

CS181a: Computer Animation

Mathematical Preliminaries
Z Sweedyk

1/28/02 CS181a Lec 01 1

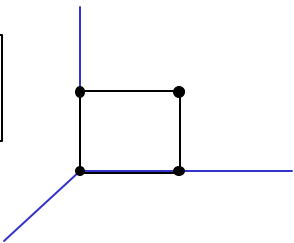
Overview

- **Review of the graphics pipeline**
- Affine Spaces
- Barycenters

1/28/02 CS181a Lec 01 2

Graphics Pipeline

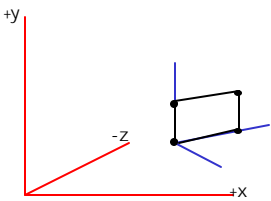
1. Build Primitives



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Graphics Pipeline

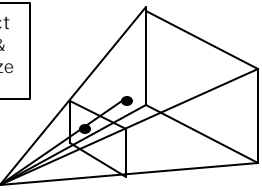
2. Assemble Scene



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Graphics Pipeline

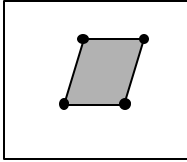
3. Project Scene & Normalize



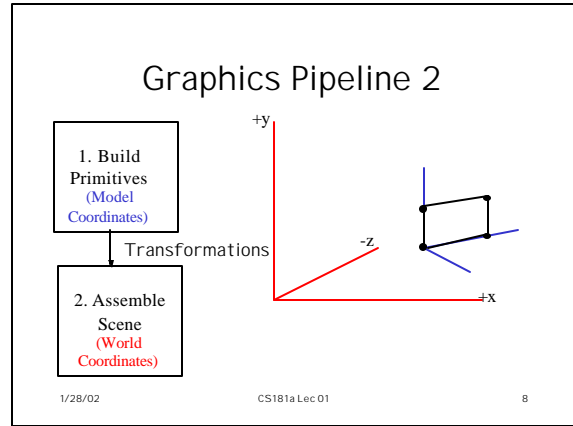
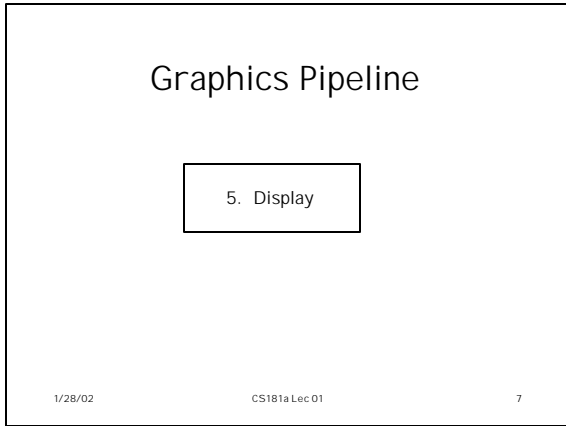
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Graphics Pipeline

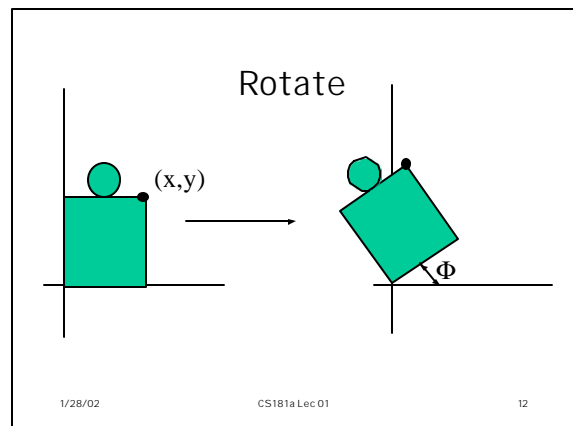
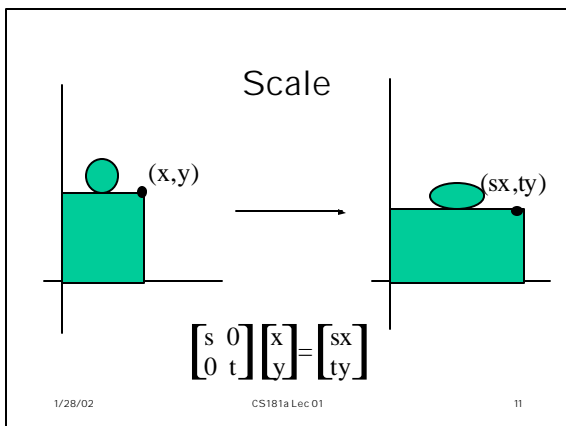
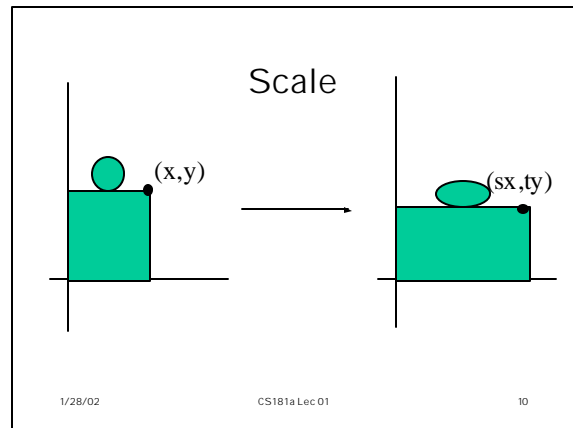
4. Scan Convert



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- ### Transformations
- Scale
 - Rotate
 - Translate
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Rotate

$$\begin{bmatrix} \cos\Phi & -\sin\Phi \\ \sin\Phi & \cos\Phi \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x\cos\Phi - y\sin\Phi \\ x\sin\Phi + y\cos\Phi \end{bmatrix}$$

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Translate

$(x+x_0, y+y_0)$

(x, y)

y_0

x_0

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Translate

NOT LINEAR

$(x+x_0, y+y_0)$

(x, y)

y_0

x_0

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Solution

Homogenous Coordinates

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Overview

- Review of the graphics pipeline
- **Affine Spaces**
- Curves Intro

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Affine Spaces

- \mathbb{R}^n : a set of points
- \mathbb{R}^n : a Linear (Vector) Space
- \mathbb{R}^n : an Affine Spaces
- Linear operators
- Frames
- Barycenters
- Affine operators

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\mathbb{R}^n : a set of points

\mathbb{R}^n is the set of n-tuples of real numbers: i.e. (x_1, x_2, \dots, x_n) where x_i is in \mathbb{R}

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19

Points $\mathbb{R}^2 = \{(x,y) \text{ where } x,y \text{ are in } \mathbb{R}\}$

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\mathbb{R}^n : a vector space

\mathbb{R}^n is the vector space containing the vectors $\langle x_1, x_2, \dots, x_n \rangle$ where x_i is in \mathbb{R} .

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Vector space \mathbb{R}^2 : $\{\langle x,y \rangle \text{ where } x,y \text{ are in } \mathbb{R}\}$

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Vector

- Vector: has magnitude & direction but no position

- Good for representing change in position; i.e. go three miles northeast

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Vector space \mathbb{P}^2 : $\{\text{vectors from } (-2,3) \text{ to } (x,y) \text{ where } x,y \text{ are in } \mathbb{R}\}$

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R² vs. P²

Changing the origin
changes the naming
convention

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Rⁿ: an Affine Space

Rⁿ: points

+

Rⁿ: vectors

We need a consistent naming convention:
 $\langle x_1, x_2, \dots, x_n \rangle$ is the vector defined from the point
 $(0, 0, \dots, 0)$ to the point (x_1, x_2, \dots, x_n)

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Vectors Act On Points

$p + \mathbf{v}$ is the point you get to by moving
 \mathbf{v} from the point p

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In other words ...

Note: $\mathbf{v} = \mathbf{q} - \mathbf{p}$

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Summary

- p : the point
- \mathbf{v} : the vector
- $q = p + \mathbf{v}$ is the point you get to by moving \mathbf{v} from the point p
- Because of our naming convention $\mathbf{v} = \mathbf{q} - \mathbf{p}$

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Example

R²: the points

R²: the vectors


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Why bother?



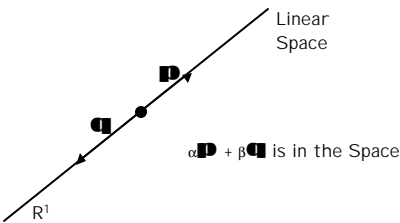
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Linear Spaces and Linear Operators are



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Linear Space: closure under linear combination



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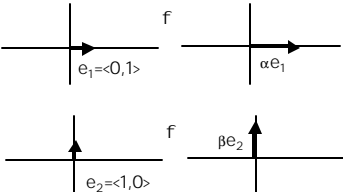
Functions (transformations) on Vectors

f is linear if

$$f(\alpha \mathbf{v} + \beta \mathbf{w}) = \alpha f(\mathbf{v}) + \beta f(\mathbf{w})$$

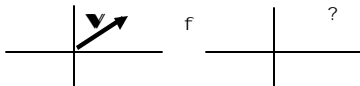
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Example in \mathbb{R}^2



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What does f do to \mathbf{v}



$\mathbf{v} = \langle x, y \rangle$ so $f(\mathbf{v}) = \langle \alpha x, \beta y \rangle$

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What does the linear operator f do to \mathbf{v} ?

$$\mathbf{v} = \langle x_1, x_2, \dots, x_n \rangle = x_1 \mathbf{e}_1 + x_2 \mathbf{e}_2 + \dots + x_n \mathbf{e}_n$$

$$f(\mathbf{v}) = x_1 f(\mathbf{e}_1) + x_2 f(\mathbf{e}_2) + \dots + x_n f(\mathbf{e}_n)$$

A linear operator is entirely characterized by its behavior on basis vectors

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To reiterate:

Linear Spaces and Linear Operators are

NICE

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(sub)Spaces

Linear (sub)Space

Not a Linear (sub)Space

L_1 L_2

We care about L_2

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Hence no closure for linear operator: $f(\mathbf{v}) = -2\mathbf{v}$

Not a Linear subSpace

\mathbf{v}

$f(\mathbf{v})$

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What is the problem?

L_1 L_2

Origin is on L_1

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Solution

L_1 L_2

Specify a "pseudo-origin"

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Frame

Specify a "pseudo-origin"

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Frame Specification

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(sub)Spaces

Linear (sub)Space Affine (sub)Space

We care about L_2

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Barycenters: Let's return to the closure problem

$\alpha \mathbf{p} + \beta \mathbf{q}$ is NOT typically in the Space

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Closure revisited

If $\alpha + \beta = 1$ then $\alpha \mathbf{p} + \beta \mathbf{q}$ is in the Space

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Closure revisited

- Show $\alpha \mathbf{p} + (1-\alpha) \mathbf{q}$ is in the space
- Note $\alpha \mathbf{p} + (1-\alpha) \mathbf{q} = \mathbf{q} + \alpha(\mathbf{p} - \mathbf{q})$

Barycenter

$\alpha(\mathbf{q} - \mathbf{p})$

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In fact:

α $(1-\alpha)$

p q

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Exercise: Barycenter

What is the barycenter $(1/4)p + (1/4)q + (1/2)r$?

p q r

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Exercise: Barycenter

What is the barycenter $p + q - r$?

p q r

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Computation of Barycenter

What is the barycenter of $(1/4)p + (1/4)q + (1/2)r$?

p q r

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Recursive computation of Barycenter

What is the barycenter of $(1/4)p + (1/4)q + (1/2)r$?

p q r

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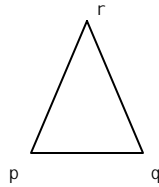
Recursive computation of Barycenter

What is the barycenter of $(1/4)p + (1/4)q + (1/2)r$?

p q r

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Exercise: Recursive Computation of Barycenter



What is the barycenter $p + q - r$?

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55

Affine operator

An operator is affine if it preserves barycenters:

$$f(\alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_n x_n) = \alpha_1 f(x_1) + \alpha_2 f(x_2) + \dots + \alpha_n f(x_n)$$

Provide $\sum \alpha_i = 1$

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56

Next Time

- Curves
- Parametric vs. Implicit forms
- Splines: Hermitian, Bezier, B-spline
- Polar forms
- Recursive computation

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57

Today's film clips: Alien Worlds

- 2001: Space Odyssey
- Titan A.E.
- Gas Planet

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58

Assignment

- Maya tutorial 3&4
- Grade tutorial 1&2

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59