SEGMENTING MULTIVARIATE TIME SERIES WITH INERTIAL HMMS

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Motivation

Yahoo! monitors millions of time series each day, looking for changes in the signals for advanced analytics.

Goal: Given a multivariate time series, find where systematic changes occur and map segments to a small number

Dataset

- 45D human activity accelerometer data
 - Activities included jumping, playing basketball, rowing, ascending stairs and walking.
 - Created 100 time series consisting on different combinations of activities and segmentations, 10K time steps each series.
 - Tested inertial methods performed vs standard HMM and Sticky HDP-HMM of Fox et al.

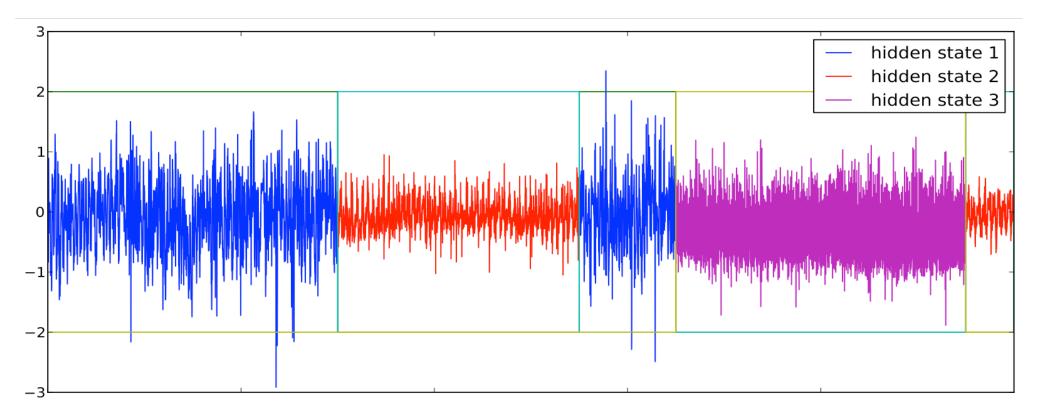
Results

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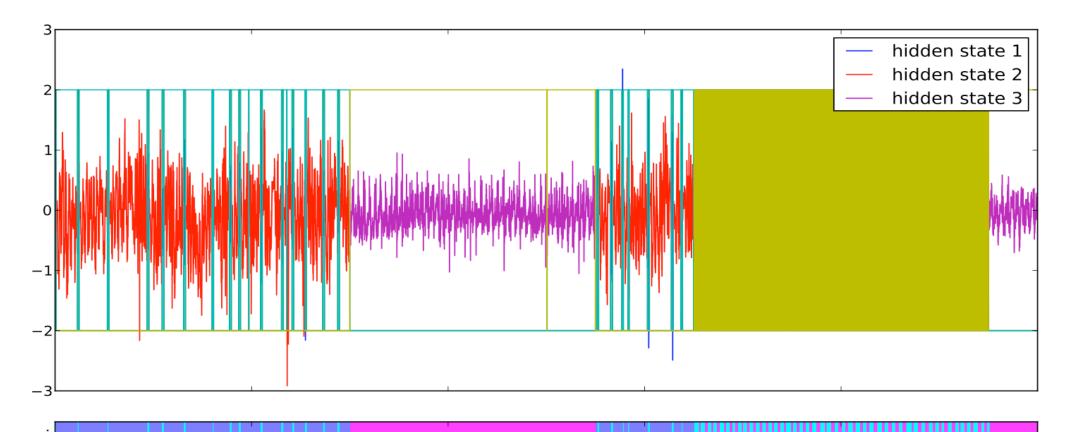
MAP Inertial HMM – Example Segmentation



of states.

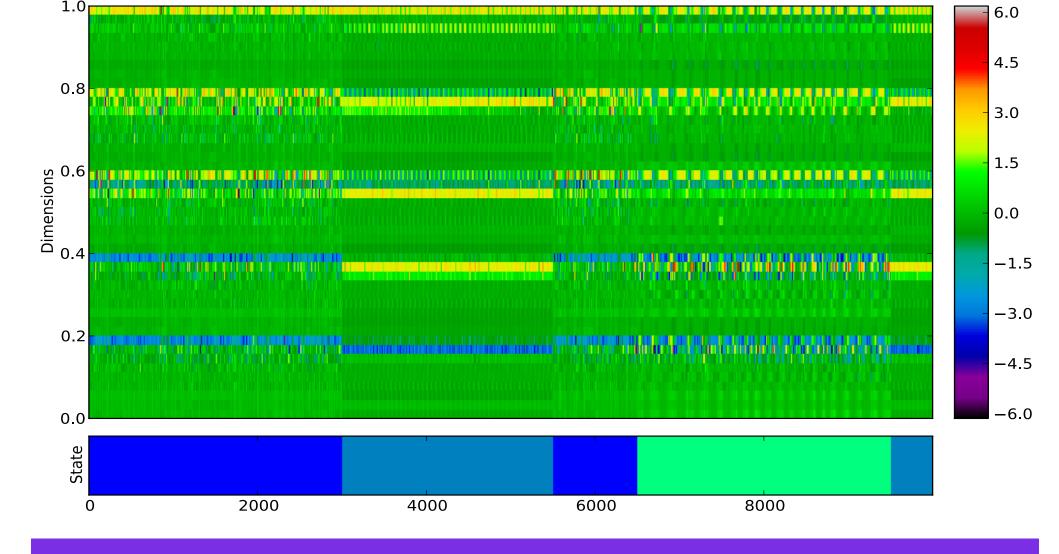
Hidden Markov Models

- Work well for segmenting sequential data.
- However, may over-segment.
- We need to impose state-persistence, i.e., few state changes over time.





Inertial HMMs

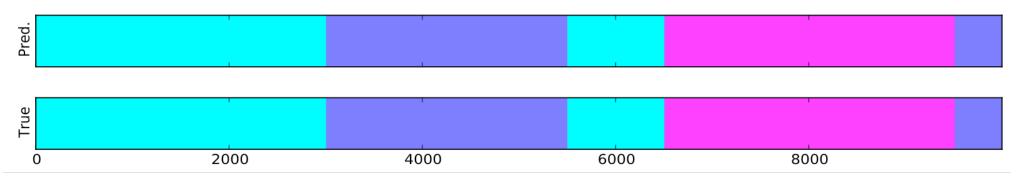


Evaluation Metrics

- Evaluated using:
 - Accuracy (for best permutation of labels)
 - Variation of Information
 - Number of Segments Difference (not shown)
 - Segment Number Ratio (not shown)

Sticky HDP-HMM

 State-of-the-art Bayesian hierarchical Dirichlet process hidden Markov model.



Extensions

Automated parameter selection for inertial HMMs.

- Used to select parameters in Results section.
- Online learning of inertial HMM model.

Main Advantages

- Works well on synthetic and real-world data.
- Very simple (change single update equation).
- Computationally efficient.
- Only two parameters, one automatically selected.
- Does not suffer from extreme sensitivity to parameter settings, as does sticky HDP-HMM.

Two models which impose state persistence through a change to the likelihood model and corresponding expectation maximization (EM) update equations.

MAP Inertial HMM

- Include Dirichlet prior on transition matrix.
- Governed by a strength parameter, ς
- Pseudo-Observation Inertial HMM
- Alter the complete datalikelihood to include fictional self-transition observations.
- Governed by strength parameter, ς.
- $\mathbf{A}_{ij} \propto \begin{cases} ((T-1)^{\xi} 1) + B_T & i = j \\ B_T & i \neq j \end{cases}$

- Used publically available HDP-HMM toolbox, with default parameters for priors.
- κ parameter, for "stickiness" of states.
- Truncation parameter *L* set to correct number of states.
- Sensitive to prior parameter values (see Results).

Results		
Method	Accuracy	Var. of Info.
Standard HMM	0.79	0.38
Sticky HDP-HMM (κ = 100.0)	0.59	0.97
MAP Inertial HMM $(\varsigma = 33.5)$	0.94	0.14
PsO Inertial HMM (ς = 49.0)	0.94	0.15

Conclusion

- Simple modification of standard HMMs performs well on unsupervised segmentation task.
- Strongly outperforms state-of-the-art sticky HDP-HMM with default parameters.

References

Emily B Fox, Erik B Sudderth, Michael I Jordan, Alan S Willsky, et al., *A sticky HDP-HMM with application to speaker diarization*, The Annals of Applied Statistics 5 (2011), no. 2A, 1020–1056.

