

Implementing Trees as Lists

- ## The Tree is a Pervasive Information Structure
- Files & Directories
 - Family Trees
 - Management Hierarchies
 - In the current discussion:
 - Trees are the abstraction
 - Lists are the implementation

Files and Directories

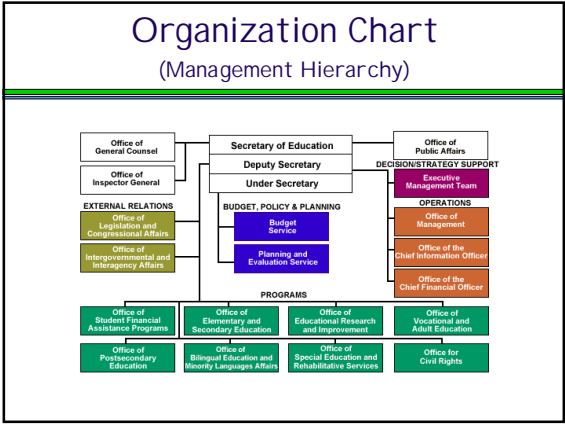
```

/
/dev
  /dev/console
  /dev/dsk
    /dev/dsk/dsk01
    /dev/dsk/dsk02
/etc
  /etc/mail
/usr
  /usr/bin/emacs
  /usr/bin/lis
  /usr/bin/more
    
```

Family Trees

```

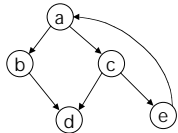
Joseph Patrick Kennedy* - (m. Rose Elizabeth Fitzgerald)
├── Joseph Patrick Kennedy Jr.*
│   ├── Rosemary Kennedy
│   ├── Kathleen Kennedy* (m. William John Robert Cavendish)
│   ├── Basil Henry Kennedy (m. Robert Sargent Shriver Jr.)
│   │   ├── Robert Sargent Shriver III
│   │   ├── Maria Odette Shriver (m. Arnold Schwarzenegger)
│   │   ├── Timothy Henry Shriver
│   │   ├── Mark Kennedy Shriver
│   │   └── Anthony Paul Shriver
│   └── Patricia Kennedy (m. Peter Lawford*, divorced)
│       ├── Christopher Kennedy Lawford
│       ├── Sydney Maria Lawford Mordkay
│       ├── Patricia Francis Lawford Snyder
│       └── Robin Elizabeth Lawford
│
│   └── Robert Francis Kennedy* (m. Ethel Davis)
│       ├── Judith Ann Bertolini Kennedy
│       ├── Joseph Patrick Kennedy II
│       ├── Robert Francis Kennedy Jr.
│       ├── David Anthony Kennedy*
│       ├── Henry Courtney Kennedy
│       ├── Michael Anthony Kennedy*
│       ├── Henry Henry Kennedy
│       ├── Christopher George Kennedy
│       ├── Matthew Maxwell Taylor Kennedy
│       ├── Douglas Sheridan Kennedy
│       └── Amy Elizabeth Scherwin Kennedy
│
│   └── John Fitzgerald Kennedy* (m. Jacqueline Lee Bouvier*)
│       ├── unnamed daughter* (will born)
│       ├── Caroline Bouvier Kennedy (m. Edwin A. Schlossberg)
│       ├── Rose Schlossberg
│       ├── Frances Schlossberg
│       ├── John Schlossberg
│       ├── John Fitzgerald Kennedy Jr.* (m. Carolyn Bessette*)
│       └── Patrick Bouvier Kennedy*
    
```



- ## Definition of Tree
- There are many different varieties of trees.
 - We discuss only some of them.
 - Use your knowledge of these to generalize to other varieties.
 - We will base our definition on *paths* and related concepts.

Paths in Directed Graphs

- A **path** in a graph G is a list of nodes n_0, n_1, \dots, n_k such that each successive pair (n_i, n_{i+1}) is in the corresponding binary relation.



- Some paths:

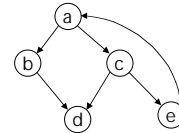
- a, b, d
- c, e, a
- a, c, e, a, c, d

Cycles

- A **cycle** is a path that starts and ends on the same node.

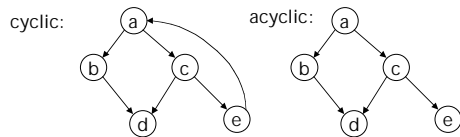
- Examples:

- a, c, e, a
- e, a, c, e, a, c, e



Cyclic and Acyclic

- A **cyclic** graph is one that has at least one cycle.
- An **acyclic** graph is one that has *no* cycles.



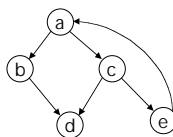
DAGs

- DAG is an acronym for "Directed Acyclic Graph"
- DAG is mainly used because it is more pronounceable than ADG ("Acyclic Directed Graph")

Target Set

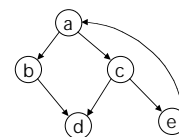
- The **target set** of a node n is the set of nodes to which there is an arc from n .

- targets(a) = {b, c}
- targets(b) = {d}
- targets(c) = {d, e}
- targets(d) = { }
- targets(e) = {a}



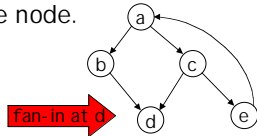
Leaves

- If a node's target set is empty, that node is called a **leaf**.



Fan-In

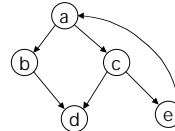
- A directed graph is said to **fan-in at** node n if the node is in the target sets of two or more different nodes.
- A directed graph **has fan-in** if it fans in at least one node.



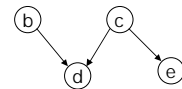
Roots

- A **root** of a directed graph is a node that is not in any node's target set.

no roots:



b and c are roots:

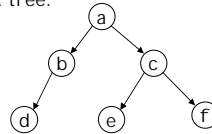


Tree at Last

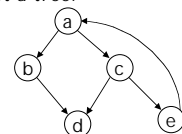
- A **tree** is a directed graph such that:
 - The graph is acyclic.
 - There is exactly one root.
 - It has no fan-in.

Tree vs Not

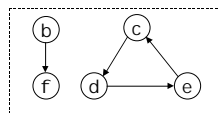
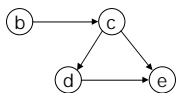
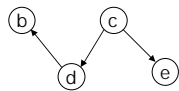
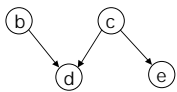
A tree:



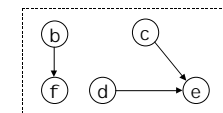
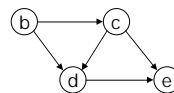
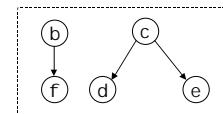
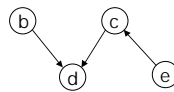
Not a tree:



Classify these for Tree-dom



More Graphs to Classify



Reverse Graphs

- Some graphs that may look tree-like aren't technically trees unless we consider the **reverse graph** (one with all of the arcs of the original reversed).



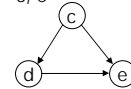
Reconvergence, an Alternative

- A **reconvergence** is a pair of *different* paths that start and end, respectively, on the *same* nodes.

- Therefore, a tree can also be characterized as a directed graph that

- has one root
- has no cycles
- has no reconvergences

Reconvergence below:
c, d, e
c, e



Subsets of Three Properties

- **DAG**: acyclic, but
 - may have multiple roots,
 - may have fan-in
- **Forest**: acyclic, and no fan-in but
 - may have multiple roots
- A forest can also be characterized as a **collection of disjoint trees**. Each tree could be identified with its root.

Adding/Removing Arcs

- Adding arcs to a _____ that is not a tree may make it into a tree.
- Adding arcs to a _____ that is not a tree will never make it into a tree.
- Removing arcs from a _____ that is not a tree may make it into a tree.
- Removing arcs from a _____ that is not a tree will never it into a tree.

Ordered Directed Graphs

- We use the adjective **ordered** to indicate that the order of targets of a node matters.
- This property is **implicit** with trees much of the time.
- Because we are going to represent trees by lists, we can have ordering for free if we want it.

Representing/Implementing Trees as Lists

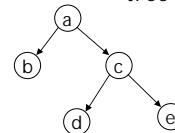
- Every tree can be represented as a list.
- Obvious:
 - Tree is a special kind of directed graph.
 - Every directed graph can be represented as a list of pairs.
- But we want a representation that makes it **clear** that we have a tree.

First Try: Target Sets

- We know that **sets** can be represented as lists.
- Use a list to represent the target set of each node.
- Associate each node with its list of targets.

Target-Lists Representation

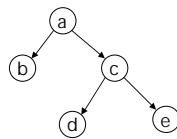
- [[a, [b, c]],
[b, []],
[c, [d, e]],
[d, []],
[e, []]
]
- This works for graphs in general; is not limited to trees.
- Doesn't directly show tree-dom.



Nested Target-Lists Representation

- List the root, followed by the representation of each sub-tree:

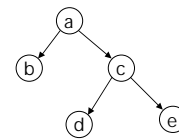
- [a, _____]
- [a, [b], [c, _____]]
- [a, [b], [c, [d], [e]]]



Modified

Nested Target-Lists Representation

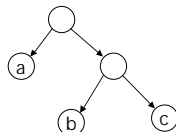
- A leaf is a node with no targets.
- When a sub-tree is a leaf, omit the brackets around it.
 - [a, _____]
 - [a, b, [c, _____]]
 - [a, b, [c, d, e]]
- Less-cluttered appearance but also less uniform.



Representation of "Unlabelled" Trees

- In this model, only *leaves* have labels.
- A leaf is represented by its label
- A non-leaf tree is represented by a list of the representations of the targets of the root.

- [a, _____]
- [a, [b, c]]



Representing Lists by Ordered Trees

- (This may look "backward" at first.)
- Every list can be represented as an ordered **binary tree** (tree in which each node has at most two targets).
- This corresponds to the "box" storage abstraction, where the data items may themselves be lists.

Representing Lists as Trees

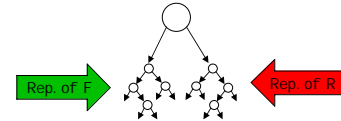
- An **atomic** item (non-list) is represented by itself.
- The **null list** is represented as a leaf [].
- A list [First | Rest] is represented by a node with two targets:
 - The **left** target is the representation of First.
 - The **right** target is the representation of Rest.
- Note that ordering of targets is essential.

Representing Lists as Trees

Atom a: a

Empty list []: []

Non-empty list [F | R]:



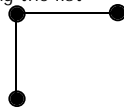
Representing Lists as Trees

- Matters are actually simpler if we rotate the tree 45°, so that "right" is horizontally right and "left" is down.

Tree representing the list

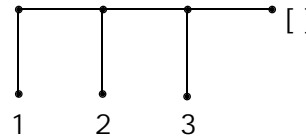
Tree representing the rest of the list

Tree representing the first element



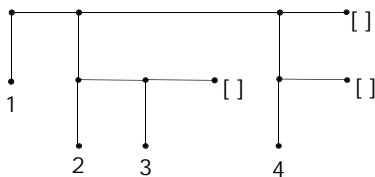
Example: Binary Tree

- Represent as a binary tree: [1, 2, 3]



Example: Binary Tree

- Represent as a binary tree:
[1, [2, 3], [4]]



Corresponding Box Diagram

[1, [2, 3], [4]]

