

CS140: Algorithms

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Lecture 15

11/07/01

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Graph Algorithms

- Topological Sort
- Single Source Shortest Path
- All Pairs Shortest Path

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Topology Sort

- Input: Directed Acyclic Graph (DAG)
- Output: Vertices of G sorted to satisfy the following condition: if there is a path from u to v in G then u occurs after v in the list.

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Topological Sort – Take 1

TopoSort(G)

If G is empty return

Choose vertex v with in-degree 0.

Return v , TopoSort($G-v$)

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Topological Sort – Take 2

TopoSort(G)

Perform DFS with timestamp

Output vertices by _____

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Single Source Shortest Path

- Input: Graph G with a designated start vertex s .
- Output: For each vertex v , the distance between s and v .

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Defs: Path Length, Distance

- In an unweighted graph
 - the length of a path is the number of edges in the path
 - the distance between two vertices is the length of a shortest path between the vertices
- We use $d_G(u,v)$ to denote the distance between u and v in G

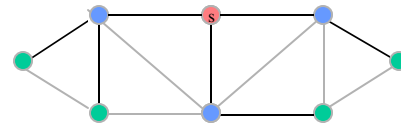
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Example: Distance

$$d_G(s,s)=0, \quad d_G(s,u)=1, \quad d_G(s,v)=2$$



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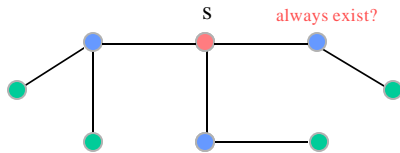
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Shortest path tree for s

A spanning tree of G such that the path between s and a vertex v in T is a shortest path in G .

Does such a tree always exist?



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Proof of Existence: Shortest path tree for s

- Order the vertices of G by distance from s :
 $v_0=s, v_1, v_2, \dots, v_n$
- Claim: There is a subtree T of G on vertices $\{v_0, \dots, v_i\}$ such that for every v_j , $d_T(s, v_j) = d_G(s, v_j)$.

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Base Case

- When $i=0$ the claim holds.

s ●

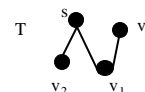
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Inductive Hypothesis

- There is a tree T such that $d_T(s, v) = d_G(s, v)$ for each v in $\{s=v_0, \dots, v_{i-1}\}$



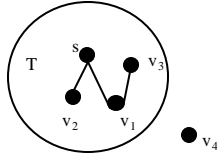
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Now add v_i

- We need to exhibit T' such that $d_T(s, v_k) = d_G(s, v_k)$ for each v in $\{s=v_0, \dots, v_{i-1}, v_i\}$.



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Observe

- Let s, \dots, u, v_i be a shortest path between s and v_i in G .
- Since $i > 0$, $u \neq v_i$.
- Thus $d_G(s, v_i) = 1 + d_G(s, u) > d_G(s, u)$.
- Therefore u precedes v_i in the ordering of vertices; i.e. $u = v_j$ for some $j < i$.

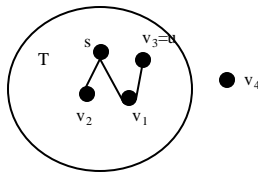
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Proof of Claim

- So u is already in T and, by our induction hypothesis, $d_G(s, u) = d_T(s, u)$.



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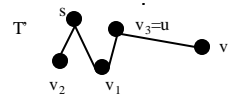
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$T' = T + (u, v_i)$

- $d_{T'}(s, v_i) = 1 + d_T(s, u) = d_G(s, v_i)$

QED



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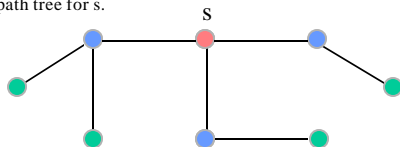
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Shortest path tree for s

The path between s and v in T is a shortest path in G .

The edges traversed in Breadth-First(s) form shortest path tree for s .

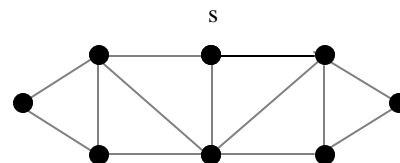


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Breadth-first(s) tree: All vertices and the edges traversed



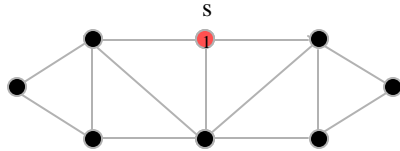
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Breadth-first(s)

Q=s



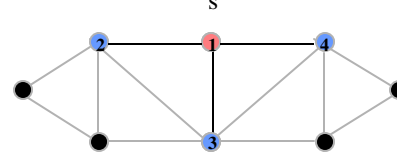
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Breadth-first(s)

Q=2,3,4



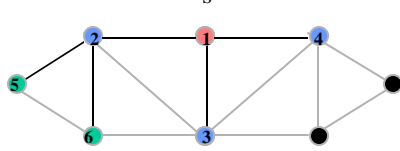
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Breadth-first(s)

Q=3,4,5,6



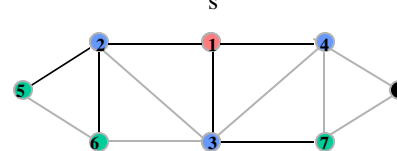
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Breadth-first(s)

Q=4,5,6,7



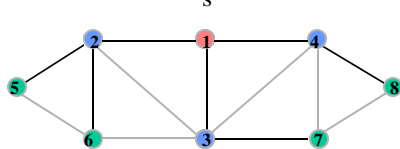
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Breadth-first(s)

Q=5,6,7,8



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Single Source Shortest Path

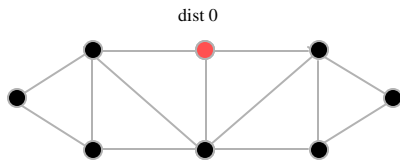
- Input: Graph G with a designated start vertex s .
- Output: For each vertex v , the length of the shortest path between s and v .
- Algorithm: Modify Breadth-first to compute $d(s,v)$ along the way.

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Breadth-first search Compute distance from s

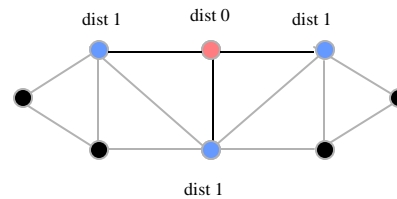


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Breadth-first search Compute distance from s

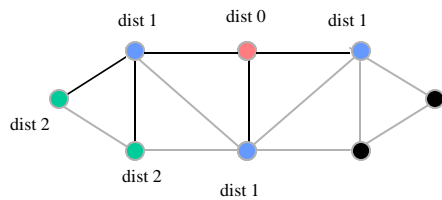


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Breadth-first search Compute distance from s

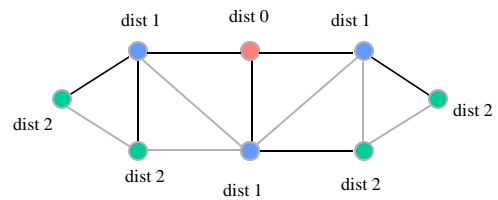


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Breadth-first search Compute distance from s



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Running Time

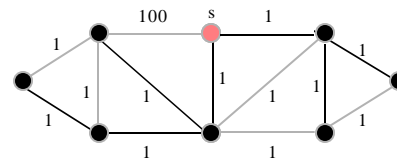
- The modified breadth-first algorithm for single source shortest path in an unweighted graph is: _____

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What if G is weighted?



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Single Source Shortest Path

- Input: Weighted graph G with a designated start vertex s . Weights are positive!
- Output: For each vertex v , the length of the **shortest path** between s and v .

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Path Length

- In a weighted graph the length of a path is the sum of the weights of the edges of the path.

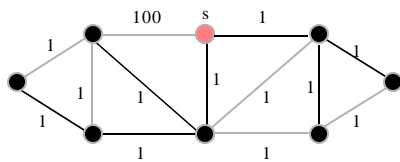
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Shortest path tree for s

The path between s and v in T is a **shortest path** in G .



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Shortest path tree for s

- Is it clear such a tree exists? YES by same argument.

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Shortest path tree for s

- Claim: Let the vertices of G be sorted by distance from s . Then there is a subtree T of G on vertices $\{v_0, \dots, v_i\}$ such that $0 \leq k \leq i$, $d_T(s, v) = d_G(s, v)$ for each v in T .
- If you have a tree for $\{v_0, \dots, v_i\}$ can you find the tree for $\{v_0, \dots, v_i, v_{i+1}\}$?

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Shortest path tree for s

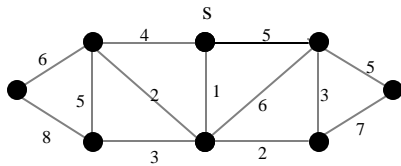
- Suppose you don't know the ordering?
- At each step find the vertex $v \notin T$ that minimizes $\min_{u \in T} d_T(s, u) + w(u, v)$.

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Dijkstra's Algorithm



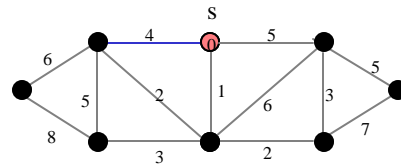
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Dijkstra's Algorithm

Number in node u indicate $d_G(s, u)$



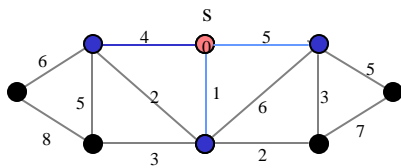
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Dijkstra's Algorithm

Number in node u indicate $d_G(s, u)$



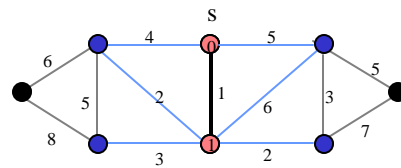
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Dijkstra's Algorithm

Number in node u indicate $d_G(s, u)$



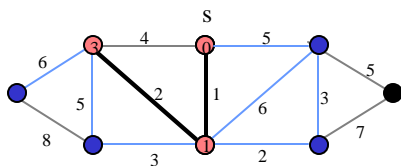
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Dijkstra's Algorithm

Number in node u indicate $d_G(s, u)$



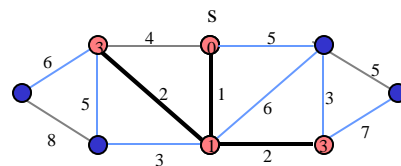
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Dijkstra's Algorithm

Number in node u indicate $d_G(s, u)$



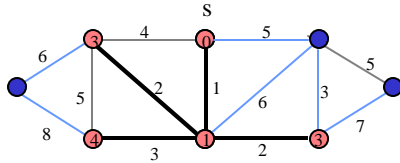
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Dijkstra's Algorithm

Number in node u indicate $d_G(s,u)$



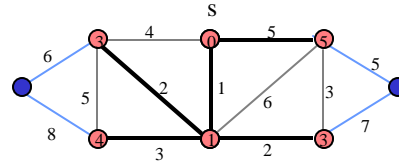
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Dijkstra's Algorithm

Number in node u indicate $d_G(s,u)$



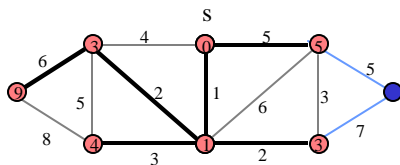
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Dijkstra's Algorithm

Number in node u indicate $d_G(s,u)$



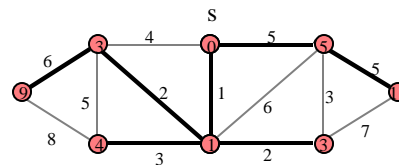
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Dijkstra's Algorithm

Number in node u indicate $d_G(s,u)$



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Does this sound familiar?

- Prim's algorithm for MST is VERY similar.
- The implementation details are almost identical.

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All Pairs Shortest Path (directed version)

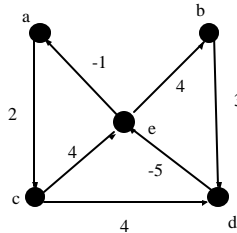
- Input: Weighted digraph G
- Output: For each pair of vertices x,y the distance between x and y in G

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What is $d(b,a)$?

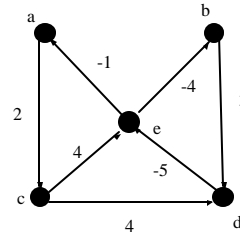


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What is $d(b,a)$?

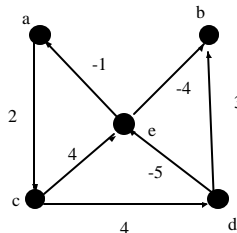


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What is $d(b,a)$?



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Three Cases:

- There is no path from a to b
- There is a path from a to b but no shortest path
- There is a shortest path from a to b

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Shortest path algorithm should

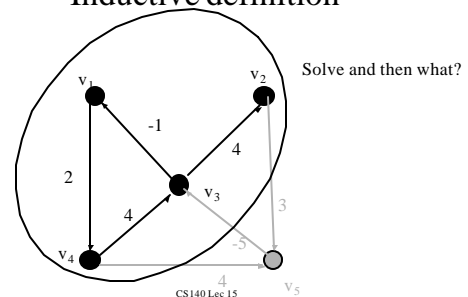
- Determine which case holds
 - There is no path from a to b
 - There is a path from a to b but no shortest path
 - There is a shortest path from a to b
- Find the length of the shortest path when one exists

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All Pairs Shortest Path
Inductive definition



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K-limited paths

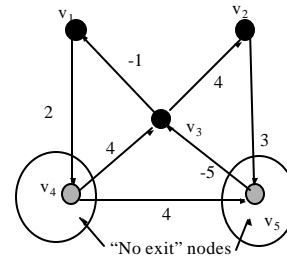
- A path from v_i to v_j is k -limited if the intermediate vertices in the path are numbered k or less

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3-limited paths

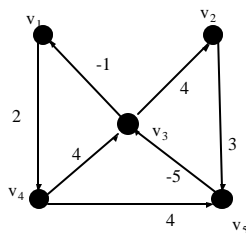


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What is the shortest 5-limited path from v_1 to v_2 ?



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Floyd-Warshall algorithm

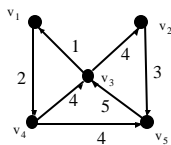
- $D^k(i,j)$ is the length of a shortest k -limited path from v_i to v_j
- $D^k(i,j) = \min(D^{k-1}(i,j), D^{k-1}(i,k) + D^{k-1}(k,j))$
- $D^0(i,j) = w(\langle v_i, v_j \rangle)$

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D^0



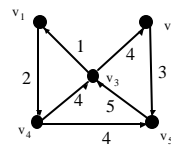
	1	2	3	4	5
1					
2					
3					
4					
5					

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D^0

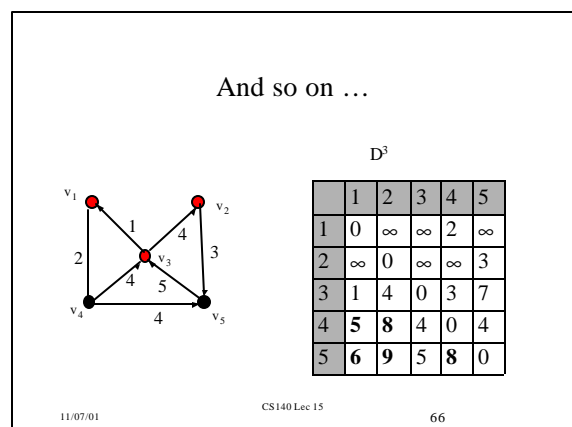
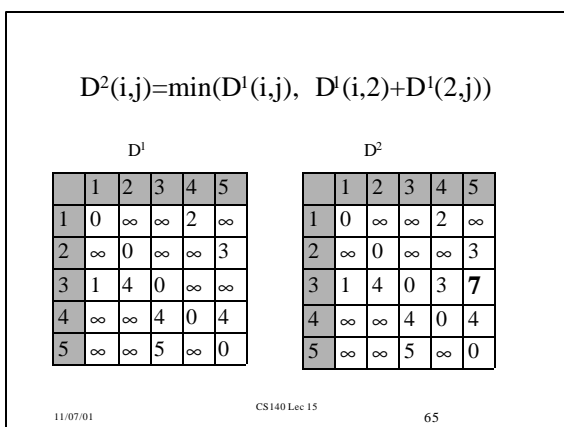
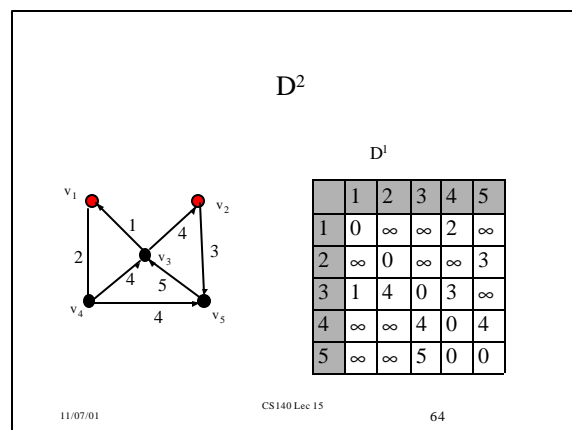
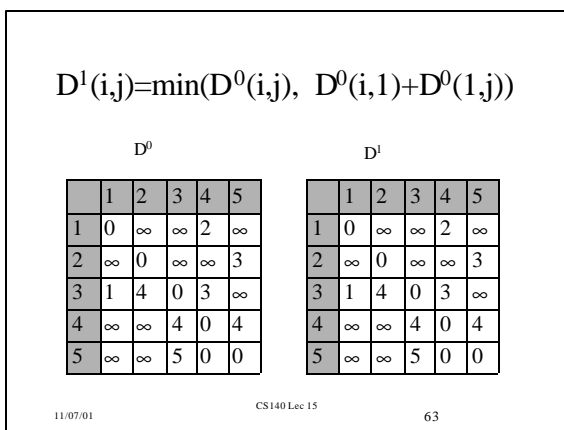
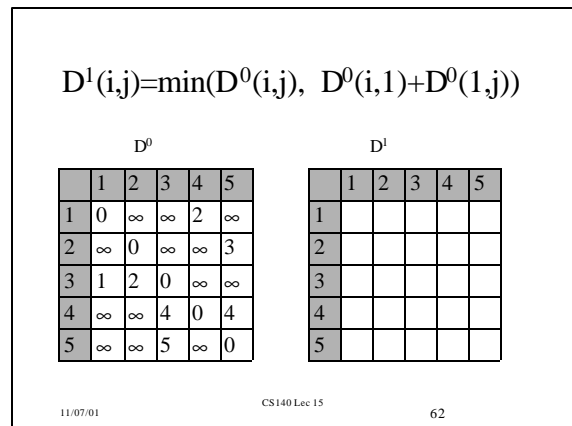
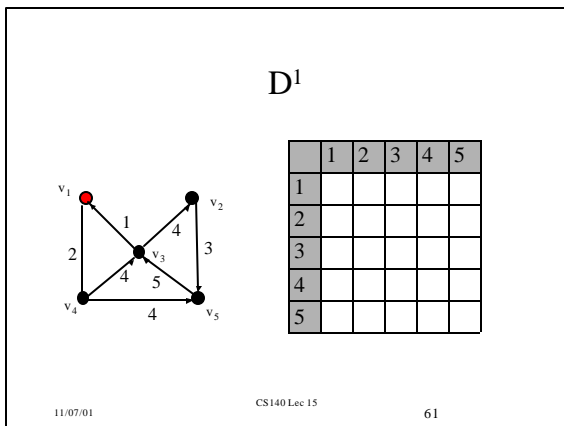


	1	2	3	4	5
1	0	∞	∞	2	∞
2	∞	0	∞	∞	3
3	1	2	0	∞	∞
4	∞	∞	4	0	4
5	∞	∞	5	∞	0

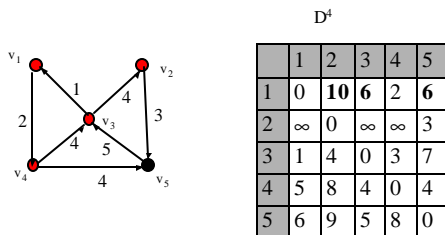
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And so on ...

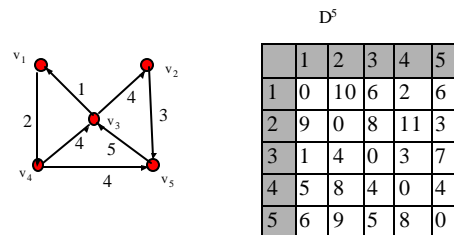


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And so on ...



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Floyd-Warshall algorithm

- $D^0(i,j) = w(\langle v_i, v_j \rangle)$
- For $i=1$ to n
 Compute D^i from D^{i-1}
- Return D^n

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Floyd-Warshall algorithm Running Time

- n Tables
- Each is $n \times n$
- Each table entry takes $O(1)$
- $O(n^3)$

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