

A Pedagogical Framework for Modeling and Simulating Intelligent Agents and Control Systems

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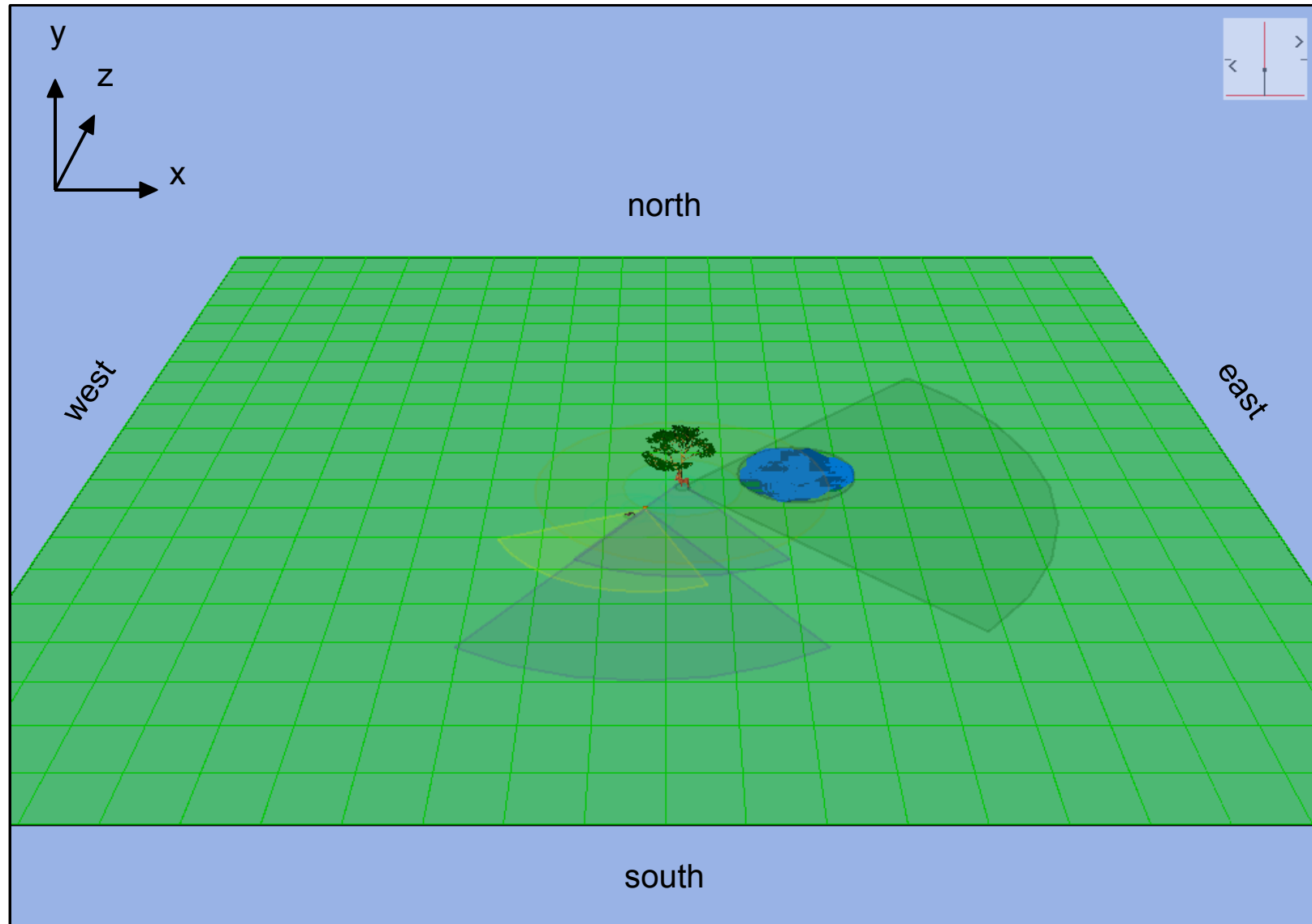
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Motivation

- Student programming assignments
 - too much troublesome administrative overhead
 - effort directed toward programming, not AI
 - non-reusable hacks
- Student-friendly AI modeling and simulation framework
 - manages components, agents, graphics, logging, etc.
 - facilitates controlled experiments
 - promotes meaningful analysis

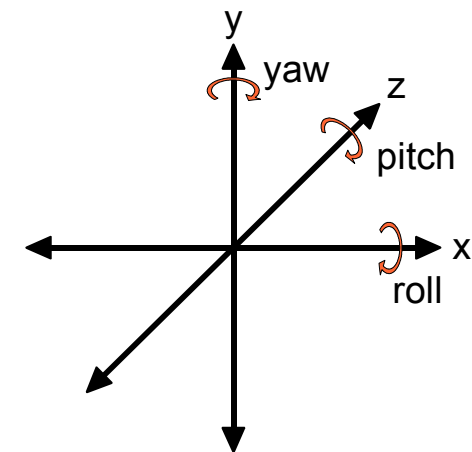
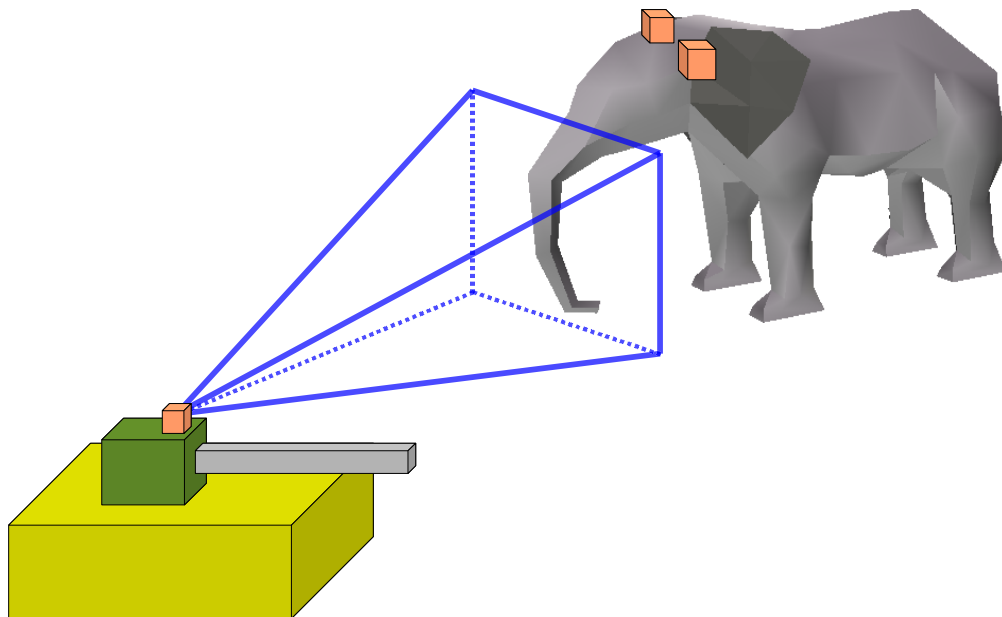
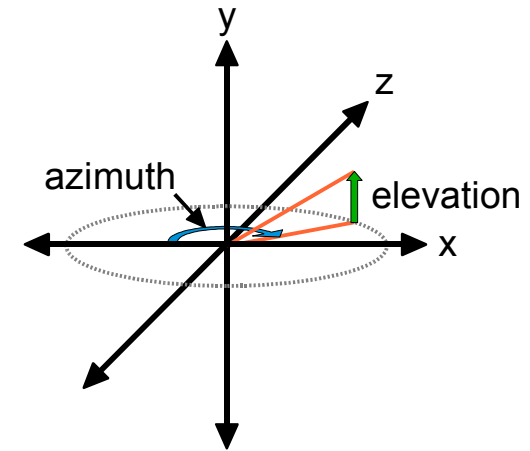
Environment

- 3D tabletop world of arbitrary scale



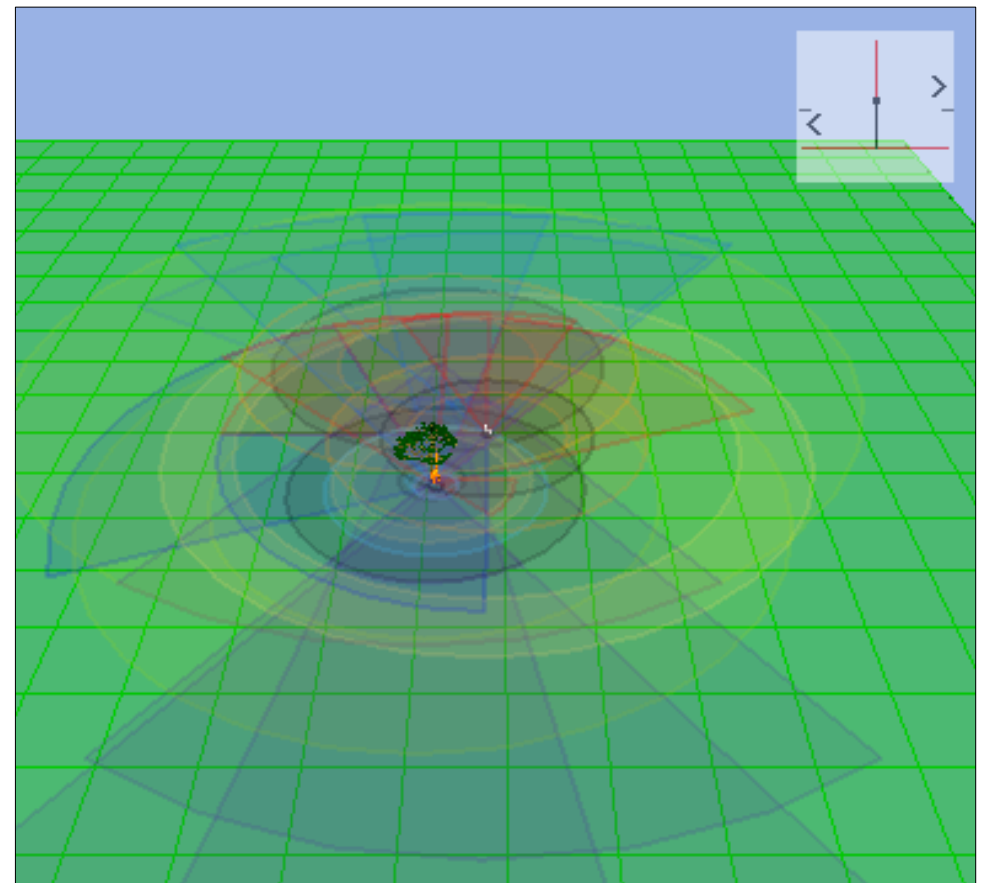
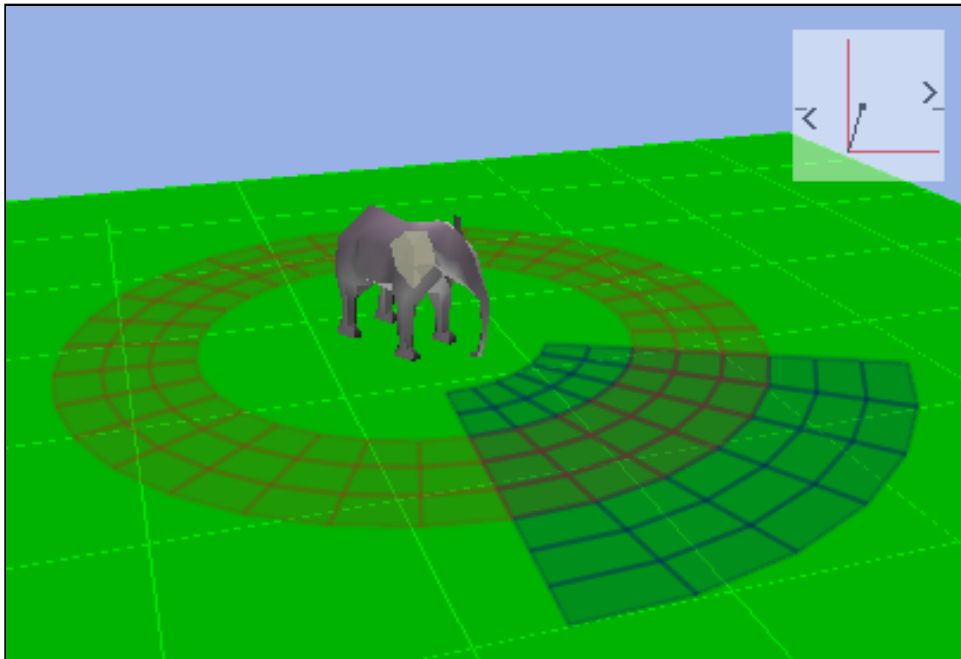
Components

- Hierarchical building blocks/infrastructure for agents
 - input/processing/output functionality
 - tedious, error-prone engineering aspects
 - mount points
 - degrees of freedom
 - speed, acceleration, timing
 - enforces students' rules and constraints



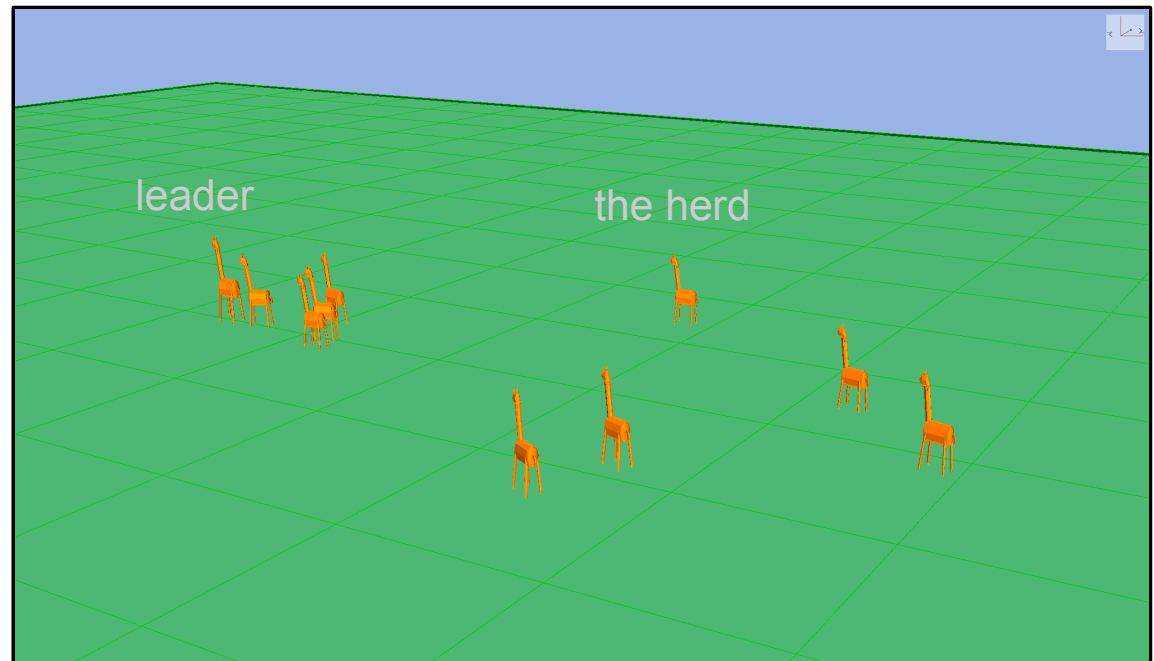
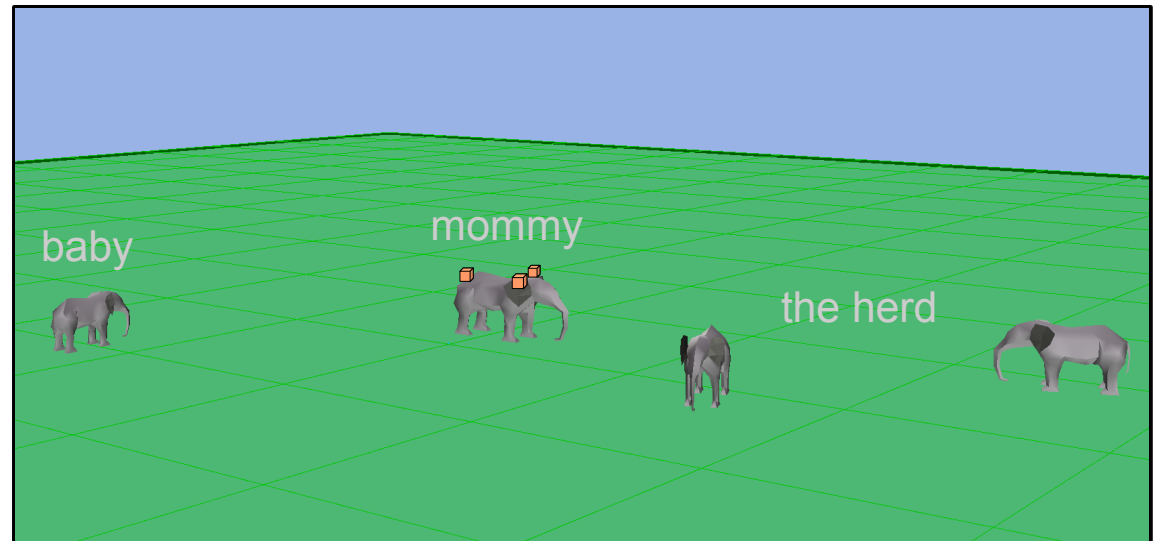
Agents

- Coordinated components in task environment
 - AI core
 - command and control
 - intercommunication



Simulation and Analysis

- Monte Carlo simulation
 - controlled experiments
 - automatic data collection
 - manual, external analysis
- Example scenarios
 - nature
 - herding
 - flocking
 - following
 - predator/prey
 - engineering
 - control systems
 - robotics
 - battle engagements



Questions?

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