
Some Applications of Backpropagation

Sonar target recognition

(Gorman and Sejnowski, 1988)

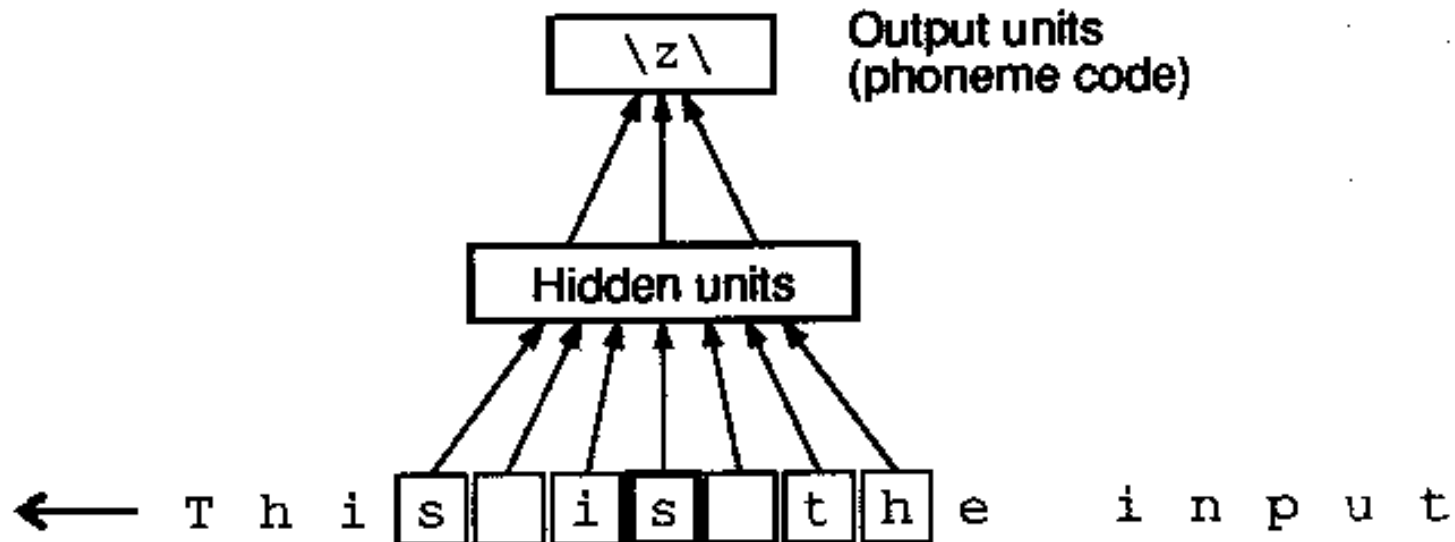
- 2-layer backprop network trained to distinguish between reflected sonar signals of rocks and metal cylinders at bottom of Chesapeake Bay
- 60 input units, 2 output units
- input patterns based on Fourier transform of raw time signal
- tried varying numbers of hidden units (0, 3, 12, 24)
- best performance with 12 hidden units (close to 100% accuracy)
- 85-90% classification accuracy for signals not in training set

NETTalk (Sejnowski and Rosenberg, 1986)

- Sejnowski, T. J. and Rosenberg, C. R. (1986)
NETtalk: a parallel network that learns to read aloud, *Cognitive Science*, 14, 179-211.
- The authors taught a neural network to “read” using backpropagation.
- A stream of words were given to the network, along with the phoneme pronunciation of each in symbolic form.
- A speech generation device was used to convert the phonemes to sound.
- The network learned the phoneme pronunciations, thus was able to “speak” the words from a stream of words.

NETTalk

- 203-80-26 Multi-layer network
- Input is rolling sequence of 7 characters
- $203 = 7 \times 29$ different characters
- Output is the phoneme (if any) for the middle letter in the sequence



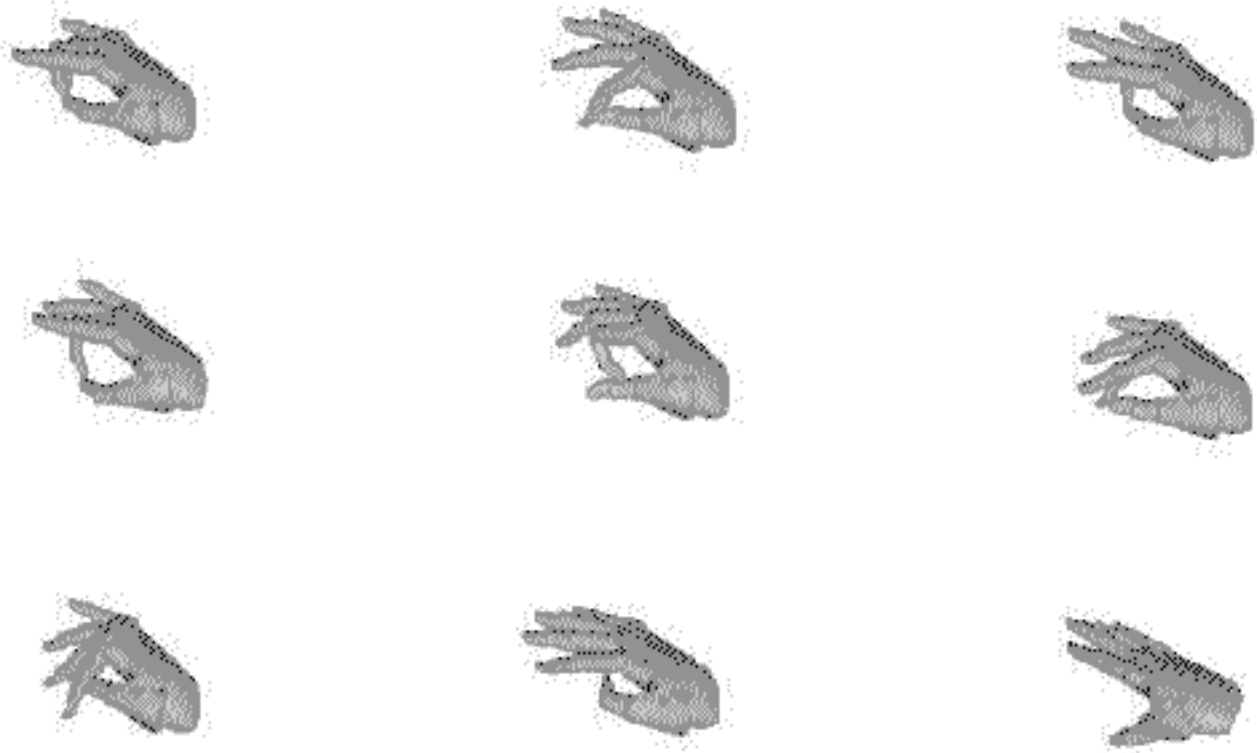
NETTalk

- 80 hidden units
- trained on 1024 words using a side-by-side English/phoneme source
- intelligible speech after 10 training epochs; 95% accuracy on training corpus after 50 epochs
- some hidden units developed meaningful responses (e.g., vowels vs. consonants)
- generalization: 78% accuracy on continuation of training text
- damaging network produced graceful degradation, with rapid recovery on retraining
- DECtalk performed better, but used hand-coded linguistic rules developed over a decade

GregTalk (2000)

- Similar results were reproduced in the spring 2000 offering of CS 152 by two Pomona College students named “Greg” (Greg Fishbein and Greg Schueler).
- The data for NETTalk can be found at
<http://homepages.cae.wisc.edu/~ece539/data/nettalk/>

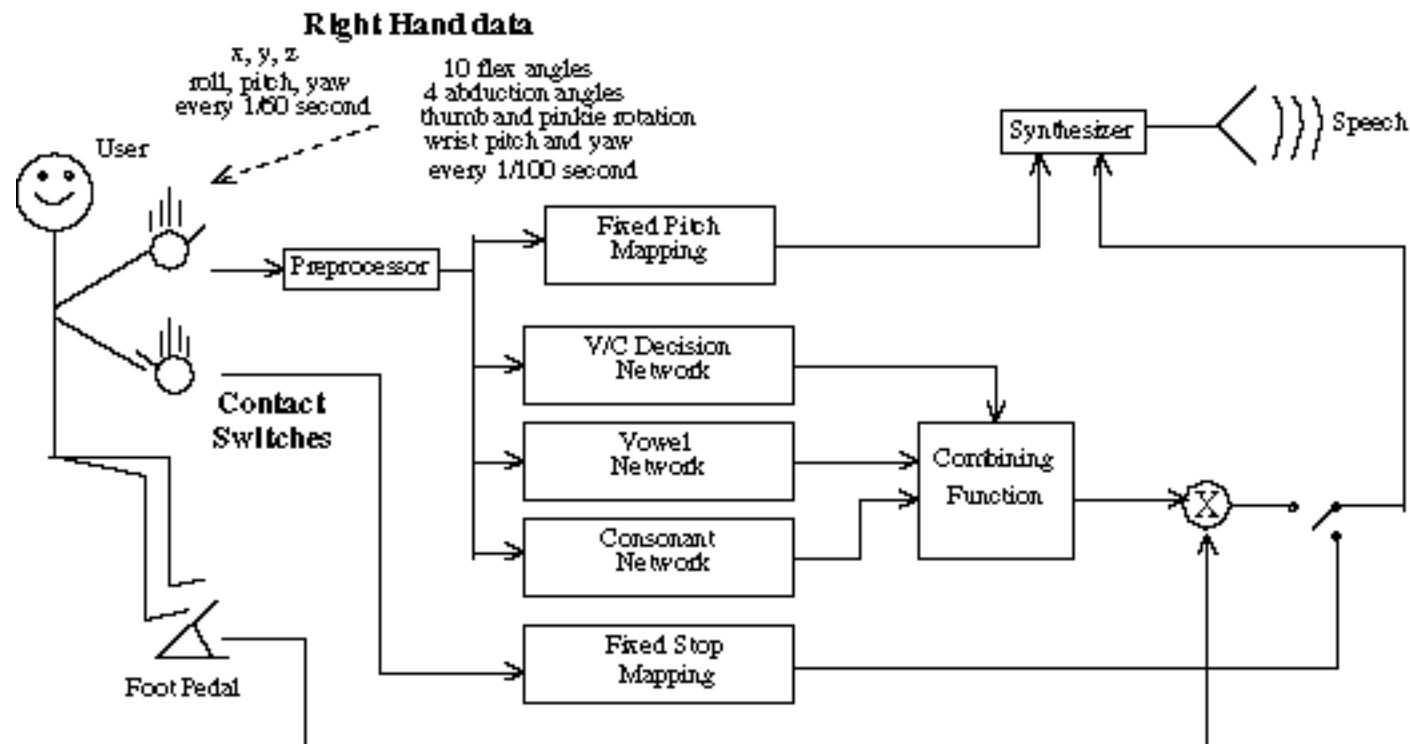
GloveTalk II (Fels & Hinton, 1995)



CHI '95 Proceedings

www.acm.org/sigchi/chi95/Electronic/documnts/papers/ssf_bdy.htm

GloveTalk II



Zipcode Recognition (Yann LeCun, 1990)

40004

75216

14199-2087

23505

96203

14310

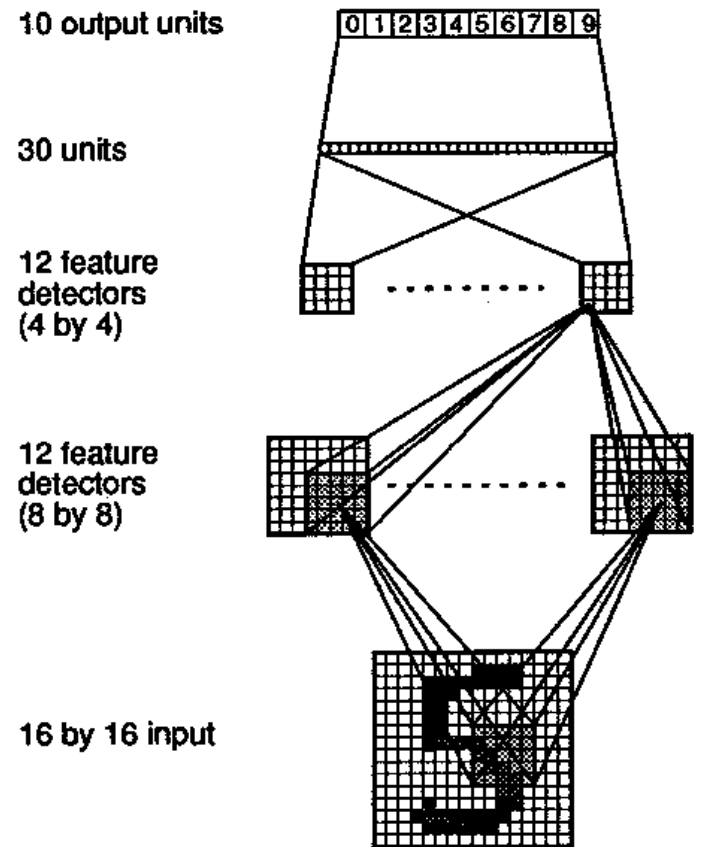
44151

05153

Normalize Digits First

1 4 1 0 1 1 9 1 5 4 8 5 7 2 6 8 0 3 2 2 6 4 1 4 1
8 6 6 3 5 9 7 2 0 2 9 9 2 9 9 7 2 2 5 1 0 0 4 6 7
0 1 3 0 8 4 4 4 4 5 9 1 0 1 0 6 1 5 4 0 6 1 0 3 6
3 1 1 0 6 4 1 1 1 0 3 0 4 7 5 2 6 2 0 0 9 9 7 9 9
6 6 8 9 1 2 0 8 6 7 2 8 5 5 7 1 3 1 4 2 7 9 5 5 4
6 0 2 0 1 8 7 5 0 1 2 7 1 1 2 9 9 3 0 8 9 9 7 0 9
8 4 0 1 0 9 7 0 7 5 9 7 3 3 1 9 7 2 0 1 5 5 1 9 0
6 5 1 0 7 5 5 1 2 5 5 1 8 2 8 1 4 3 5 8 0 9 0 9
4 3 1 7 8 7 5 2 1 6 5 5 4 6 0 3 5 4 6 0 3 5 4 6 0
5 5 1 8 2 5 5 1 0 8 5 0 3 0 4 7 5 2 0 4 3 9 4 0 1

Network Structure



Feature Detectors

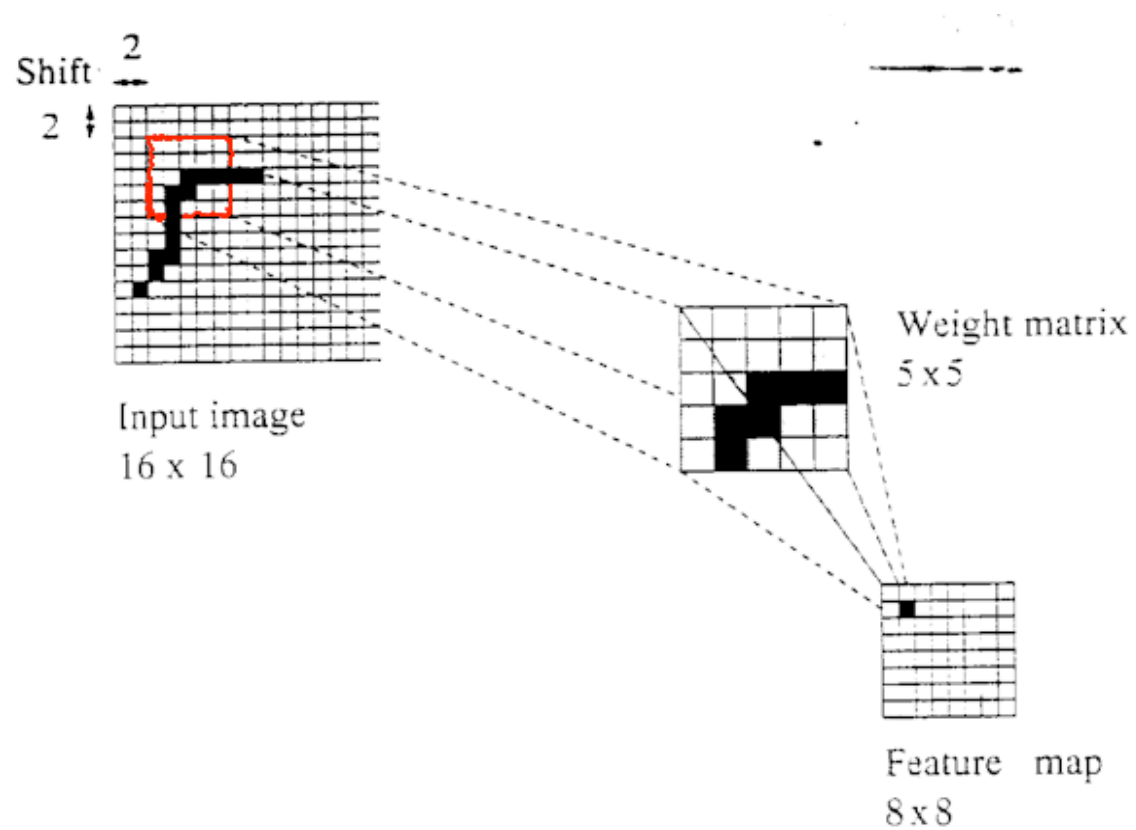


Figure 5.3: A feature map.

Sub-sampling Map

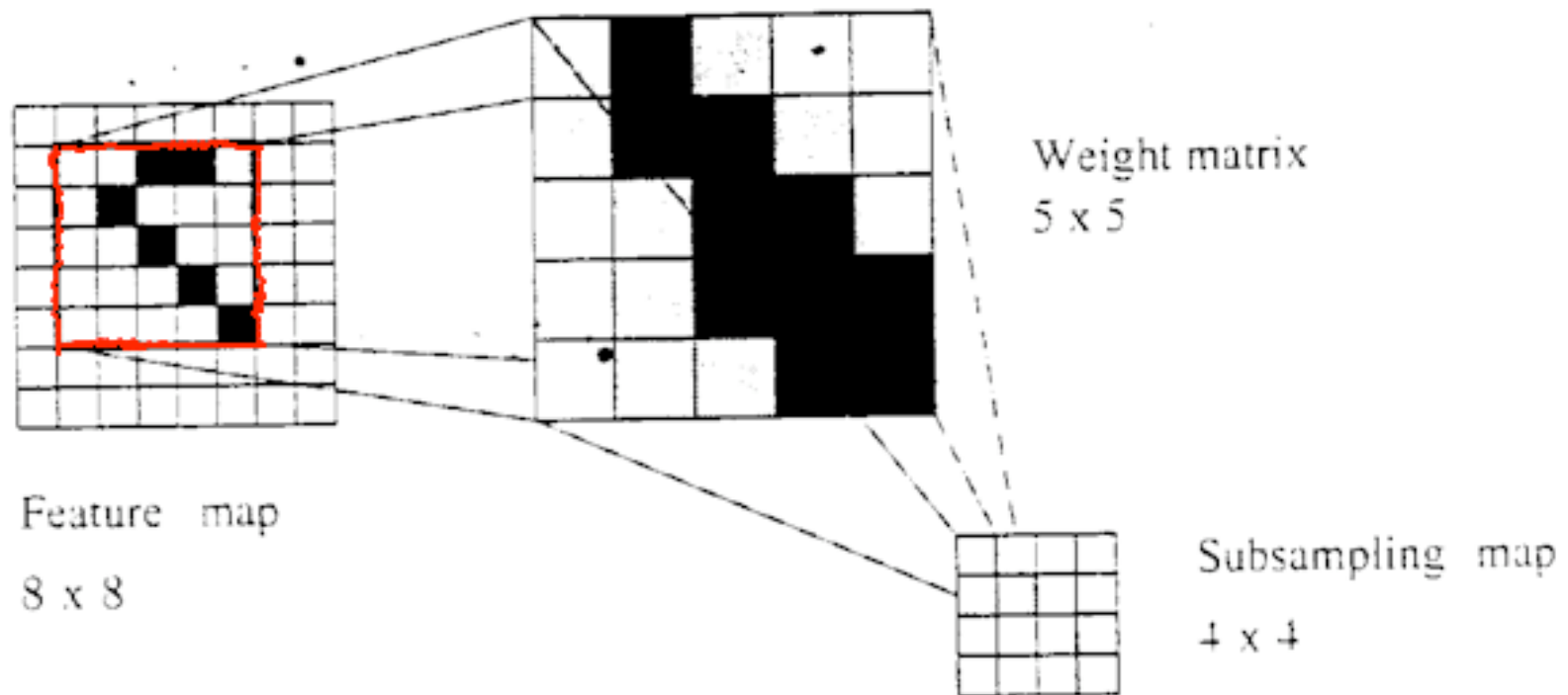


Figure 5.4: A sub-sampling map.

Architecture

- **Input layer:** 256 = 16x16 neurons with input values in range [-1, 1].
- **Hidden layer H1:** consists of 12 feature maps H1.1, ... , H1.12.
- **Feature map:**
 - 8x8 neurons.
 - Each neuron in the feature map has the *same* incoming weights, but is connected to a square at a unique position in the input image. This square is called a *template*.

Architecture

- Hidden layer H2: consists of 12 sub-sampling maps H2.1, ... , H2.12.
- Sub-sampling map:
 - Consists of 4x4 neurons.
 - Each neuron of the sub-sampling map is connected to a 5x5 square of H1.j, for each j in 8 of the 12 feature maps.
 - All neurons of the sub-sampling map share the same 25 weights.

Architecture

- Hidden layer H3:
 - Consists of 30 neurons.
 - H3 is completely connected to the sub-sampling layer (H2).
- Output layer: consists of 10 neurons, numbered 0, ... , 9 and the neuron with the highest activation value is chosen. The digit recognized is equal to the cell number.

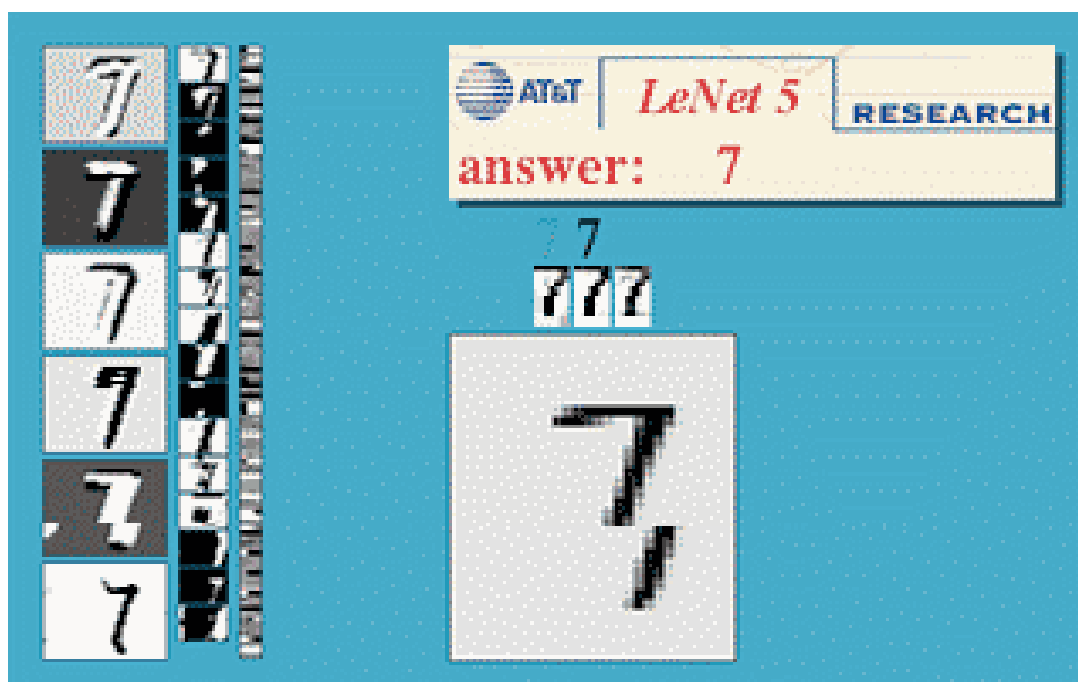
Atypical Data Recognized



Further Details and Results

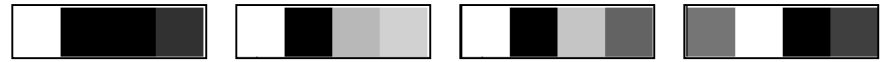
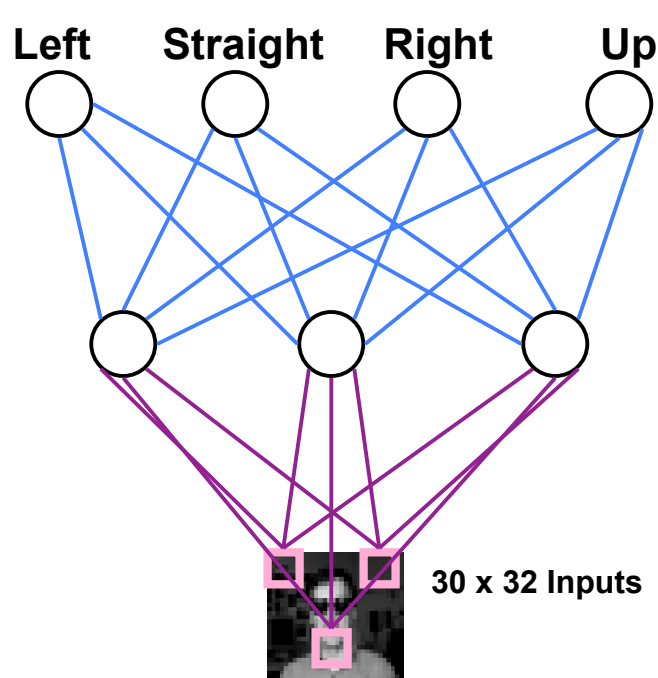
- [~10,000 digits from the U.S. mail](#) were used to train and test system
- ZIP codes on envelopes were initially located and segmented by a separate system (difficult task in itself)
- *weight sharing* used to constrain number of free parameters
- 1256 units + 30060 links + 1000 biases, but only 9760 free parameters
- used an accelerated version of backprop (pseudo-Newton rule)
- trained on 7300 digits, tested on 2000
- error rate of ~1% on training set, ~5% on test set
- if marginal cases were rejected (two or more outputs approximately the same), error reduced to ~1% with 12% rejected
- used "optimal brain damage" technique to prune unnecessary weights
- after removing weights and retraining, only ~1/4 as many free parameters as before, but better performance
- 99% classification accuracy with 9% rejection rate
- achieved state of the art in digit recognition
- much problem-specific knowledge was designed into the network architecture
- preprocessing of input data was crucial to success

<http://yann.lecun.com/exdb/lenet/>

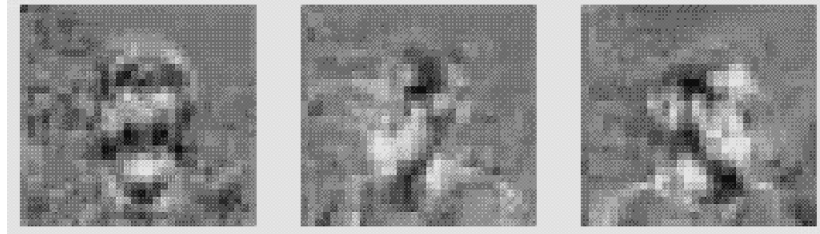


Layer-1
Layer-3
Layer-5
Input

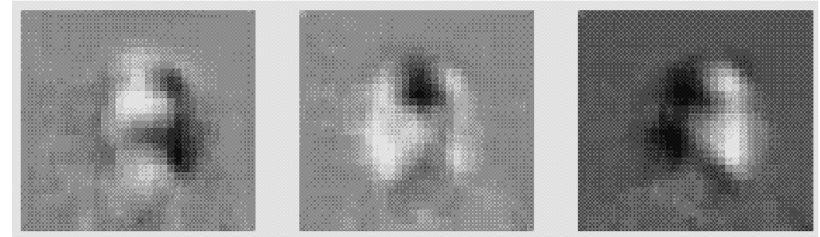
Face Recognition (Mitchell, 1997)



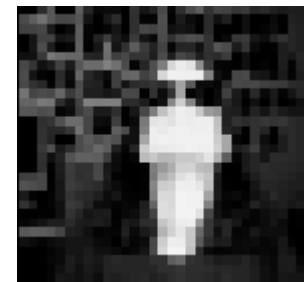
Output Layer Weights (including $w_0 = \theta$) after 1 Epoch



Hidden Layer Weights after 25 Epochs



Hidden Layer Weights after 1 Epoch



- 90% Accurate Learning Head Pose, Recognizing 1-of-20 Faces
- <http://www.cs.cmu.edu/~tom/faces.html>

ALVINN (Pomerleau, 1996)

- network controlled steering of a car on a winding road
- network inputs: 30 x 32 pixel image from a video camera, 8 x 32 gray scale image from a range finder
- 29 hidden units
- 45 output units arranged in a line corresponding to steering angle
- achieved speeds of up to 70 mph for 90 minutes on highways outside of Pittsburgh



Tabulation of Some Large Backpropagation Examples

application	#weights	#samples	error	ref.
text -> speech	25000	5000	0.20	Sejnowski
sonar target rec	1105	192	0.15	Gorman
car control	>36000	1200	car drives on winding road	Pomerleau
back-gammon	>11000	3000	computer champion	Tesauro
sex rec from faces	>36000	90	0.09	Golomb
char rec	9900	5000	0.055	Sato
remote sensing	1800	50	0.05-0.10	Kamata
signature verif.	480	280	0.05	Sabourin

- T.J. Sejnowski and C.R. Rosenberg, *NETtalk: a parallel network that learns to read aloud*, The John Hopkins University Electrical Eng. and Comp. Science, 1986.
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