

# Computer Graphics

Z Sweedyk  
Lecture 2  
9/4/00

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## Line Segments

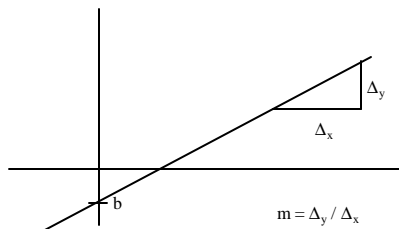
- **Scan converting line segments**
  - Naïve algorithm
  - Midpoint algorithm
  - Bresenham's algorithm
- **Clipping line segments (intro)**
  - Scissoring
  - Analytical clipping

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Line: Set of points  $(x,y)$   
satisfying  $y = mx + b$



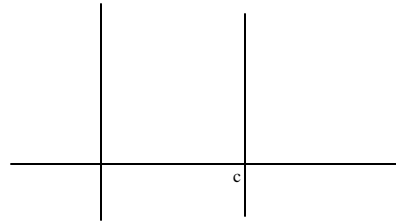
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Line: Set of points  $(x,y)$   
satisfying  $y = mx + b$

Or  $x=c$  in the case of a vertical line

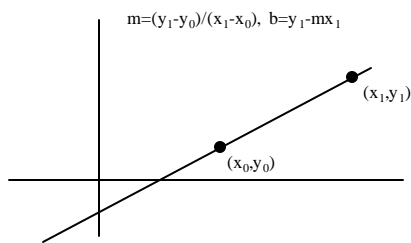


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Line through  $(x_0, y_0)$  and  $(x_1, y_1)$

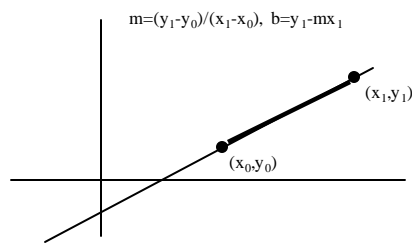


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Line segment with endpoints  
 $(x_0, y_0)$  and  $(x_1, y_1)$



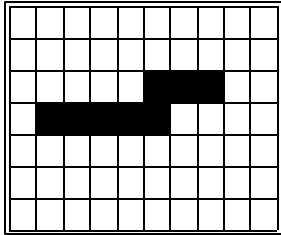
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## Scan Converting Line Segments

Which pixels should be on?

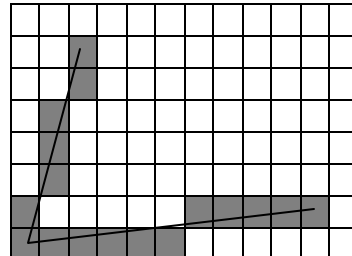


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## 1-pixel wide lines

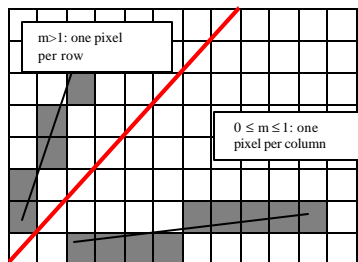


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## 1-pixel wide lines: $m \geq 0$

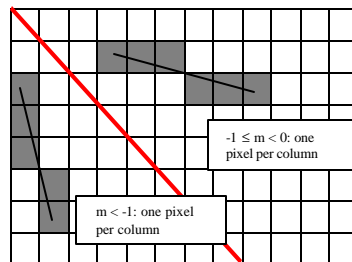


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## 1-pixel wide lines: $m < 0$



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## Scan Conversion

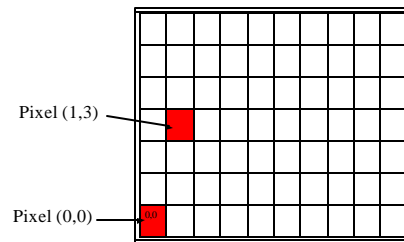
- Input: Endpoint Pixels
- Output: Pixels to turn on for a 1-pixel wide line segment

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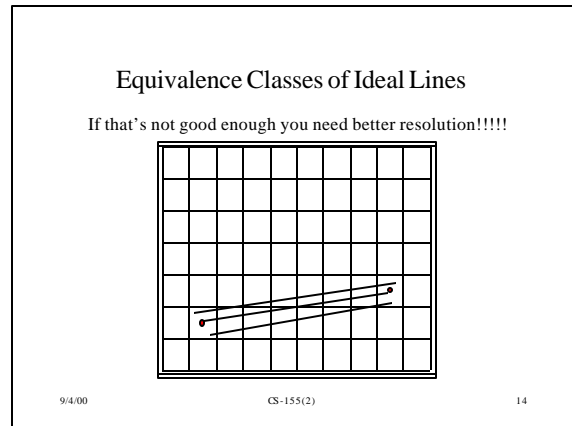
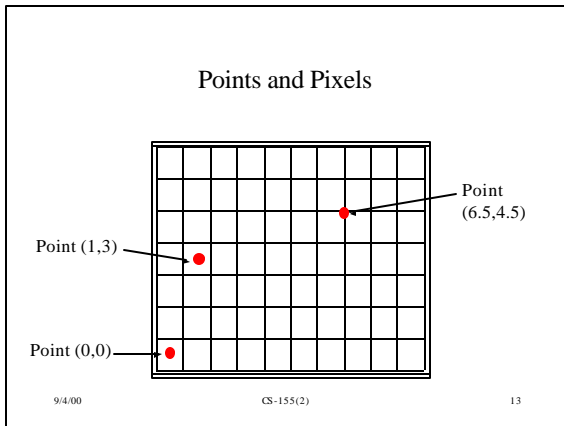
## Points and Pixels



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- ### Line Segments
- **Scan converting line segments**
    - Naïve algorithm
    - Midpoint algorithm
    - Bresenham's algorithm
  - **Clipping line segments**
    - Scissoring
    - Analytical clipping
  - **Antialiasing**
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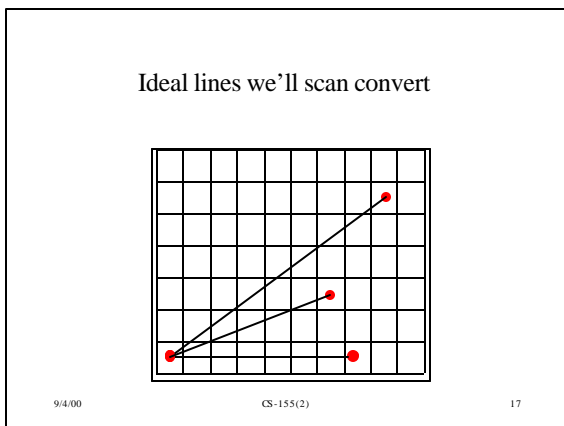
### Claim

All we have to do is solve the scan conversion problem for the special case where

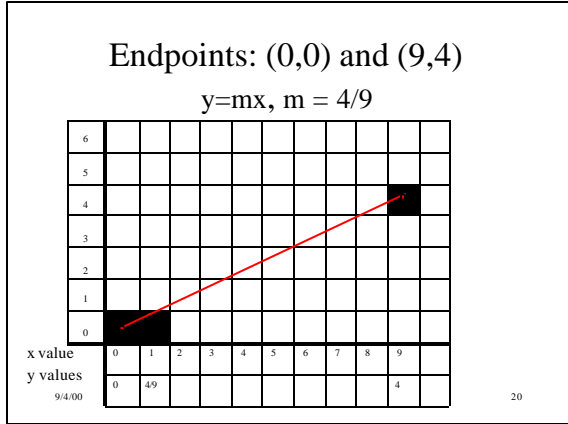
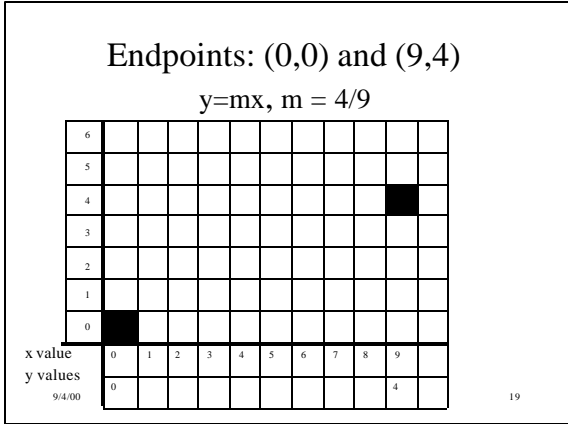
1.  $0 \leq m \leq 1$
2.  $x_0 = y_0 = 0$

We'll prove this later ... first we'll devise an algorithm for the special case.

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- ### Line Segments
- **Scan converting line segments**
    - Naïve algorithm (special case)
    - Midpoint algorithm
    - Bresenham's algorithm
  - **Clipping line segments**
    - Scissoring
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  - **Antialiasing**
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Special Case Line Algorithm 1  
 $x_0=y_0=0, 0 \leq m \leq 1$

```

SpecialCaseLine1(int x1, int y1)
int current_x=0;
float current_y=0;
float m = (float) y1 / (float) x1;
while (current_x <= x1)
    DrawPixel(current_x,round(current_y));
    current_x += 1; current_y += m;

```

Horizontal Anti-Aliasing

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- ### Line Segments
- **Scan converting line segments**
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  - **Antialiasing**
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Let's try to do better!

(i,j)

- Suppose we've just drawn the (i,j) pixel. How do we choose the next pixel?

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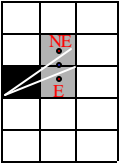
How do we choose next pixel?  
 $y=mx, 0 \leq m \leq 1$

- The options are **E** and **NE**
- Choose pixel whose center is closest to the ideal line

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### How do we choose next pixel?

$y=mx, 0 \leq m \leq 1$



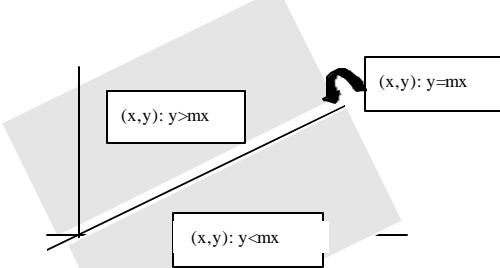
Define  $(u,v)$  to be the midpoint of the line segment between the centers of **NE** and **E**

If  $(u,v)$  lies below the ideal line: go NE  
 Else: go E

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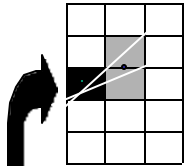
### Line in the plane

(through the origin)



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### The Test



$u = i + 1$   
 $v = j + 1/2$   
 Ideal line:  $y = mx/2$   
 If  $v < mu$  then go **NE**  
 Else go **E**

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### Special Case Line Algorithm 2

$(x_0=y_0=0 \text{ and } 0 \leq m \leq 1)$

```

SpecialCaseLine2(x1,y1)
  m = y1/x1
  i=0, j=0
  while i < x1
    write-pixel(i,j)
    if i+1/2 < m(i+1)
      i+=1, j+=1 // go NE
    else i+=1 // go E
  
```

Horizontal Axis

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### Modified Test

Is  $j + 1/2 < m(i + 1)$ ?

↕

Is  $j + 1/2 < (y_1 / x_1) \cdot (i+1)$  ?

↕

Is  $x_1(2j + 1) < 2y_1(i+1)$ ?

Important:  $x_1$  and  $y_1$  are integers!

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### Special Case Line Algorithm 3

$(x_0=y_0=0 \text{ and } 0 \leq m \leq 1)$

```

SpecialCaseLine3(x1,y1)
  i=0, j=0
  while current_i < x1
    write-pixel(i,j)
    if x1(2j+1) < 2y1(i+1)
      i+=1, j+=1 // go NE
    else i+=1 // go E
  
```

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### Endpoints (0,0) & (9,4):

If  $9(2j+1) < 8(i+1)$   
Go NE  
Else Go E

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### Endpoints (0,0) & (9,4):

If  $9(2j+1) < 8(i+1)$   
Go NE  
Else Go E

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### Special Case Line Algorithm 3

$(x_0=y_0=0 \text{ and } 0 \leq m \leq 1)$

SpecialCaseLine3 ( $x_1, y_1$ )

```

i=0, j=0
while current_i < x1
  writepixel(i,j)
  if x1(2j+1) < 2y1(i+1)
    i+=1, j+=1 // go NE
  else i+=1 // go E
  
```

Multi-processor

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### Line Segments

- **Scan converting line segments**
  - Naïve algorithm
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- Clipping line segments
  - Scissoring
  - Analytical clipping
- Antialiasing

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### Sleight of hand

```

if x1(2j+1) < 2y1(i+1)
  go NE
else go E
  
```

```

d = x1(2j+1) - 2y1(i+1) if d < 0
  go NE
else go E
  
```

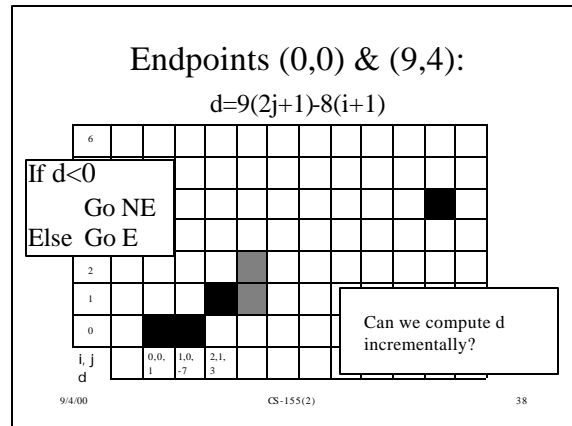
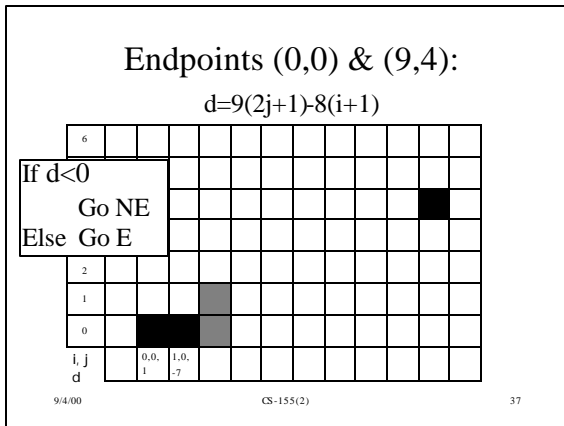
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### Endpoints (0,0) & (9,4):

$d = 9(2j+1) - 8(i+1)$

If  $d < 0$   
Go NE  
Else Go E

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### Special Case Bresenham's

$(x_0=y_0=0 \text{ and } 0 \leq m \leq 1)$

Yay!

```

SpecialCaseBresenham's (x1,y1)
i=0, j=0
d = x1-2y1
while i < x1
  write-pixel(i,j)
  if d < 0
    i+=1, j+=1, d+=2(x1-y1)
  else
    i+=1, d-=2y1
  
```

Do as addition

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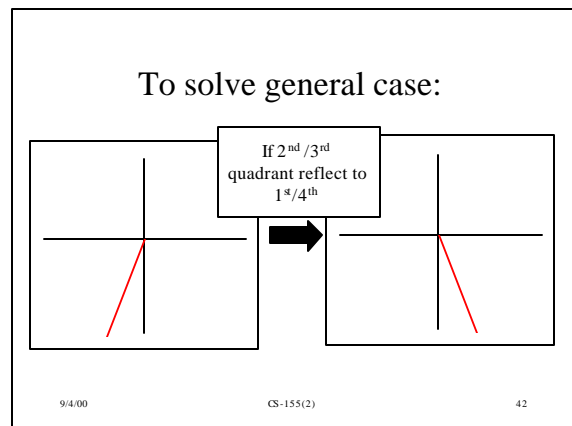
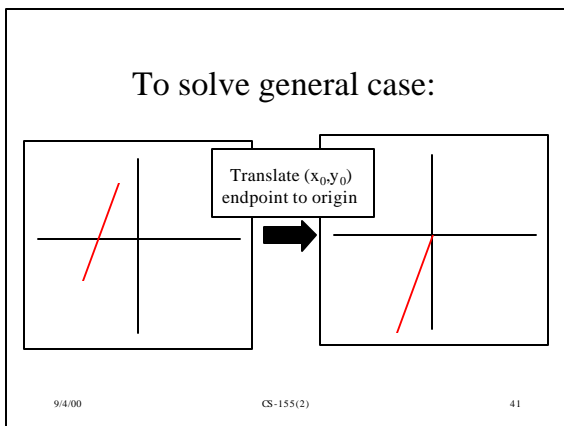
### Claim

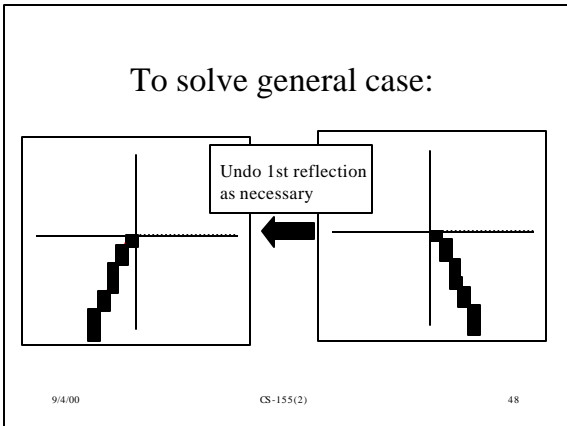
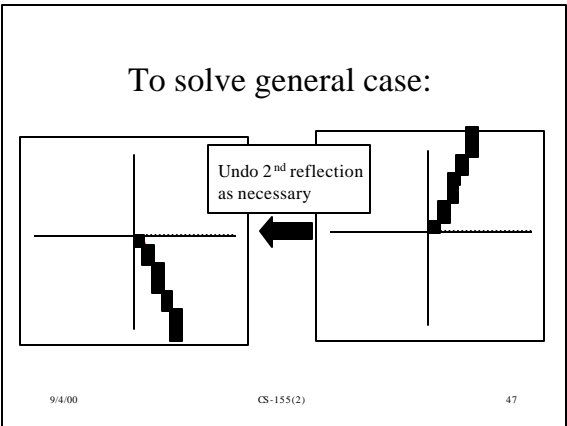
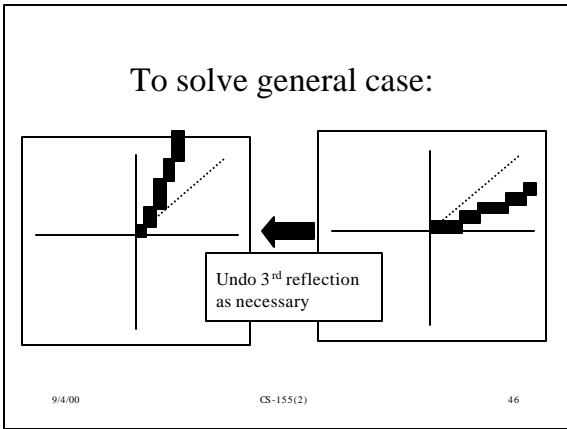
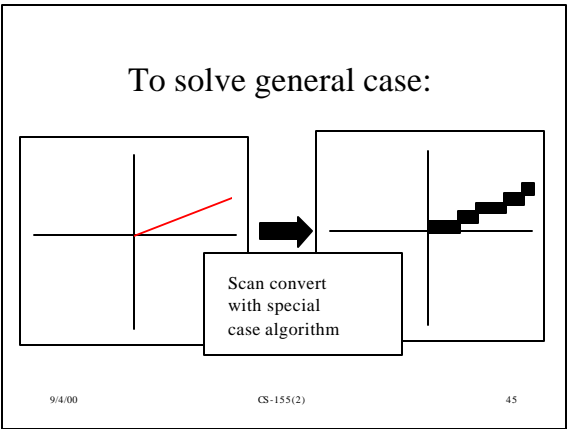
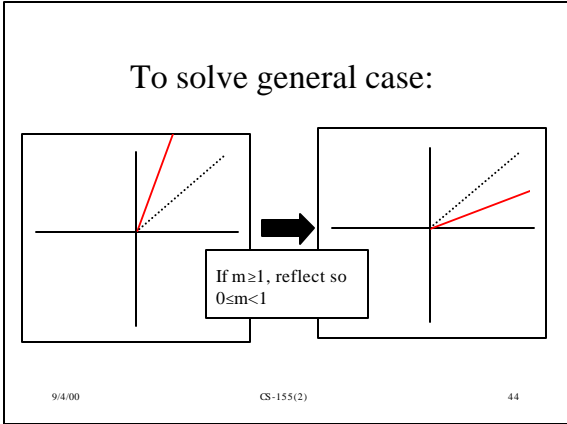
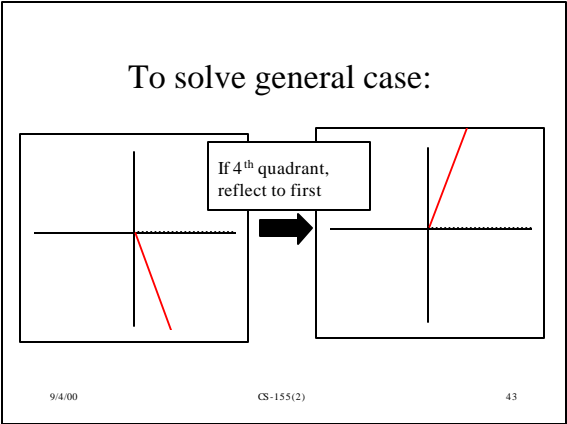
All we have to do is solve the problem for the special case where

1.  $0 \leq m < 1$
2.  $x_0=y_0=0$

Now we'll prove this claim

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### To solve general case:

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### Example

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### Implementation

- Think it through
- Get special case working first
- Endpoint order MATTERS!

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### Endpoint Order

- Why it matters

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### Implementation??

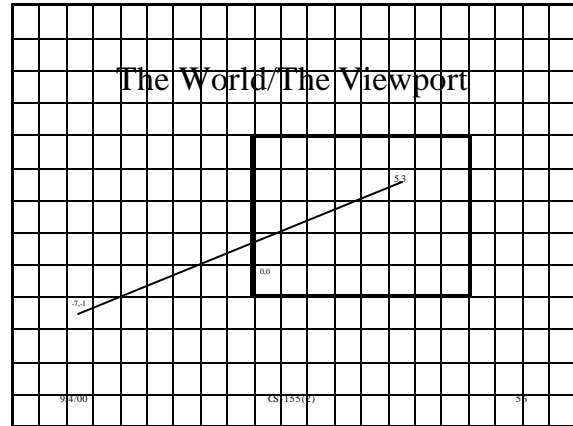
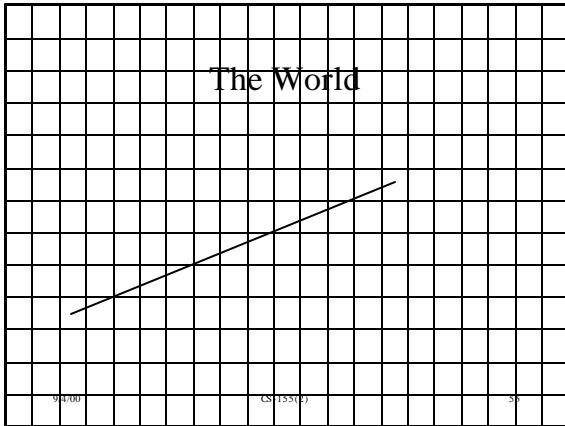
- Modified special case Bresenham's for different slopes/endpoint orders
- Reduction (in this case Bresenham's should return an array of  $y$ -values)

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### Line Segments

- Scan converting line segments
  - Naïve algorithm
  - Midpoint algorithm
  - Bresenham's algorithm
- **Clipping line segments (intro)**
  - Scissoring
  - Analytical clipping

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### Answer 1: Scissoring

- Compute pixels in world grid
- Then check chosen pixels against viewport boundaries

Problem: Inefficient

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### Answer 2: Analytical Clipping

- Compute intersection points
- Scan convert line segment between intersection points

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### But ... a' and b' are not likely to have integer coordinates

1. We could go back to using floating point operations.
2. We could round the endpoint coordinates and scan convert.
3. We could do it the right way.

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### The right way

```

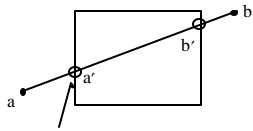
SpecialCaseBresenham's(x1,y1,xfirst,xlast)
m=y1/x1
i=xfirst, j=round(m*xfirst)
d = x1(2*j+1)-2y1(i+1)
while i < xlast
  write-pixel(i,j)
  if d < 0
    i+=1, j+=1, d+=2(x1-y1)
  else
    i+=1, d-=2y1

```

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### Answer 2: Analytical Clipping

- Compute intersection points
- Scan convert line segment between intersection points



Intersection of lines:  $y=mx$  and  $x=c$

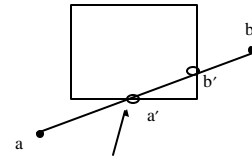
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### Answer 2: Analytical Clipping

- Compute intersection points
- Scan convert line segment between intersection points



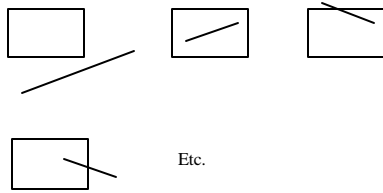
Or Intersection of lines:  
 $y=mx$  and  $y=d$

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Or



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Next time

- Clipping line segments concluded.
- Polygons

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