



# Implementing Trees as Lists

# The Tree is a Pervasive Information Structure

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- Files & Directories
- Family Trees
- Management Hierarchies
  
- In the current discussion:
  - Trees are the abstraction
  - Lists are the implementation

# Files and Directories

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/

/dev

/dev/console

/dev/dsk

/dev/dsk/dsk01

/dev/dsk/dsk02

/etc

/etc/mail

/usr

/usr/bin/emacs

/usr/bin/lis

/usr/bin/more

# Family Trees

Joseph Patrick Kennedy\* - (m. Rose Elizabeth Fitzgerald\*)

-Joseph Patrick Kennedy Jr.\*

-Rosemary Kennedy

-Kathleen Kennedy\* (m. William John Robert Cavendish)

-Eunice Mary Kennedy (m. Robert Sargent Shriver Jr.)

|-Robert Sargent Shriver III  
|-Maria Owings Shriver (m. Arnold Schwarzenegger)  
|-Timothy Perry Shriver  
|-Mark Kennedy Shriver  
|-Anthony Paul Shriver

-Patricia Kennedy (m. Peter Lawford\*, divorced)

|-Christopher Kennedy Lawford  
|-Sydney Maleia Lawford McKelvey  
|-Victoria Francis Lawford Ponder  
|-Robin Elizabeth Lawford

-Robert Francis Kennedy\* ([m. Ethel Skakel](#))

|-Kathleen Hartington Kennedy  
|-Joseph Patrick Kennedy II  
|-Robert Francis Kennedy Jr.  
|-David Anthony Kennedy\*  
|-Mary Courtney Kennedy  
|-Michael LeMoyne Kennedy\*  
|-Mary Kerry Kennedy  
|-Christopher George Kennedy  
|-Matthew Maxwell Taylor Kennedy  
|-Douglas Harriman Kennedy  
|-Rory Elizabeth Katherine Kennedy

-Jean Ann Kennedy (m. Stephen Edward Smith\*)

|-Stephen Edward Smith Jr.  
|-William Kennedy Smith  
|-Amanda Mary Smith  
|-Kym Marie Smith

-Edward Moore Kennedy (m. #1: Virginia Joan Bennet)  
(m. #2: Victoria Anne Reggie)

|-Kara Ann Kennedy Allen  
|-Edward Moore Kennedy Jr.  
|-Patrick Joseph Kennedy

-John Fitzgerald Kennedy\* (m. Jacqueline Lee Bouvier\*)

-unnamed daughter\* (still born)

-Caroline Bouvier Kennedy (m. Edwin A. Schlossberg)

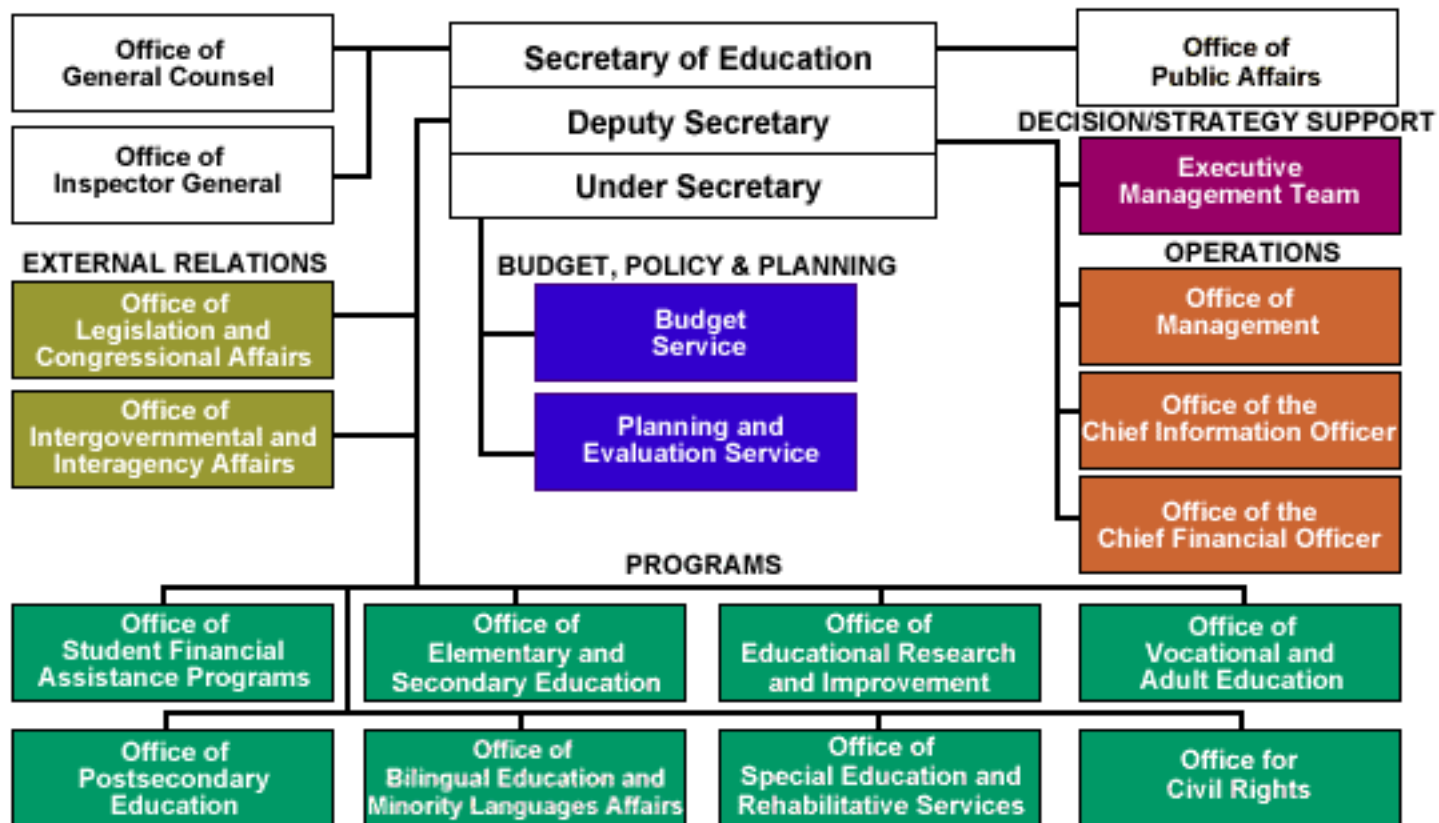
|-Rose Schlossberg  
|-Tatiana Schlossberg  
|-John Schlossberg

-John Fitzgerald Kennedy Jr.\* (m. Carolyn Bessette\*)

-Patrick Bouvier Kennedy\*

# Organization Chart

## (Management Hierarchy)



# Definition of *Tree*

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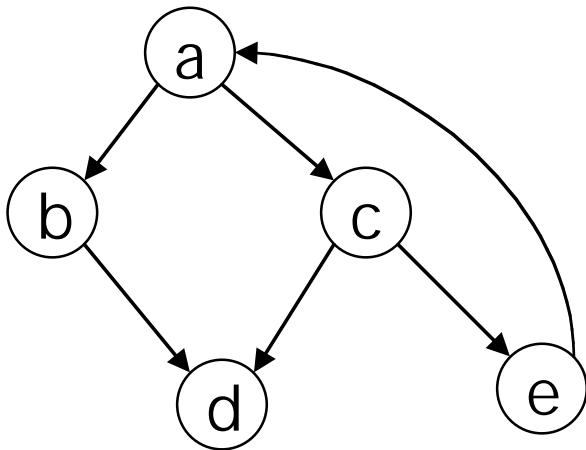
- There are many different varieties of trees.
- We discuss only some of them.
- Use your knowledge of these to generalize to other varieties.
- We will base our definition on *paths* and related concepts.

# Paths in Directed Graphs

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- A **path** in a graph  $G$  is a list of nodes  $n_0, n_1, \dots, n_k$  such that each successive pair  $(n_i, n_{i+1})$  is in the corresponding binary relation.



- Some paths:

- a, b, d

- c, e, a

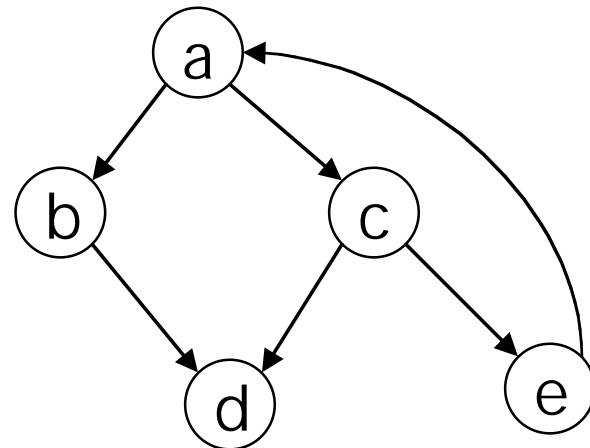
- a, c, e, a, c, d

# Cycles

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- A **cycle** is a path that starts and ends on the same node.
- Examples:
  - a, c, e, a
  - e, a, c, e, a, c, e

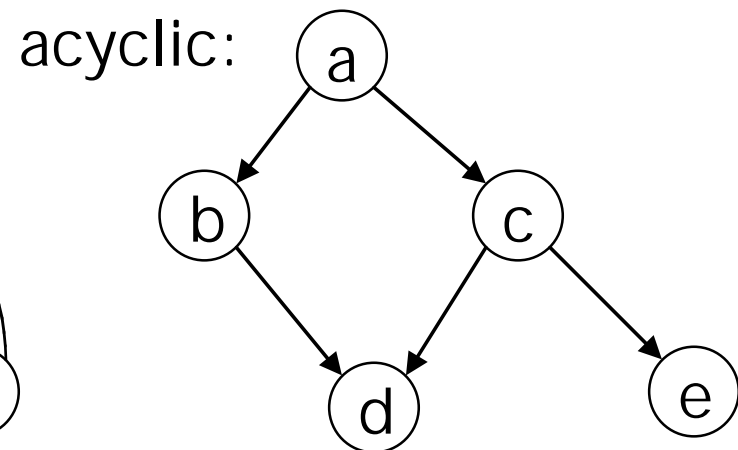
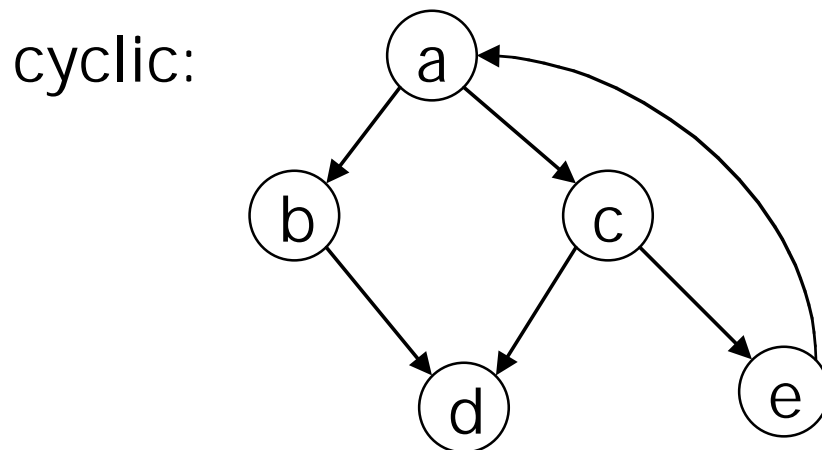


# Cyclic and Acyclic

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- A *cyclic* graph is one that has at least one cycle.
- An *acyclic* graph is one that has *no* cycles.



# DAGs

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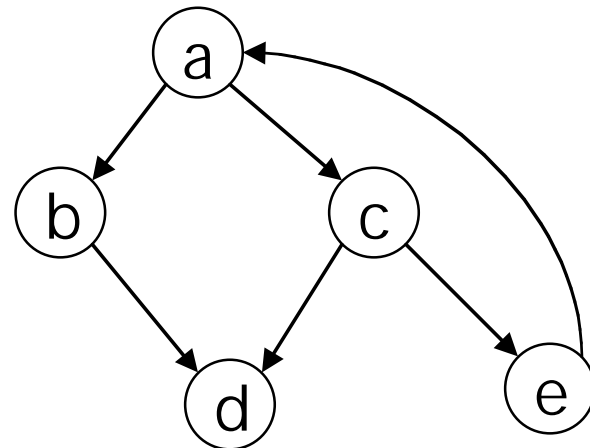
- DAG is an acronym for "Directed Acyclic Graph"
- DAG is mainly used because it is more pronounceable than ADG ("Acyclic Directed Graph")

# Target Set

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- The *target set* of a node  $n$  is the set of nodes to which there is an arc from  $n$ .
  - $\text{targets}(a) = \{b, c\}$
  - $\text{targets}(b) = \{d\}$
  - $\text{targets}(c) = \{d, e\}$
  - $\text{targets}(d) = \{\}$
  - $\text{targets}(e) = \{a\}$

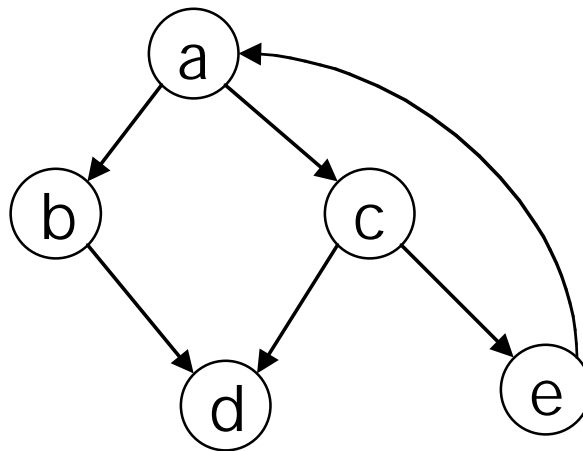


# Leaves

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- If a node's target set is empty, that node is called a *leaf*.

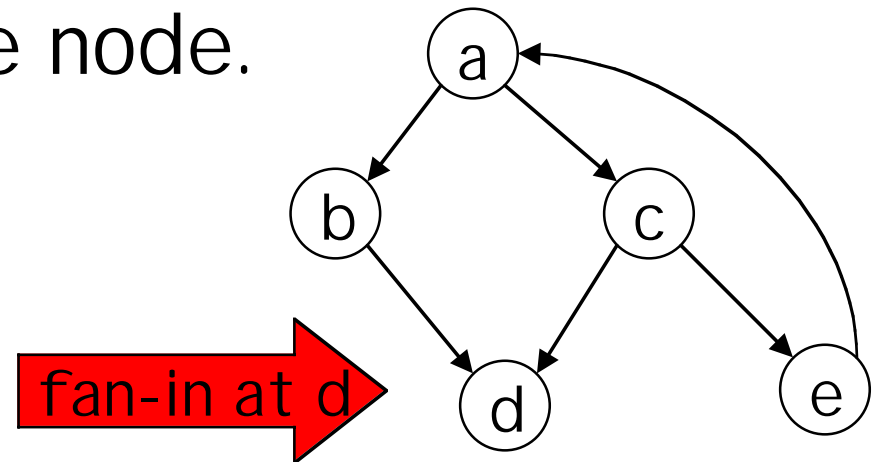


# Fan-In

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- A directed graph is said to *fan-in at* node  $n$  if the node is in the target sets of two or more different nodes.
- A directed graph "**has fan-in**" if it fans in at least one node.



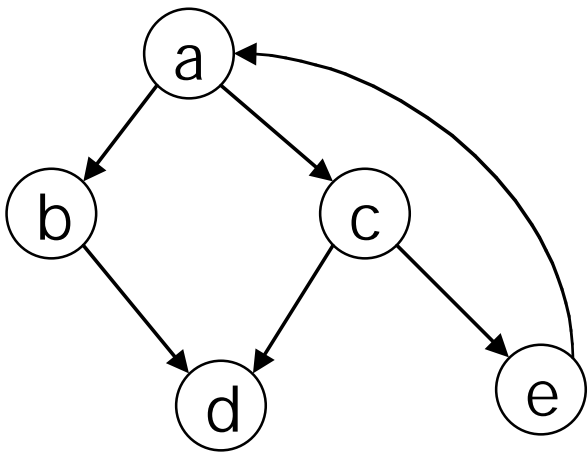
# Roots

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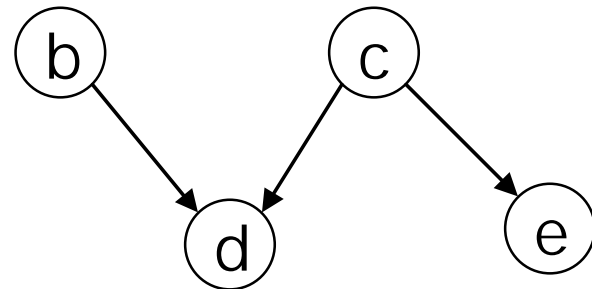
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- A **root** of a directed graph is a node that is not in any node's target set.

no roots:



b and c are roots:



# Tree at Last

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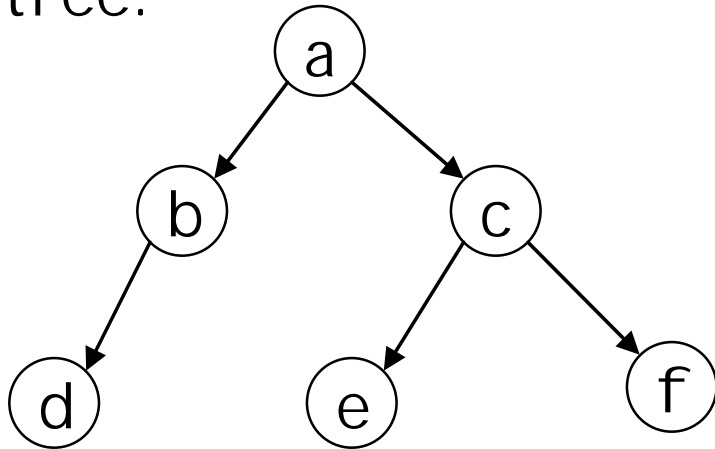
- A *tree* is a directed graph such that:
  - The graph is acyclic.
  - There is exactly one root.
  - It has no fan-in.

# Tree vs Not

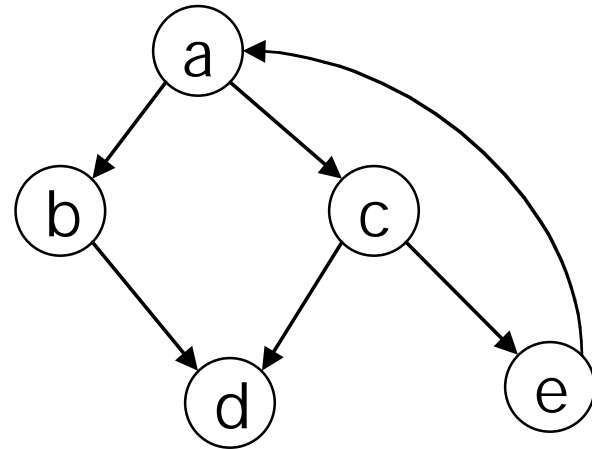
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A tree:



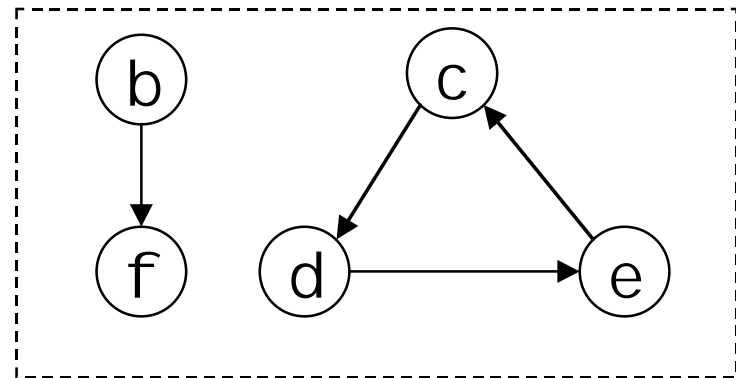
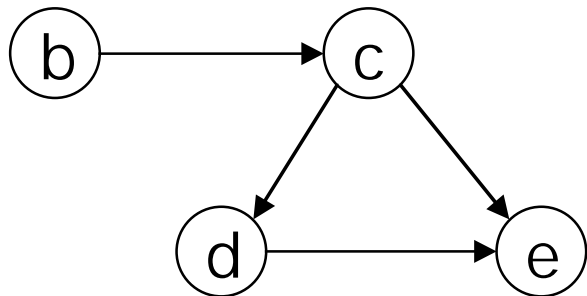
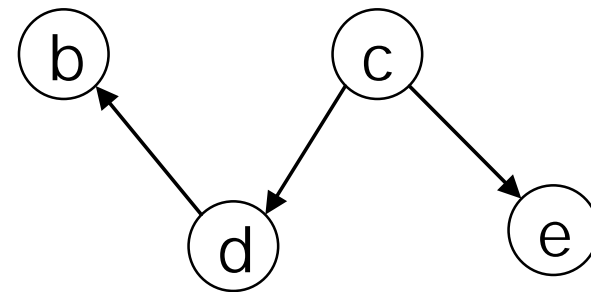
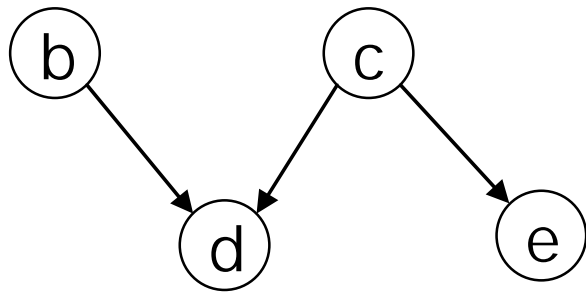
Not a tree:



# Classify these for Tree-dom

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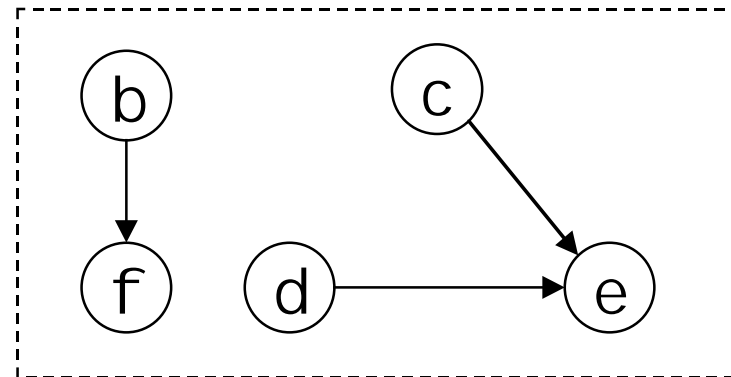
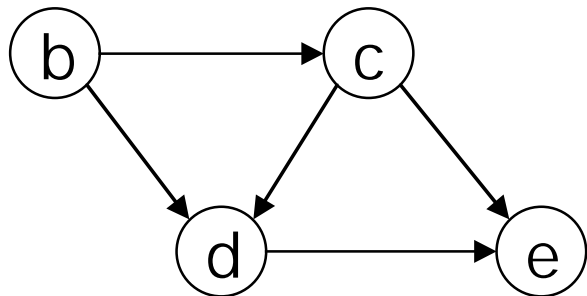
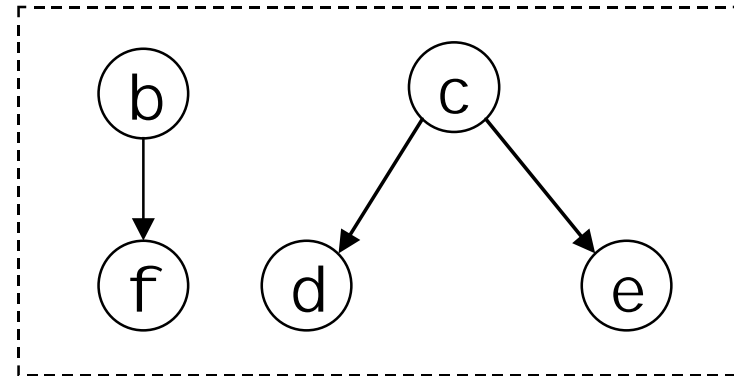
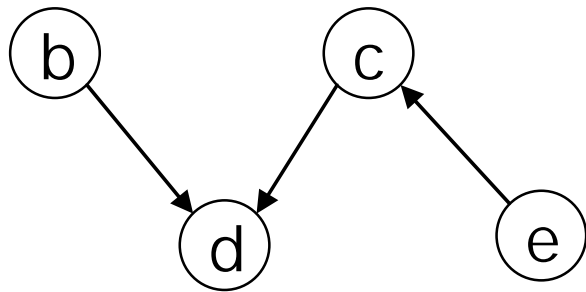
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# More Graphs to Classify

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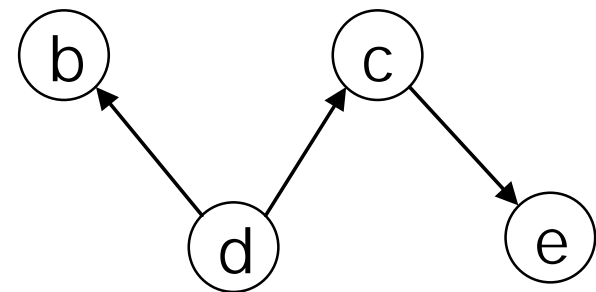
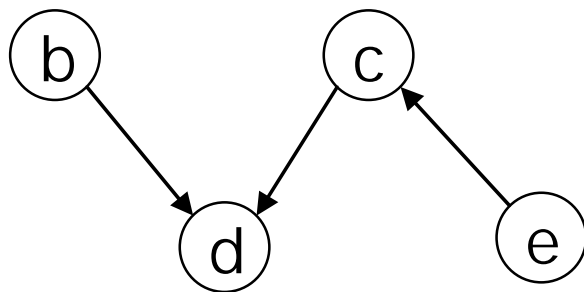


# Reverse Graphs

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- Some graphs that may look tree-like aren't technically trees unless we consider the **reverse graph** (one with all of the arcs of the original reversed).



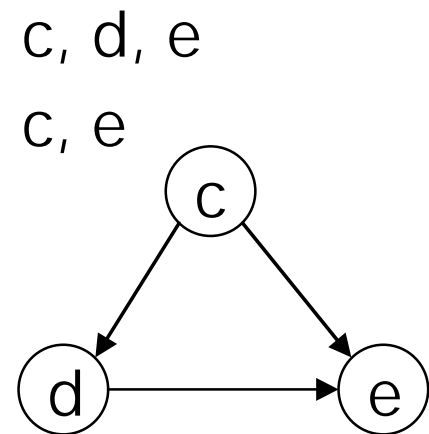
# Reconvergence, an Alternative

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- A **reconvergence** is a pair of *different* paths that start and end, respectively, on the *same* nodes.
- Therefore, a tree can also be characterized as a directed graph that
  - has one root
  - has no cycles
  - has no reconvergences

Reconvergence below:



# Subsets of Three Properties

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- **DAG**: acyclic, but
  - may have multiple roots,
  - may have fan-in
- **Forest**: acyclic, and no fan-in but
  - may have multiple roots
- A forest can also be characterized as a **collection of disjoint trees**.  
Each tree could be identified with its root.

# Adding/Removing Arcs

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- Adding arcs to a \_\_\_\_\_ that is not a tree may make it into a tree.
- Adding arcs to a \_\_\_\_\_ that is not a tree will never make it into a tree.
- Removing arcs from a \_\_\_\_\_ that is not a tree may make it into a tree.
- Removing arcs from a \_\_\_\_\_ that is not a tree will never it into a tree.

# Ordered Directed Graphs

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- We use the adjective *ordered* to indicate that the order of targets of a node matters.
- This property is *implicit* with trees much of the time.
- Because we are going to represent trees by lists, we can have ordering for free if we want it.

# Representing/Implementing Trees as Lists

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- Every tree can be represented as a list.
- Obvious:
  - Tree is a special kind of directed graph.
  - Every directed graph can be represented as a list of pairs.
- But we want a representation that makes it **clear** that we have a tree.

# First Try: Target Sets

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- We know that **sets** can be represented as lists.
- Use a list to represent the target set of each node.
- Associate each node with its list of targets.

# Target-Lists Representation

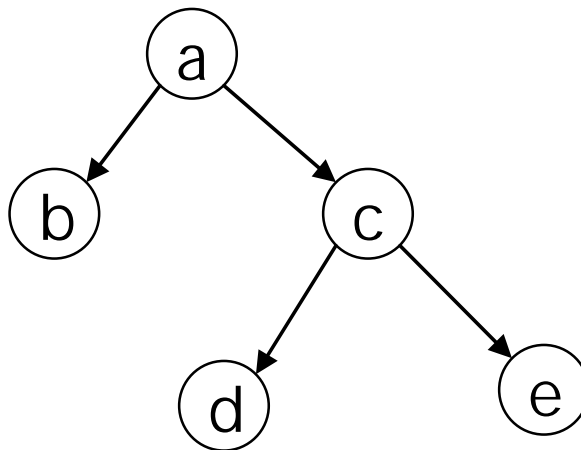
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- [ [a, [b, c]],  
[b, []],  
[c, [d, e]],  
[d, []],  
[e, []]

]

- This works for graphs in general; is not limited to trees.
- Doesn't directly show tree-dom.

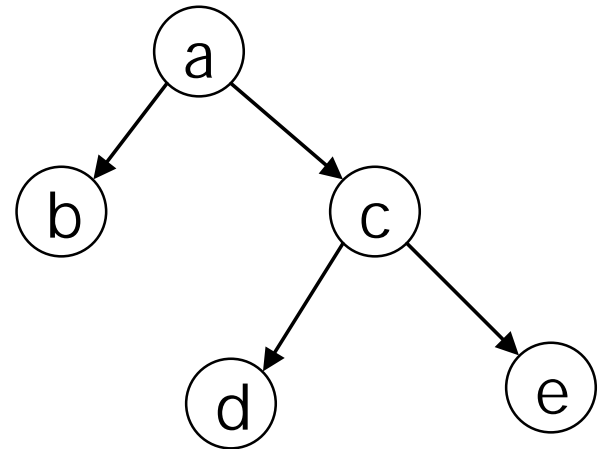


# *Nested Target-Lists Representation*

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- List the root, followed by the representation of each sub-tree:



- [a, \_\_\_\_\_, \_\_\_\_\_]
- [a, [b], [c, \_\_\_\_\_, \_\_\_\_\_ ]]
- [a, [b], [c, [d], [e]]]

## *Modified*

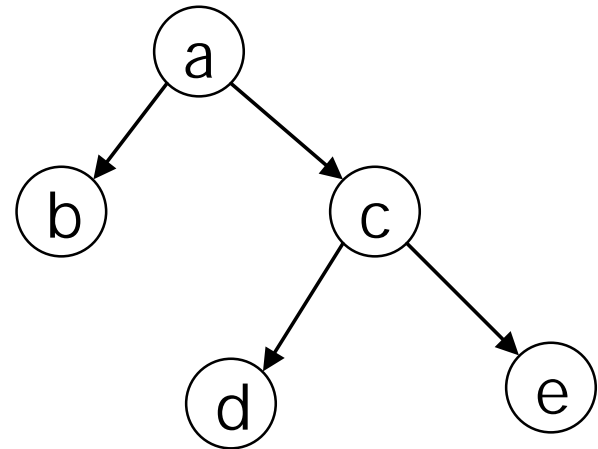
# Nested Target-Lists Representation

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- A leaf is a node with no targets.
- When a sub-tree is a leaf, omit the brackets around it.

- [a, \_\_\_\_\_, \_\_\_\_\_]
- [a, b, [c, \_\_\_\_\_, \_\_\_\_\_ ]]
- [a, b, [c, d, e]]



- Less-cluttered appearance but also less uniform.

# Representation of “Unlabelled” Trees

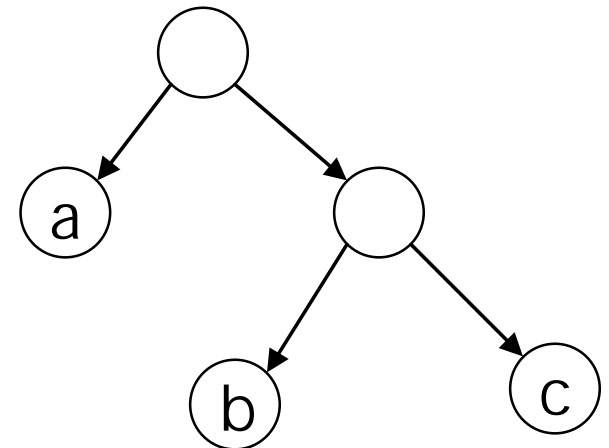
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- In this model, only *leaves* have labels.
- A leaf is represented by its label
- A non-leaf tree is represented by a list of the representations of the targets of the root.

- [a, \_\_\_\_\_]

- [a, [b, c]]



# Representing Lists by Ordered Trees

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- (This may look “backward” at first.)
- Every list can be represented as an ordered *binary tree* (tree in which each node has at most two targets).
- This corresponds to the “box” storage abstraction, where the data items may themselves be lists.

# Representing Lists as Trees

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- An **atomic** item (non-list) is represented by itself.
- The **null list** is represented as a leaf [].
- A list [First | Rest] is represented by a node with two targets:
  - The **left** target is the representation of First.
  - The **right** target is the representation of Rest.
- Note that ordering of targets is essential.

# Representing Lists as Trees

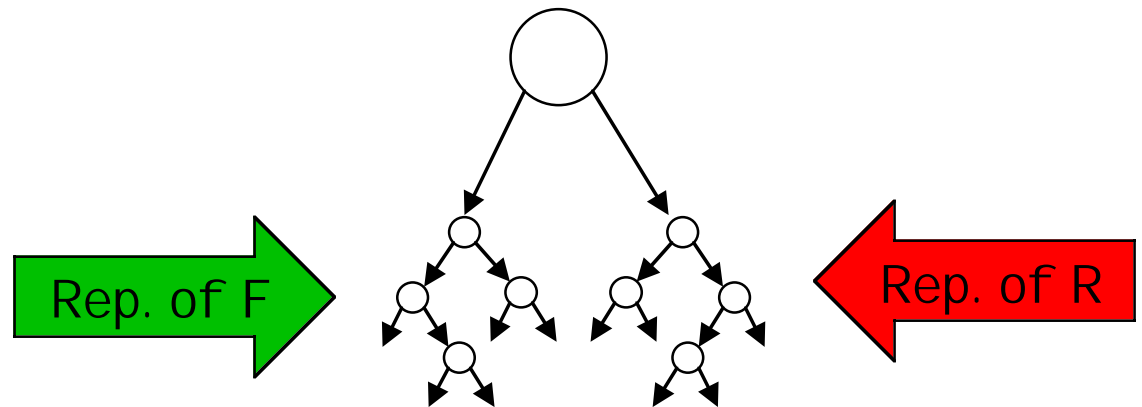
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Atom  $a$ :  $a$

Empty list  $[]$ :  $[]$

Non-empty list  $[F | R]$ :



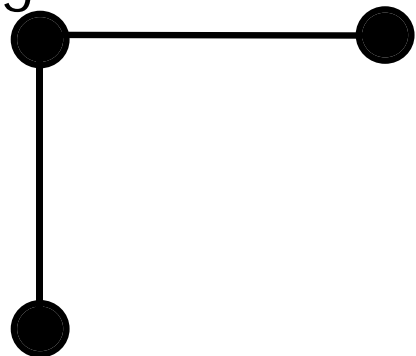
# Representing Lists as Trees

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- Matters are actually simpler if we rotate the tree  $45^\circ$ , so that “right” is horizontally right and “left” is down.

Tree representing the list



Tree representing the rest of the list

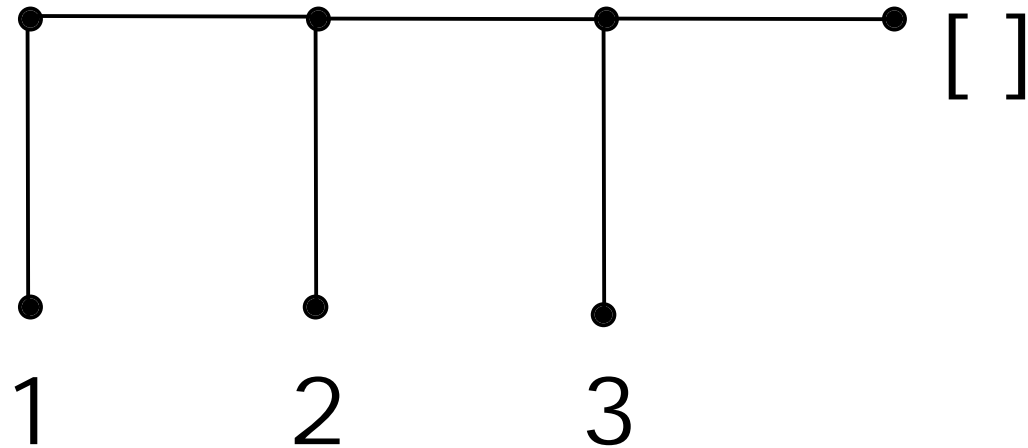
Tree representing the first element

# Example: Binary Tree

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- Represent as a binary tree: [1, 2, 3]





# Corresponding Box Diagram

[1, [2, 3], [4]]

