## Not-ROS

Circa 2010: FLAIL (for a true CS 0)

Circa 2011: FLAIL 2 (for a unit at Elon)

## Stories from Elon:

The hardware hiccups were incredibly annoying and inconvenient and definitely detracted from the experience.

The camera didn't work well with the laptop and made it frustrating but I don't think it detracted from the unit at all.

(I don't believe this for a second)

The most difficult thing for me was my frustration with the camera lag.

## ROS (without ROS)

http://bitbucket.org/macmason/rosflail