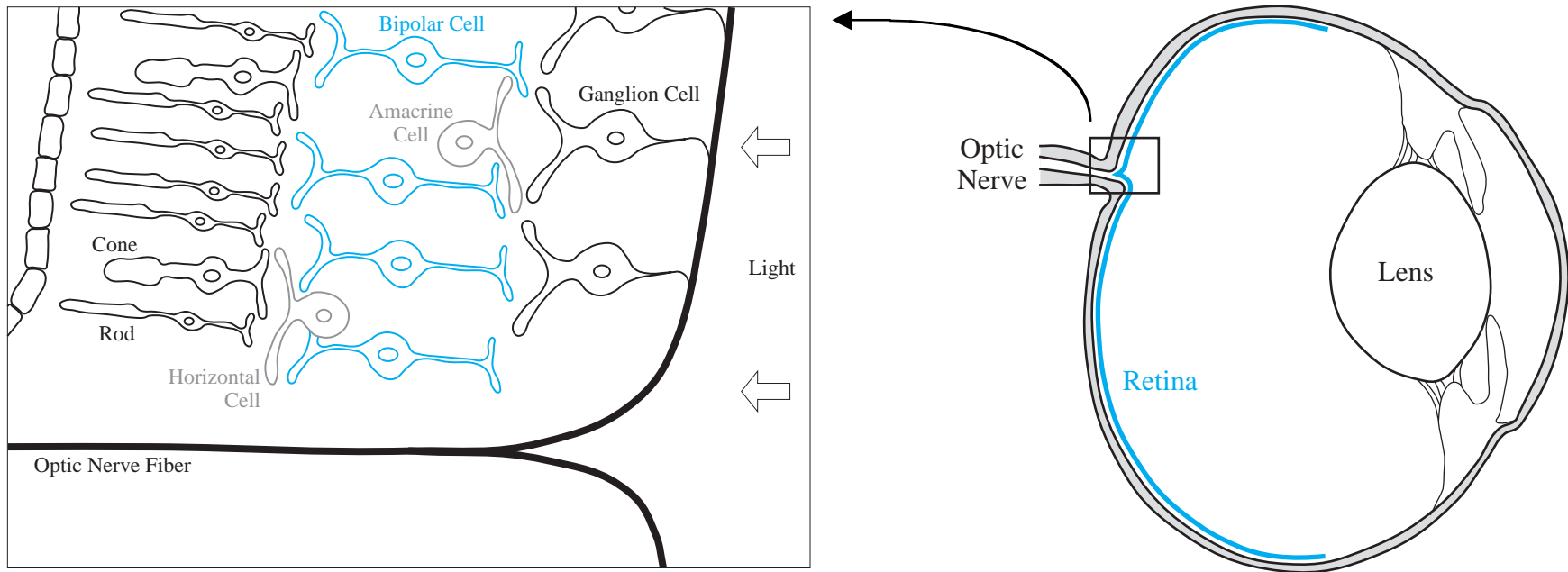




Grossberg Network



Eyeball and Retina



The retina is a part of the brain that covers the back inner wall of the eye and consists of three layers of neurons:

Outer Layer:

Photoreceptors - convert light into electrical signals

Rods - allow us to see in dim light

Cones - fine detail and color

Middle Layer

Bipolar Cells - link photoreceptors to third layer

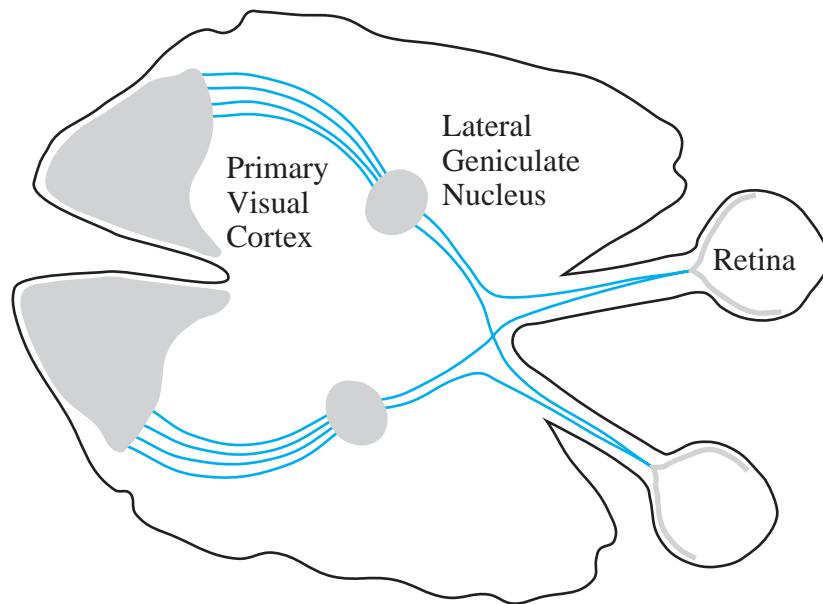
Horizontal Cells - link receptors with bipolar cells

Amacrine Cells - link bipolar cells with ganglion cells

Final Layer

Ganglion Cells - link retina to brain through optic nerve

Visual Pathway



15

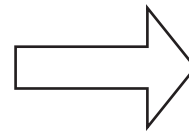
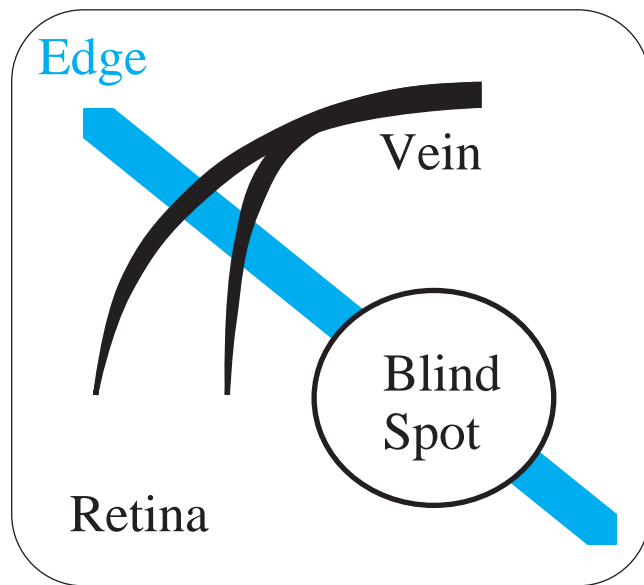
Photograph of the Retina



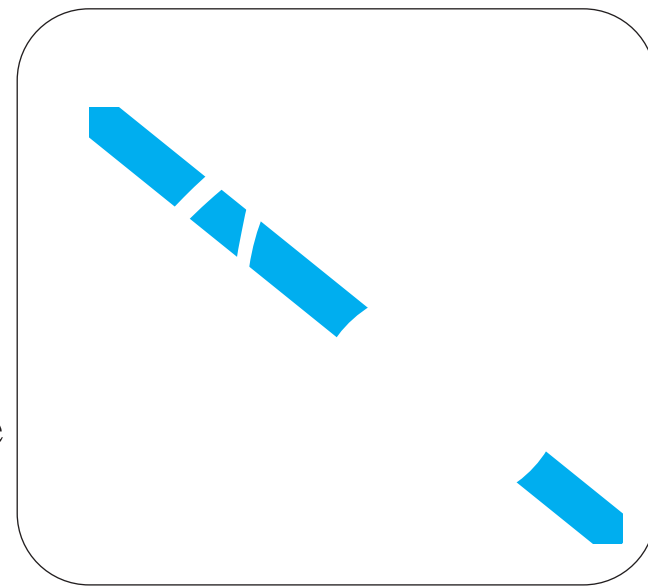
Blind Spot (Optic Disk)

Vein

Fovea



Stabilized
Images Fade



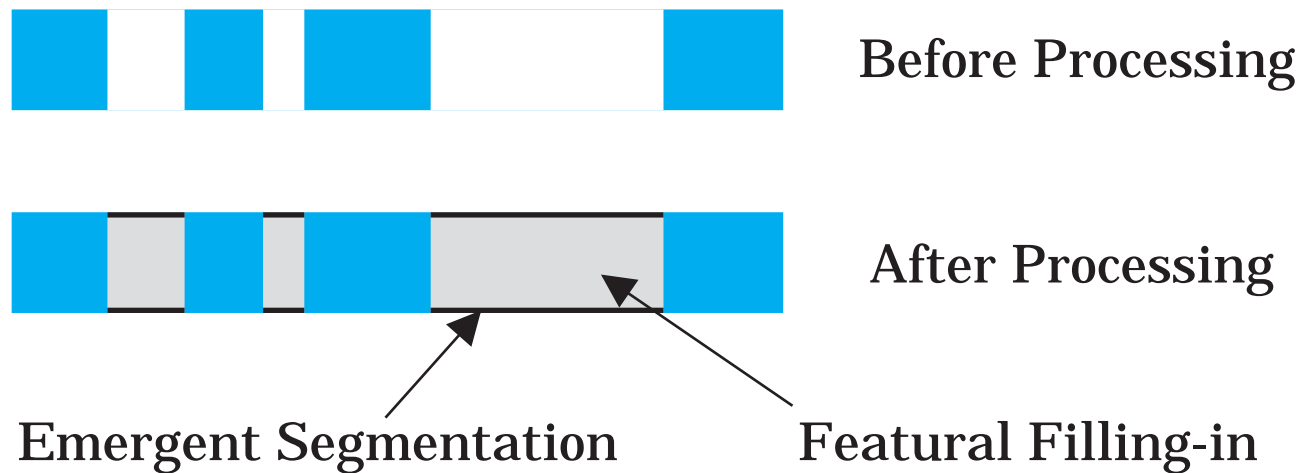


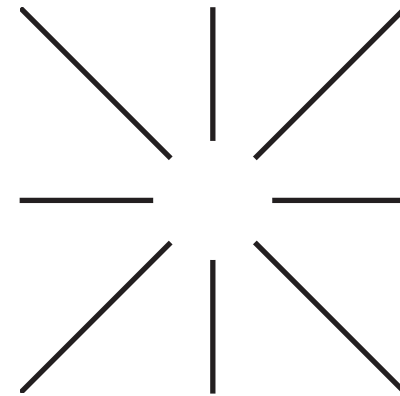
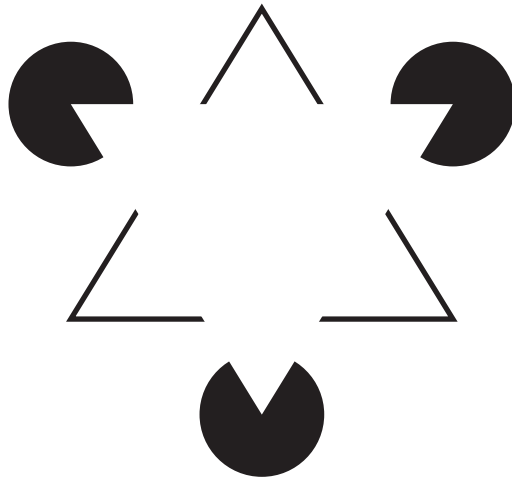
Emergent Segmentation:

Complete missing boundaries.

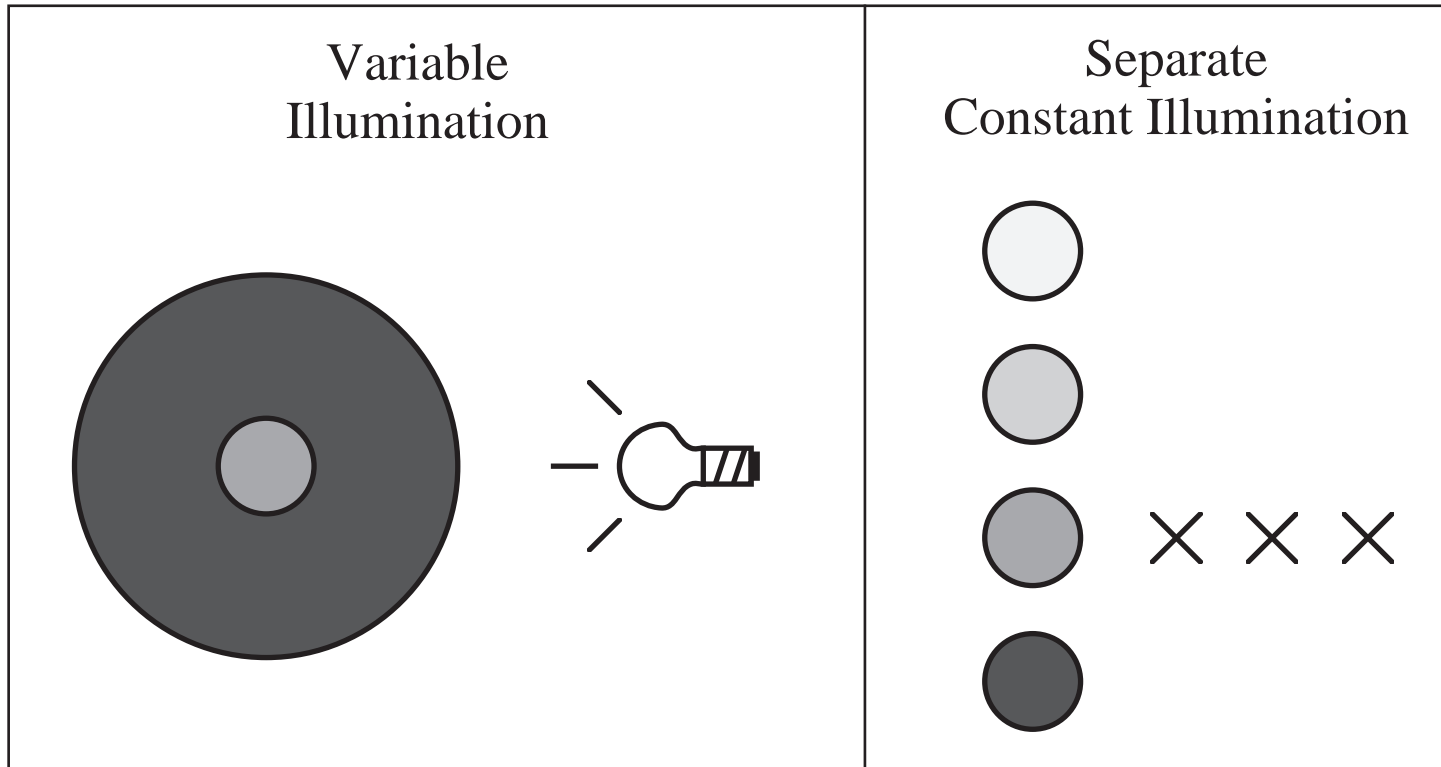
Featural Filling-In:

Fill in color and brightness.

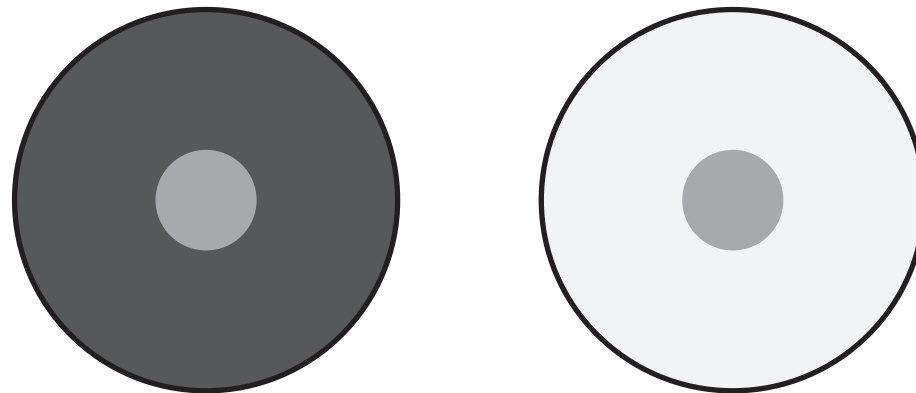




Illusions demonstrate the compensatory processing of the visual system. Here we see a bright white triangle and a circle which do not actually exist in the figures.



The vision systems normalize scenes so that we are only aware of relative differences in brightness, not absolute brightness.



If you look at a point between the two circles, the small inner circle on the left will appear lighter than the small inner circle on the right, although they have the same brightness. It is relatively lighter than its surroundings.

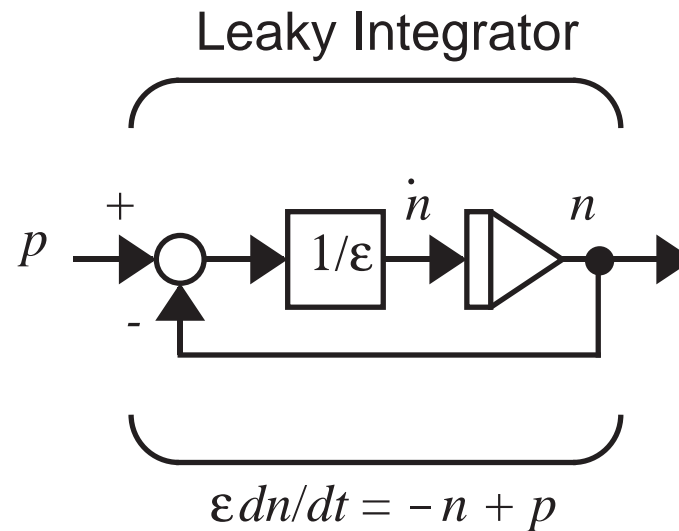
The visual system normalizes the scene. We see relative intensities.

Leaky Integrator



(Building block for basic nonlinear model.)

$$\varepsilon \frac{dn(t)}{dt} = -n(t) + p(t)$$

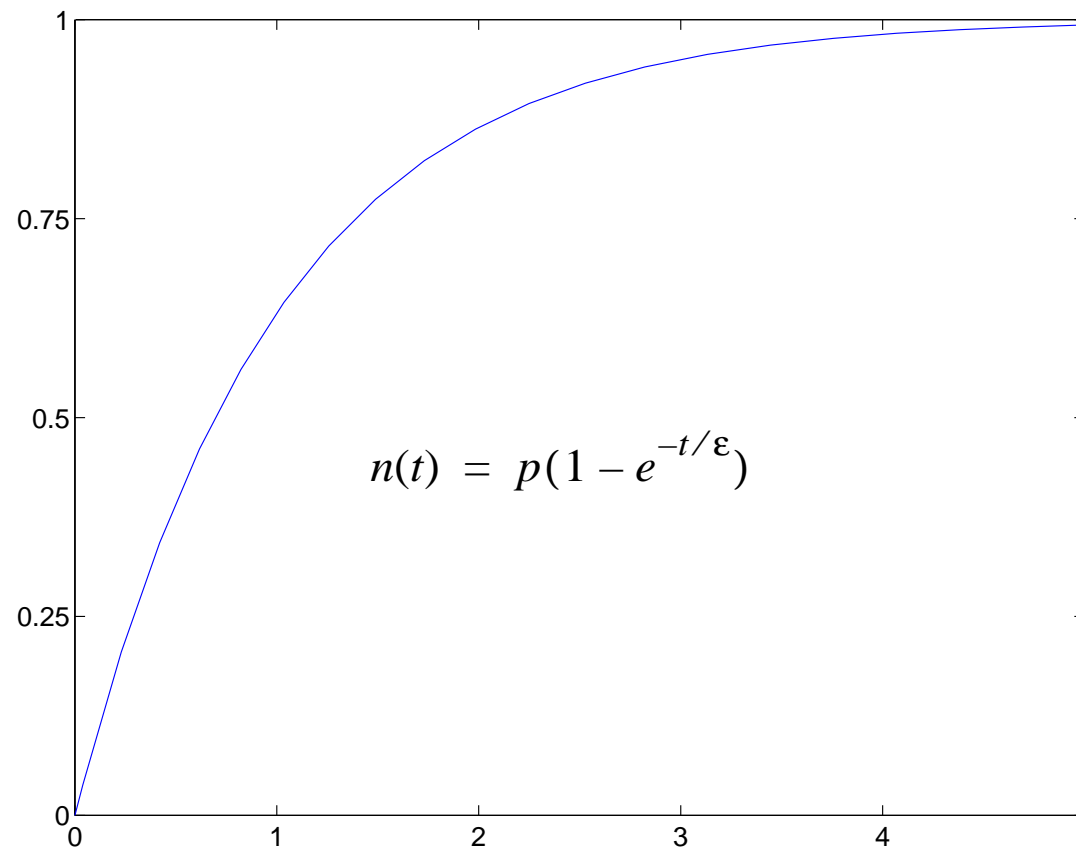


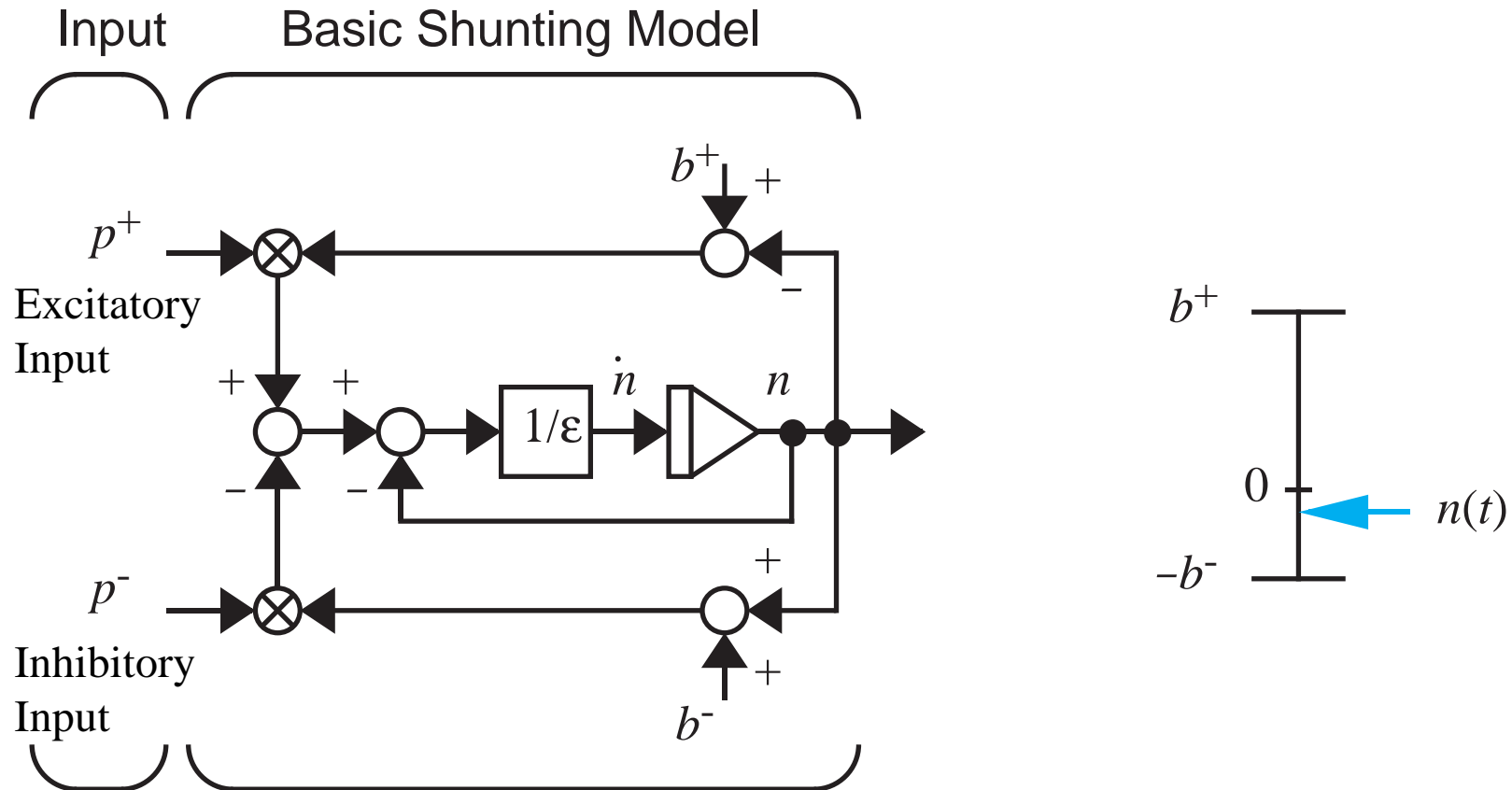
Leaky Integrator Response



$$n(t) = e^{-t/\varepsilon} n(0) + \frac{1}{\varepsilon} \int_0^t e^{-(t-\tau)/\varepsilon} p(t-\tau) d\tau$$

For a constant input and zero initial conditions:





$$\epsilon \frac{dn}{dt} = -n + \underbrace{(b^+ - n)p^+}_{\text{Gain Control (Sets upper limit)}} - \underbrace{(n + b^-)p^-}_{\text{Gain Control (Sets lower limit)}}$$

Gain Control (Sets upper limit) Gain Control (Sets lower limit)

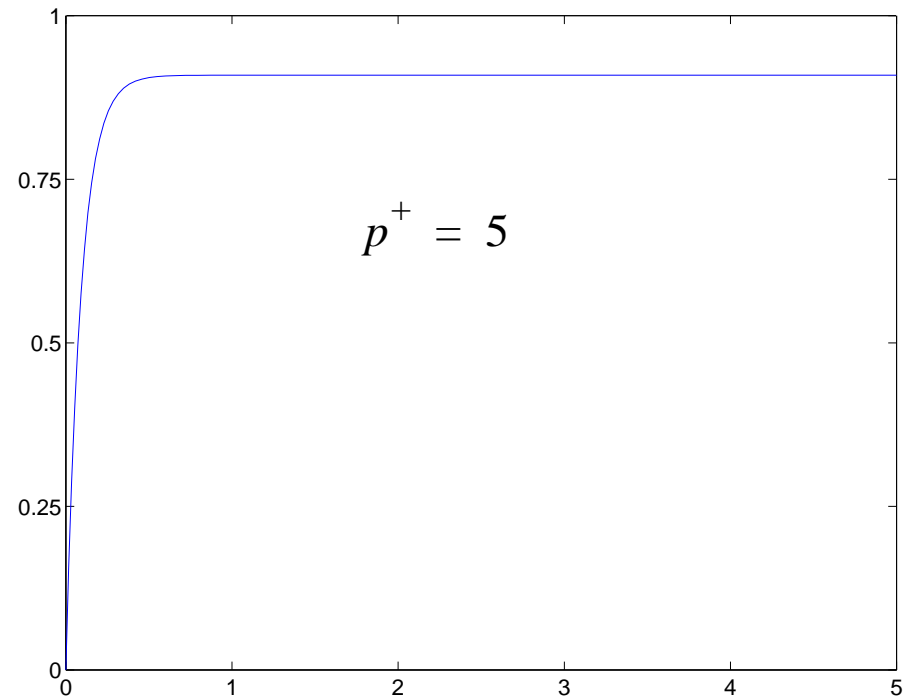
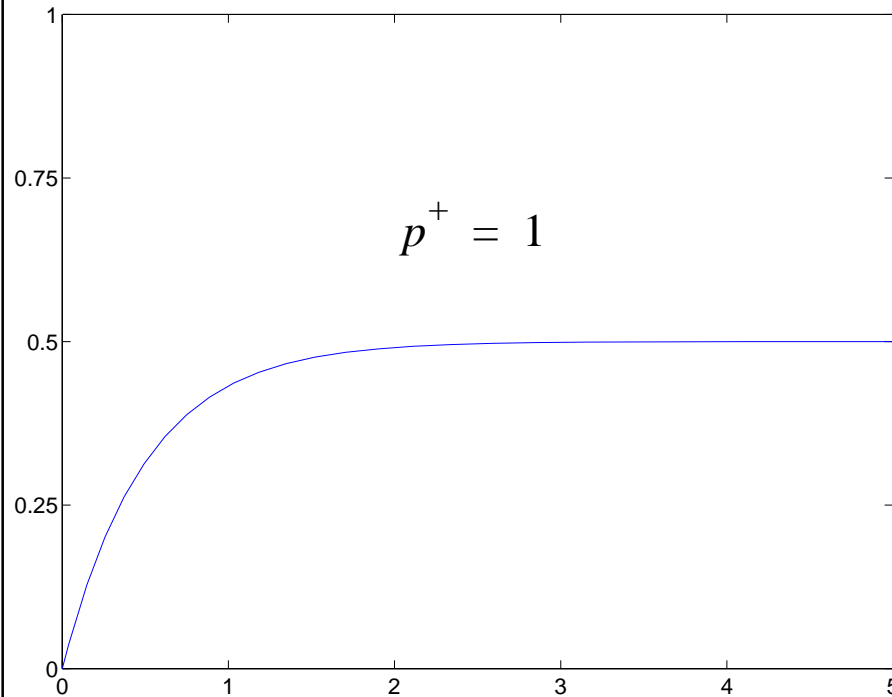
Shunting Model Response

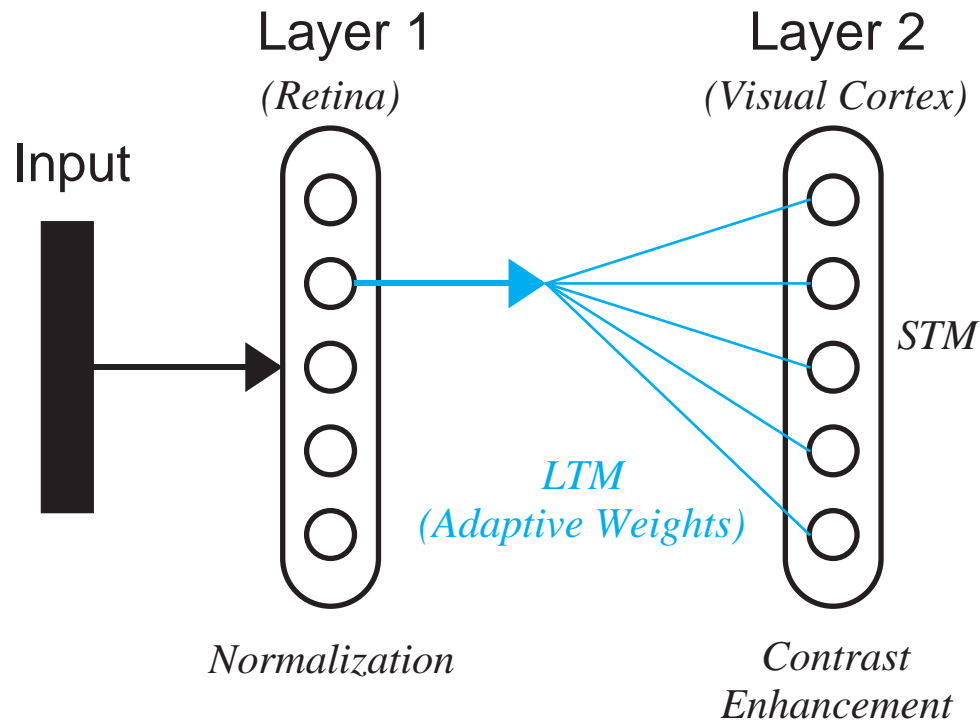


$$\varepsilon \frac{dn(t)}{dt} = -n(t) + (b^+ - n(t))p^+ - (n(t) + b^-)p^-$$

$$b^+ = 1 \quad b^- = 0 \quad \varepsilon = 1 \quad p^- = 0$$

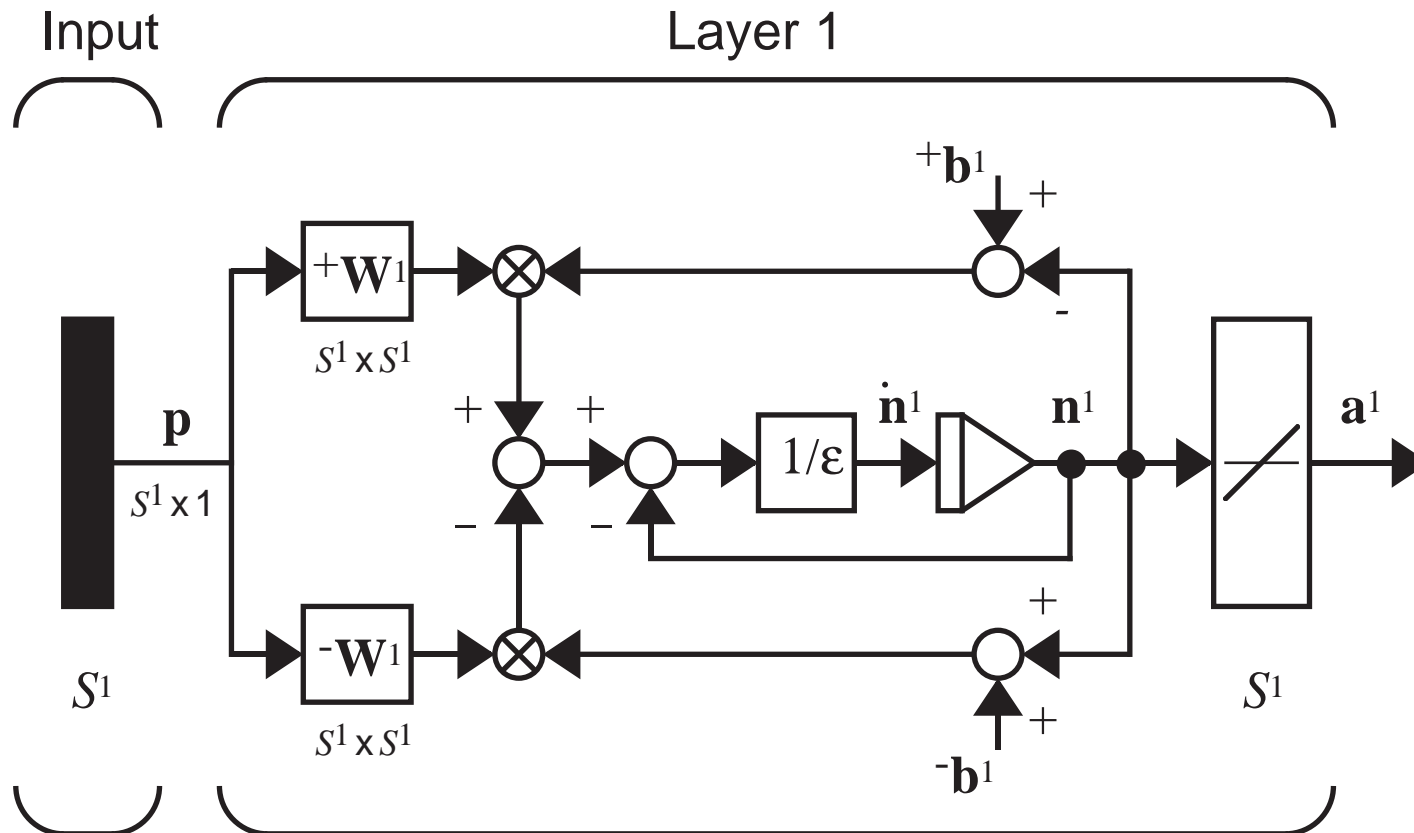
Upper limit will be 1, and lower limit will be 0.





LTM - Long Term Memory (Network Weights)

STM - Short Term Memory (Network Outputs)



$$\epsilon d\mathbf{n}^1/dt = -\mathbf{n}^1 + ({}^+b^1 - \mathbf{n}^1)[{}^+W_1]\mathbf{p} - (\mathbf{n}^1 + {}^-b^1)[{}^-W_1]\mathbf{p}$$



$$\varepsilon \frac{d\mathbf{n}^1(t)}{dt} = -\mathbf{n}^1(t) + ({}^+\mathbf{b}^1 - \mathbf{n}^1(t)) [{}^+\mathbf{W}^1] \mathbf{p} - (\mathbf{n}^1(t) + {}^-\mathbf{b}^1) [{}^-\mathbf{W}^1] \mathbf{p}$$

$${}^-\mathbf{b}^1 = \mathbf{0}$$

$${}^+b_i^1 = {}^+b_i^1$$

Excitatory Input

$$[{}^+\mathbf{W}^1] \mathbf{p}$$

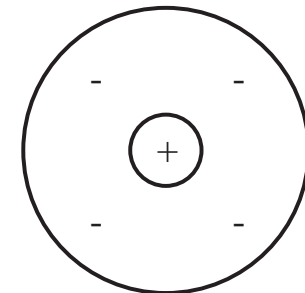
$${}^+\mathbf{W}^1 = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

Inhibitory Input

$$[{}^-\mathbf{W}^1] \mathbf{p}$$

$${}^-\mathbf{W}^1 = \begin{bmatrix} 0 & 1 & \cdots & 1 \\ 1 & 0 & \cdots & 1 \\ \vdots & \vdots & & \vdots \\ 1 & 1 & \cdots & 0 \end{bmatrix}$$

On-Center/
Off-Surround
Connection
Pattern



Normalizes the input while maintaining relative intensities.



Neuron i response:

$$\varepsilon \frac{dn_i^1(t)}{dt} = -n_i^1(t) + ({}^+b^1 - n_i^1(t))p_i - n_i^1(t) \sum_{j \neq i} p_j$$

At steady state:

$$0 = -n_i^1 + ({}^+b^1 - n_i^1)p_i - n_i^1 \sum_{j \neq i} p_j \quad \Rightarrow \quad n_i^1 = \frac{{}^+b^1 p_i}{1 + \sum_{j=1}^{S^1} p_j}$$

Define relative intensity:

$$\bar{p}_i = \frac{p_i}{P} \quad \text{where} \quad P = \sum_{j=1}^{S^1} p_j$$

Steady state neuron activity:

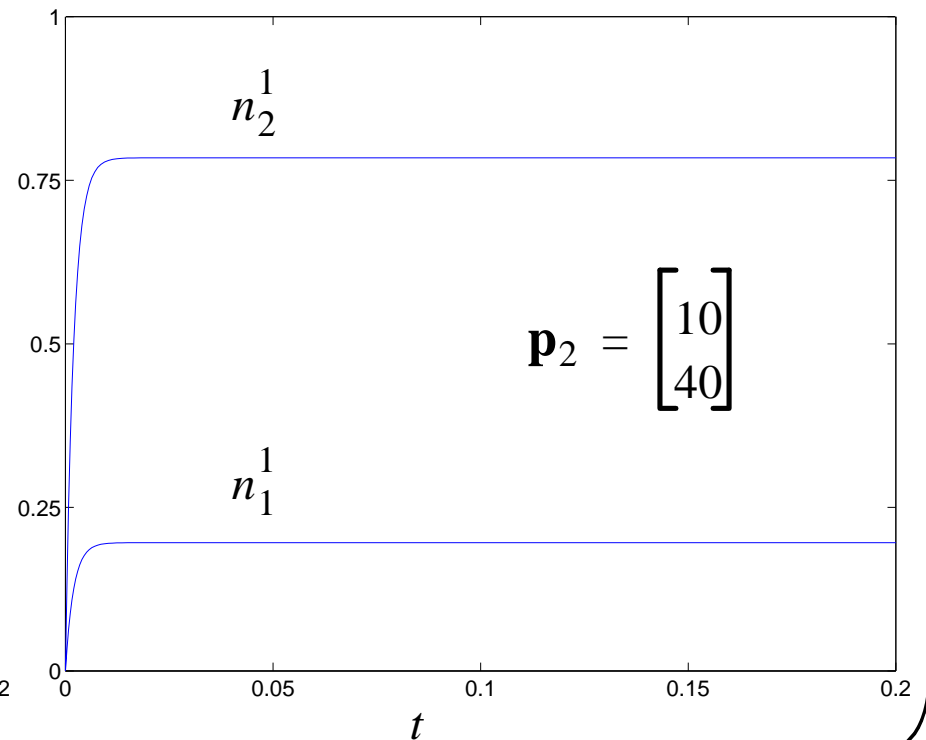
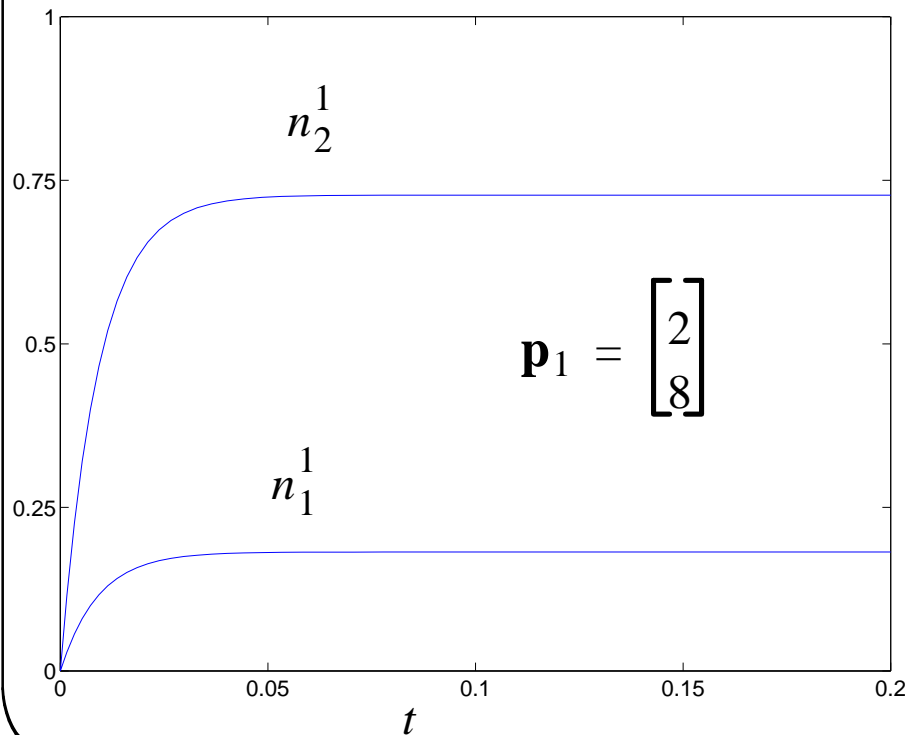
$$n_i^1 = \left(\frac{{}^+b^1 P}{1 + P} \right) \bar{p}_i \quad \text{Total activity:} \quad \sum_{j=1}^{S^1} n_j^1 = \sum_{j=1}^{S^1} \left(\frac{{}^+b^1 P}{1 + P} \right) \bar{p}_j = \left(\frac{{}^+b^1 P}{1 + P} \right) \leq {}^+b^1$$

Layer 1 Example



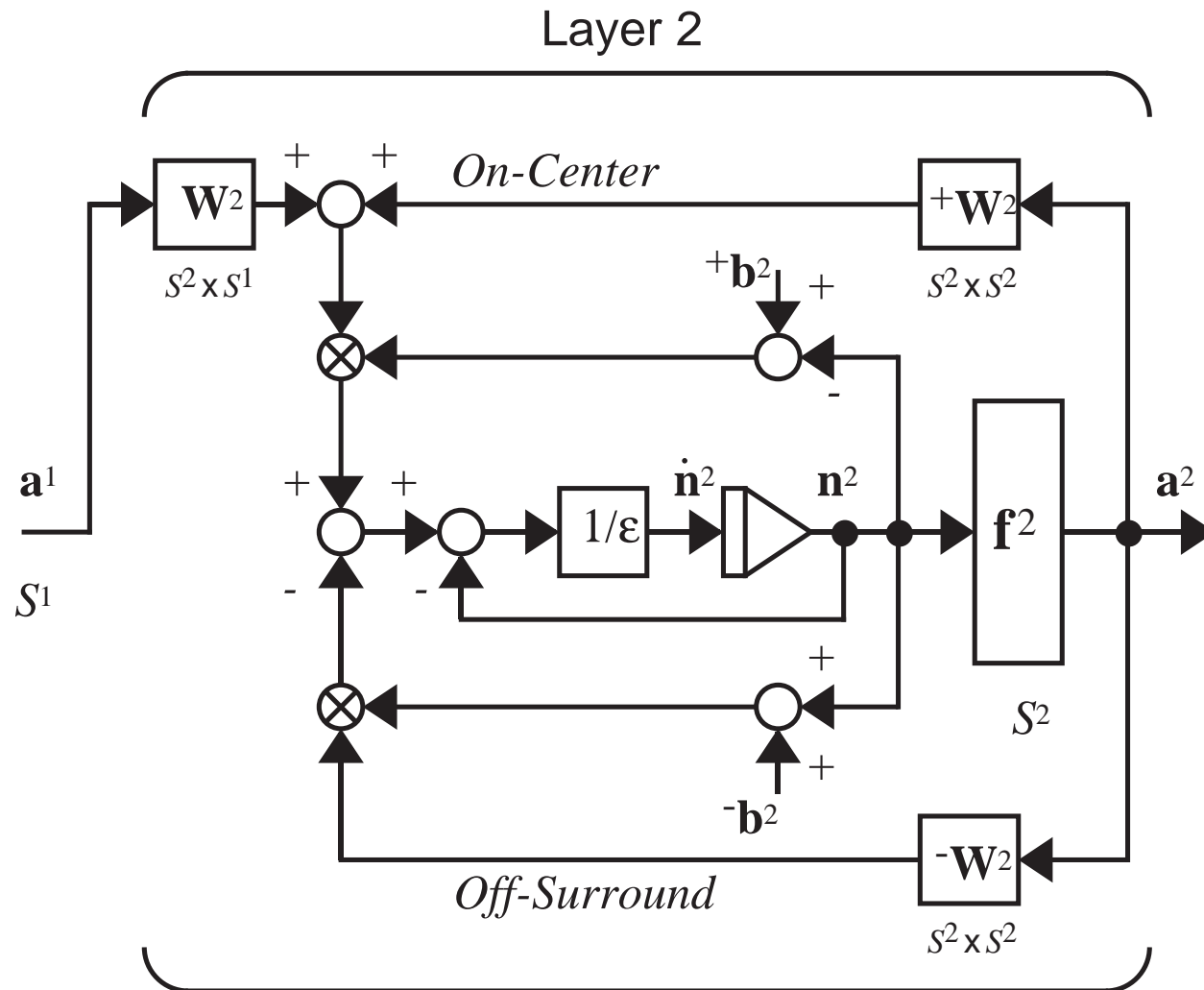
$$(0.1) \frac{dn_1^1(t)}{dt} = -n_1^1(t) + (1 - n_1^1(t))p_1 - n_1^1(t)p_2$$

$$(0.1) \frac{dn_2^1(t)}{dt} = -n_2^1(t) + (1 - n_2^1(t))p_2 - n_2^1(t)p_1$$





- The network is sensitive to relative intensities of the input pattern, rather than absolute intensities.
- The output of Layer 1 is a normalized version of the input pattern.
- The on-center/off-surround connection pattern and the nonlinear gain control of the shunting model produce the normalization effect.
- The operation of Layer 1 explains the brightness constancy and brightness contrast characteristics of the human visual system.



$$\epsilon dn^2/dt = -n^2 + (+b^2 - n^2) \{ [+W^2] f^2(n^2) + W^2 a^1 \} \\ - (n^2 + -b^2) [-W^2] f^2(n^2)$$



$$\varepsilon \frac{d\mathbf{n}^2(t)}{dt} = -\mathbf{n}^2(t) + ({}^+\mathbf{b}^2 - \mathbf{n}^2(t)) \{ [{}^+\mathbf{W}^2] \mathbf{f}^2(\mathbf{n}^2(t)) + \mathbf{W}^2 \mathbf{a}^1 \} \\ - (\mathbf{n}^2(t) + {}^-\mathbf{b}^2) [{}^-\mathbf{W}^2] \mathbf{f}^2(\mathbf{n}^2(t))$$

Excitatory Input:

$$\{ [{}^+\mathbf{W}^2] \mathbf{f}^2(\mathbf{n}^2(t)) + \mathbf{W}^2 \mathbf{a}^1 \}$$

$${}^+\mathbf{W}^2 = {}^+\mathbf{W}^1 \quad (\text{On-center connections})$$

$$\mathbf{W}^2 \quad (\text{Adaptive weights})$$

Inhibitory Input:

$$[{}^-\mathbf{W}^2] \mathbf{f}^2(\mathbf{n}^2(t))$$

$${}^-\mathbf{W}^2 = {}^-\mathbf{W}^1 \quad (\text{Off-surround connections})$$

Layer 2 Example



$$\varepsilon = 0.1 \quad \mathbf{b}^2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \bar{\mathbf{b}}^2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad f^2(n) = \frac{10(n)^2}{1 + (n)^2} \quad \mathbf{W}^2 = \begin{bmatrix} ({}_1\mathbf{w}^2)^T \\ ({}_2\mathbf{w}^2)^T \end{bmatrix} = \begin{bmatrix} 0.9 & 0.45 \\ 0.45 & 0.9 \end{bmatrix}$$

Correlation between
prototype 1 and input.

$$(0.1) \frac{dn_1^2(t)}{dt} = -n_1^2(t) + (1 - n_1^2(t)) \left\{ f^2(n_1^2(t)) + \overbrace{({}_1\mathbf{w}^2)^T \mathbf{a}^1} \right\} - n_1^2(t) f^2(n_2^2(t))$$

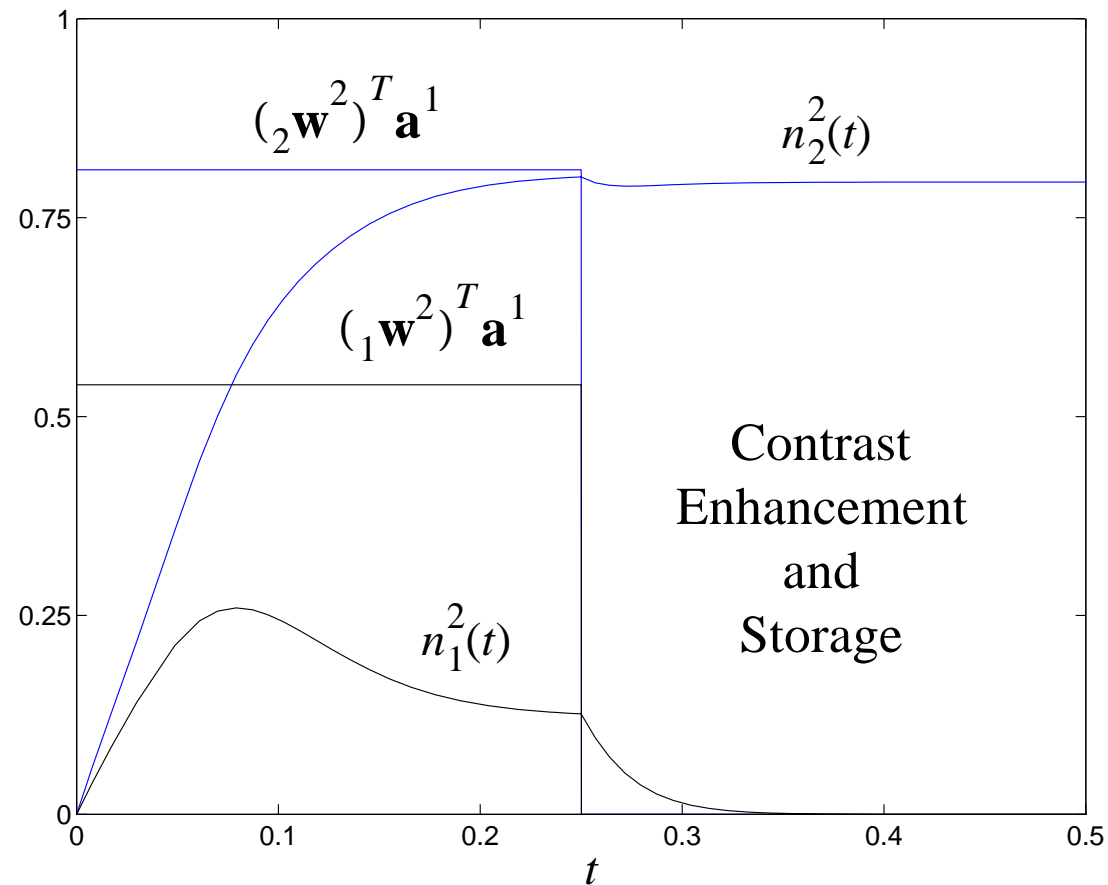
Correlation between
prototype 2 and input.

$$(0.1) \frac{dn_2^2(t)}{dt} = -n_2^2(t) + (1 - n_2^2(t)) \left\{ f^2(n_2^2(t)) + \overbrace{({}_2\mathbf{w}^2)^T \mathbf{a}^1} \right\} - n_2^2(t) f^2(n_1^2(t)) .$$

Layer 2 Response



$$\mathbf{a}^1 = \begin{bmatrix} 0.2 \\ 0.8 \end{bmatrix}$$



Input to neuron 1:

$$({}_1\mathbf{w}^2)^T \mathbf{a}^1 = [0.9 \ 0.45] \begin{bmatrix} 0.2 \\ 0.8 \end{bmatrix} = 0.54$$

Input to neuron 2:

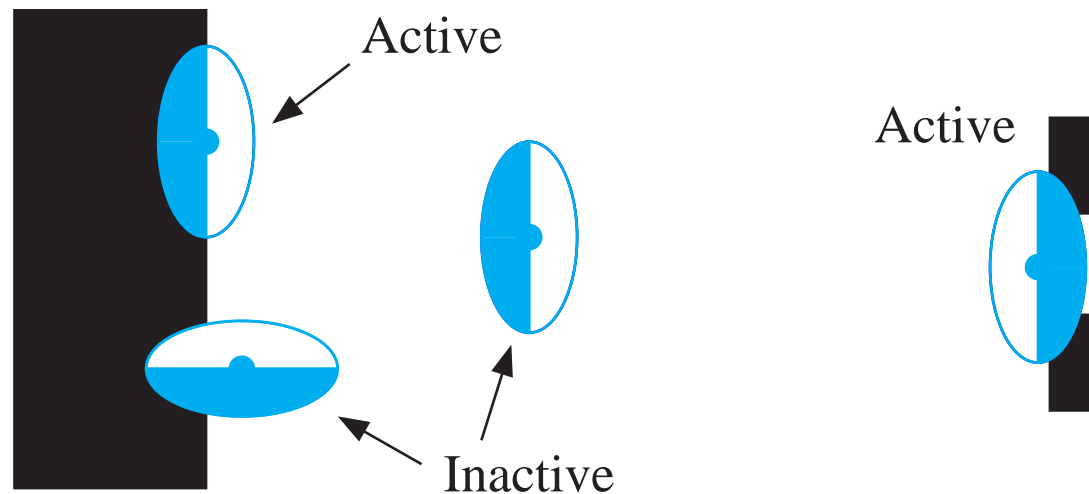
$$({}_2\mathbf{w}^2)^T \mathbf{a}^1 = [0.45 \ 0.9] \begin{bmatrix} 0.2 \\ 0.8 \end{bmatrix} = 0.81$$

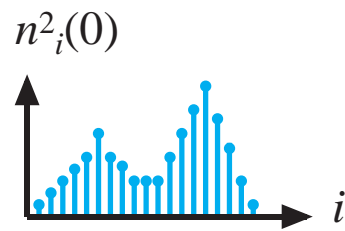


- As in the Hamming and Kohonen networks, the inputs to Layer 2 are the inner products between the prototype patterns (rows of the weight matrix \mathbf{W}^2) and the output of Layer 1 (normalized input pattern).
- The nonlinear feedback enables the network to store the output pattern (pattern remains after input is removed).
- The on-center/off-surround connection pattern causes contrast enhancement (large inputs are maintained, while small inputs are attenuated).



When an oriented receptive field is used, instead of an on-center/off-surround receptive field, the emergent segmentation problem can be understood.





$f^2(n)$	Stored Pattern $n^2(\infty)$	Comments
<p>Linear</p>		Perfect storage of any pattern, but amplifies noise.
<p>Slower than Linear</p>		Amplifies noise, reduces contrast.
<p>Faster than Linear</p>		Winner-take-all, suppresses noise, quantizes total activity.
<p>Sigmoid</p>		Suppresses noise, contrast enhances, not quantized.



Hebb Rule with Decay

$$\frac{dw_{i,j}^2(t)}{dt} = \alpha \{-w_{i,j}^2(t) + n_i^2(t)n_j^1(t)\}$$

Instar Rule (Gated Learning)

$$\frac{dw_{i,j}^2(t)}{dt} = \alpha n_i^2(t) \{-w_{i,j}^2(t) + n_j^1(t)\} \quad \left\{ \begin{array}{l} \text{Learn when} \\ n_i^2(t) \text{ is active.} \end{array} \right.$$

Vector Instar Rule

$$\frac{d[{}_i\mathbf{w}^2(t)]}{dt} = \alpha n_i^2(t) \{-[{}_i\mathbf{w}^2(t)] + \mathbf{n}^1(t)\}$$



$$\frac{dw_{1,1}^2(t)}{dt} = n_1^2(t) \{-w_{1,1}^2(t) + n_1^1(t)\}$$

$$\frac{dw_{1,2}^2(t)}{dt} = n_1^2(t) \{-w_{1,2}^2(t) + n_2^1(t)\}$$

$$\frac{dw_{2,1}^2(t)}{dt} = n_2^2(t) \{-w_{2,1}^2(t) + n_1^1(t)\}$$

$$\frac{dw_{2,2}^2(t)}{dt} = n_2^2(t) \{-w_{2,2}^2(t) + n_2^1(t)\}$$



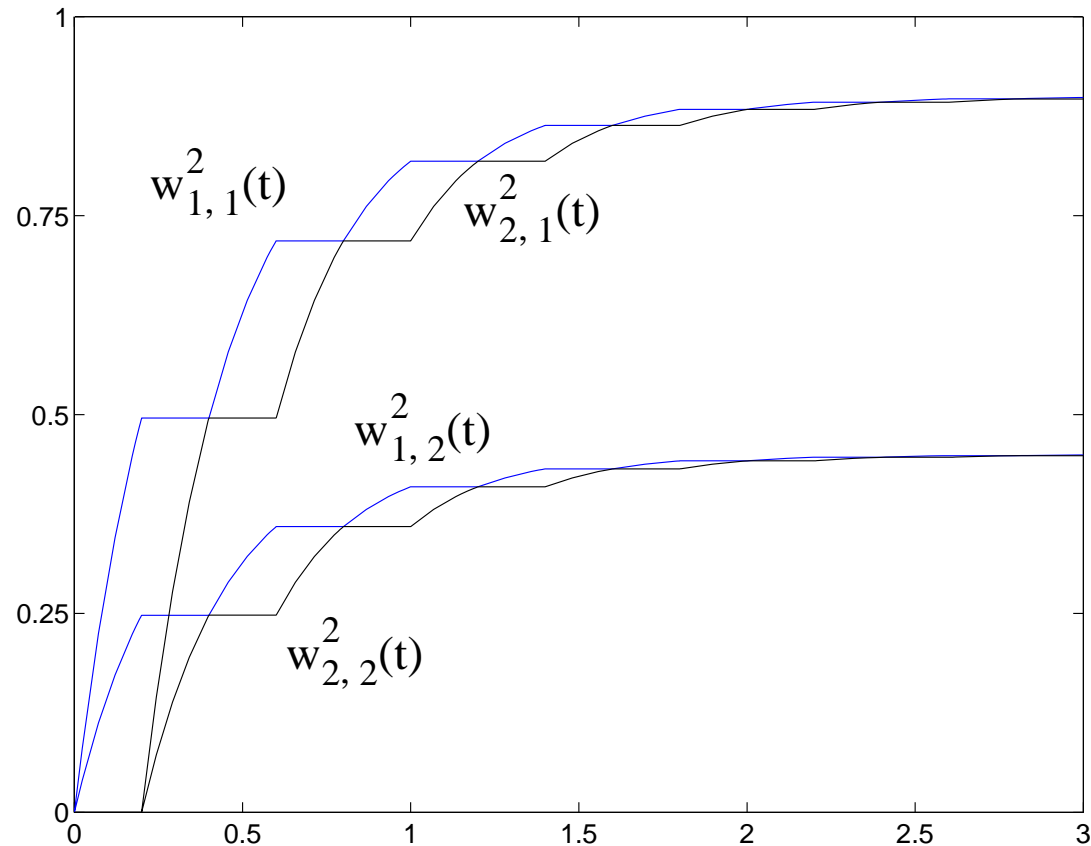
Two different input patterns are alternately presented to the network for periods of 0.2 seconds at a time.

For Pattern 1:

$$\mathbf{n}^1 = \begin{bmatrix} 0.9 \\ 0.45 \end{bmatrix} \quad \mathbf{n}^2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

For Pattern 2:

$$\mathbf{n}^1 = \begin{bmatrix} 0.45 \\ 0.9 \end{bmatrix} \quad \mathbf{n}^2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



The first row of the weight matrix is updated when $n_1^2(t)$ is active, and the second row of the weight matrix is updated when $n_2^2(t)$ is active.



Grossberg Learning (Continuous-Time)

$$\frac{d[{}_i\mathbf{w}^2(t)]}{dt} = \alpha n_i^2(t) \{-[{}_i\mathbf{w}^2(t)] + \mathbf{n}^1(t)\}$$

Euler Approximation for the Derivative

$$\frac{d[{}_i\mathbf{w}^2(t)]}{dt} \approx \frac{{}_i\mathbf{w}^2(t + \Delta t) - {}_i\mathbf{w}^2(t)}{\Delta t}$$

Discrete-Time Approximation to Grossberg Learning

$${}_i\mathbf{w}^2(t + \Delta t) = {}_i\mathbf{w}^2(t) + \alpha(\Delta t)n_i^2(t) \{-{}_i\mathbf{w}^2(t) + \mathbf{n}^1(t)\}$$



Rearrange Terms

$${}_i \mathbf{w}^2(t + \Delta t) = \{1 - \alpha(\Delta t)n_i^2(t)\} {}_i \mathbf{w}^2(t) + \alpha(\Delta t)n_i^2(t) \{ \mathbf{n}^1(t) \}$$

Assume Winner-Take-All Competition

$${}_{i^*} \mathbf{w}^2(t + \Delta t) = \{1 - \alpha'\} {}_{i^*} \mathbf{w}^2(t) + \{\alpha'\} \mathbf{n}^1(t) \quad \text{where} \quad \alpha' = \alpha(\Delta t)n_{i^*}^2(t)$$

Compare to Kohonen Rule

$${}_{i^*} \mathbf{w}(q) = (1 - \alpha) {}_{i^*} \mathbf{w}(q - 1) + \alpha \mathbf{p}(q)$$