense of the other. To receive a good score, you must achieve a balance.

- Style (10 points).
  - Your code should be properly decomposed into functions and use as few static or global variables as possible. (You will probably need at least one static to keep track of details about the heap.)
  - Your code should begin with a header comment that describes the structure of your free and allocated blocks, the organization of the free list, and how your allocator manipulates the free list. Each function should be preceded by a header comment that describes what the function does.
  - Each function should have a header comment that describes what it does and how it does it.
  - Your heap consistency checker `mm_check` should be thorough and well-documented.

You will be awarded 5 points for a good heap consistency checker and 5 points for good program structure and comments.

## 12 Submission Instructions

Submit only `mm.c`, using `cs105submit`. For convenience, typing “`make submit`” will submit for you. You may submit your solution for testing as many times as you wish up until the due date. When you are satisfied with your solution, submit it again. Only the last version you submit will be graded.

Note that the final grading will be done on Wilkes. While it is possible to run your allocator on other machines (including your own), the score generated by `mdriver` may be different because of speed differences. Therefore, be sure to test your allocator on Wilkes to be sure you will get the grade you think you deserve.

## 13 Hints

- *Use the `mdriver -f` option.* During initial development, using tiny trace files will simplify debugging and testing. We have included two such trace files (`short1`, `2-bal.rep`) that you can use for initial debugging.

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<sup>1</sup>The value for  $T_{std}$  is a constant in the driver that was established when the lab was set up.

- *Use the `mdriver -v` and `-V` options.* The `-v` option will give you a detailed summary for each trace file. If you give `-V` instead, the driver will also indicate when each trace file is read, which will help you isolate errors.
- *Change your `Makefile` to replace `-O2` with `-g` so you can use a debugger.* A debugger will help you isolate and identify out of bounds memory references. Only switch back to `-O2` after your code is working.
- *Call your consistency checker after every change to the heap.* Many allocator bugs show up long after the error is made; a consistency checker can catch them right away and make it easy to find them. To help catch the bugs, write your allocator so that whenever you change the heap, the new state is self-consistent. Then call the checker *right away*. A good allocator function will call the checker at the beginning, at the end, and several times in between.
- *Keep your consistency checker up to date.* **NEVER** make a change to how your allocator works without fixing your consistency checker to match.
- *Start by writing an implicit-list allocator.* The trickiest parts of writing an allocator involve the manipulation of pointers (i.e., converting between payload and header pointers) and the coalescing of freed blocks. If you add to that trickiness by writing linked lists or red-black trees, you will crash and burn, and you won't have any idea where your bugs are.
- *Encapsulate your pointer arithmetic in C functions.* Pointer arithmetic in memory managers is confusing and error-prone because of all the type-casting that is necessary. You can reduce the complexity significantly by writing inline functions for your pointer operations. Samples of some of these functions can be found in the supplied code.
- *Do your implementation in stages.* The first 9 traces contain requests to `malloc` and `free`. The last 2 traces contain requests for `realloc`, `malloc`, and `free`. We recommend that you start by getting your `malloc` and `free` routines working correctly and efficiently on the first 9 traces. Only then should you turn your attention to the `realloc` implementation. For starters, build `realloc` on top of your existing `malloc` and `free` implementations. But to get really good performance, you will need to build a stand-alone `realloc`.
- *Use a profiler.* You may find the `gprof` tool helpful for optimizing performance.
- *Start early!* It is possible to write an efficient `malloc` package with a few pages of code. However, we can guarantee that it will be some of the most difficult and sophisticated code you have written so far in your career. So start early, and good luck!