Training Techniques and Tips
Launder Input

- If the network is to learn a function, make sure that the samples are functional, i.e. that they don’t specify conflicting outputs for the same input value.

- For example, if clinical outcomes are the output, it is possible that two patients with the same symptoms have different outputs; presenting these to the network will mean that it will never fully converge.
BackProp Technique & Tricks
(Some of these apply to General Neural Networks)

(Two References:
Neural Networks Tricks of the Trade, Orr and Muller, eds., LNCS 1524
http://www.dontveter.com/bpr/bpr.html)

• Choose examples with maximum information content
  – Shuffle the training set so that successive samples rarely belong to the same class.
  – Present input examples that produce a large error more frequently than ones that produce a small error.
Technique & Tricks

• Normalize the inputs
  – Better if mean of a particular variable is near 0.
    • Then weight changes are less likely to be synchronized, since some will be positive, others negative.
    • Therefore, subtract the actual mean from the variable before training.
  – Better if the variables are scaled to have similar auto-covariances, defined as
    (sum-of-squares of variable)/(number of samples)
    • Then the weights will learn at similar rates.
    • Exception: When some variables are known in advance to be of less significance.
Technique & Tricks

• Decorrelate the inputs
  – Better if no two input variables are correlated.
  – Correlated inputs analogous to having linearly dependent variables in a linear system.
  – A technique called PCA (Principal Components Analysis), aka Karhunen-Loeve Expansion, can be used to remove linear correlations.
  – We will look at PCA later; PCA itself can be done by a PCA neural network.
Summary of Input Normalization

- Subtract means
- Scale
- PCA
BackProp Technique & Tricks

• Prefer tansig (hyperbolic tangent) rather than logsig for inner layers.
  – tansig output is symmetric about origin, logsig is not.
  – tansig will more likely produce outputs close to 0 for the next stage of the network

• Some recommend adding a small linear constant to the output of tansig to “avoid flat spots”
Piecewise Quadratic Approx. to \( \tanh \) (faster to compute)

<table>
<thead>
<tr>
<th>( x )</th>
<th>( f(x) )</th>
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</thead>
<tbody>
<tr>
<td>( x &gt; 1.92033 )</td>
<td>0.96016</td>
</tr>
<tr>
<td>( 0 &lt; x \leq 1.92033 )</td>
<td>( 0.96016 - 0.26037 \times (x - 1.92033)^2 )</td>
</tr>
<tr>
<td>( -1.92033 &lt; x &lt; 0 )</td>
<td>( 0.26037 \times (x + 1.92033)^2 - 0.96016 )</td>
</tr>
<tr>
<td>( x \leq -1.92033 )</td>
<td>-0.96016</td>
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Derivative: \( \tanh'(x) = 1 - \tanh^2(x) \) can still be used.
Choice of Target Values

• Choosing target values of +1, -1 for a tansig causes the neuron to be driven toward the **saturation region**.

• To get into this region, the weights are large and may become “stuck” because small gradient values will not change them sufficiently.

• It may be better to **choose the targets offset** from these saturation values, or to scale the tansig to get the same effect, e.g.
  
  – $f(x) = 1.7159 \tanh(2x/3)$, which has a maximum 2nd derivative where the function’s value is +/- 1.
Weight Initialization

• Assuming that the training set has been normalized and the previous sigmoid is used,

• Draw the initial weights from a distribution, such as a uniform distribution, with mean 0 and standard deviation $1/\sqrt{m}$ where $m$ is the fan-in (number of inputs to the node).

• Increases likelihood that the input to the sigmoid will have a standard deviation of 1 (since the latter is the $\sqrt{\text{sum of the squares of the weights}}$, for normalized input).
Learning Rates

• Ideally, each weight should have its own learning rate. See the Neural Networks Tricks of the Trade, Orr and Muller, eds., LNCS 1524 for how to choose learning rate based on 2nd derivatives.

• As a substitute, each neuron, or each layer could have its own learning rate.

• Learning rates should be proportional to the sqrt of the number of inputs to the neuron.

• Weights in earlier layers should be larger than those in later layers, since the earlier layers tend to have a smaller 2nd derivative of the MSE.
Second Derivatives by Layer

Fig. 1.21. Multilayered architecture: the second derivative is often smaller in lower layers.
Validation Technique ("Cross-Validation") & Early Stopping

• Split the training set into training and validation subsets, e.g. 2:1 or 5:1 ratio.
• Train only on the training subset; use the validation set for MSE, every so often (e.g. every 5 epochs).
• For early stopping: Stop training as soon as the validation error goes up.
• Use the weights before the error went up.
• Rational: Even though a lower minimum might have been reached, the local minima tend to be fairly close in value in practice.
A Validation Error Curve

See Neural Networks Tricks of the Trade, Orr and Muller, eds., LNCS 1524 for further refinements of the validation idea.
Over-Fitting

- It is possible for a network to *over-fit* the data, meaning that it learns small variations in the data which might actually be due to noise.
- Another way of saying this is that the network does not generalize well; it is *too specialized*.
- **Validation** is one technique used to help avoid over-fitting.
- Over-fitting can result if the network has *too many neurons* at its disposal.
Sizing a Network

• Given a problem:
  – How many layers?
  – How many neurons per layer?
  – What activation functions?
Layers

- Theoretically, any function can be emulated over a given range by a network with just one hidden layer and one output layer (two layers total), with sufficient neurons in that layer.

- Practically, 2-3 layers suffice for large families of problems, although more may be used, especially when special feature-selection layers are used, as in the zip-code recognition network.
Neurons

• Choose number of neurons based on the assessed complexity within a layer (number of crests and valleys of a function, for example).

• Two approaches for experimental determination:
  – Start with a large number of neurons and prune.
  – Start with a small number of neurons and build up.
Pruning

• Negligible weights can be eliminated (set to 0).
• If all input weights to a node are 0, the node can be eliminated.
• If all weights a node feeds are 0, the node itself can be eliminated.
• Vary weights $w$ to see whether $\frac{\partial J}{\partial w}$ is significant; if not, prune the weight.
Building

• Cascade-Correlation Network (Fahlman) adds one neuron at a time, testing the quality of the results and stopping when they are adequate.

• Training by correlation is a technique to be explored later.

• Problem with cascade correlation is that each added neuron is effectively a new layer.
Doubling

• Start with a small number of neurons in the inner layer.
• If at the conclusion of a training cycle, the MSE is inadequate, repeat with double the number of neurons.
Number of Training Samples for a Given Size Network

- Baum-Hausler rule (1989):

  **Necessary condition:**

  \[(\text{number of samples}) > \frac{W}{1-a}\]

  where \(W\) is the number of weights in the network and \(a\) is the desired accuracy on the test set.

- **Sufficient condition:**

  \[(\text{number of samples}) \geq \log\left(\frac{N}{1-a}\right) \times \frac{W}{1-a}\]

  where \(N\) is the number of neurons.