



# Ensemble Methods: Bagging

Instructor: Jessica Wu -- Harvey Mudd College

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Robot Image Credit: Viktoriya Sukhanova © 123RF.com

## Ensemble Methods Basics

Learning Goals

- Describe the goal of ensemble methods

# Basic Idea

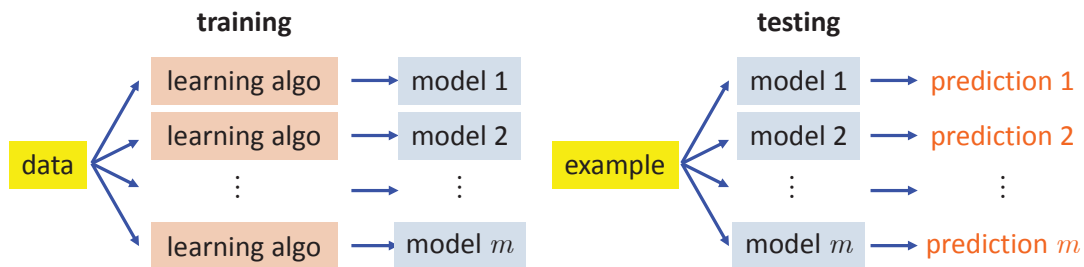
If one classifier works well...

why not use multiple classifiers!?!

Ensemble: “All the parts of a thing taken together so that each part is considered in relation to the whole.”

ML Ensemble:

**Combine multiple classifiers** to improve prediction

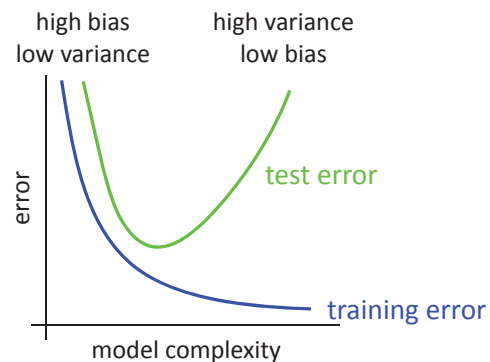


Based on slide by David Kauchak

## Bias vs Variance

Recall ML balances

- estimation error (variance)
  - precision of match
  - sensitivity to training data
- structural error (bias)
  - distance from true relationship



Goals

- Reduce variance without increasing bias
- Reduce bias and variance

# Benefits of Ensemble Learning

Setup (for example)

- Assume a binary classification problem
- Suppose that we have trained 3 classifiers  $h^1(\mathbf{x})$ ,  $h^2(\mathbf{x})$ ,  $h^3(\mathbf{x})$ , each with a misclassification rate of 0.4
- Assume that decisions made between classifiers are independent
- Take majority vote of classifiers

model 1	model 2	model 3	probability of this combination
c	c	c	

What is the probability that we make a mistake?



# Benefits of Ensemble Learning

In general, for  $m$  classifiers with  $r$  probability of mistake,

$$h(\mathbf{x}) = \arg \max_{y \in \{+1, -1\}} \sum_{b=1}^m \mathbb{I}[h^b(\mathbf{x}) = y]$$

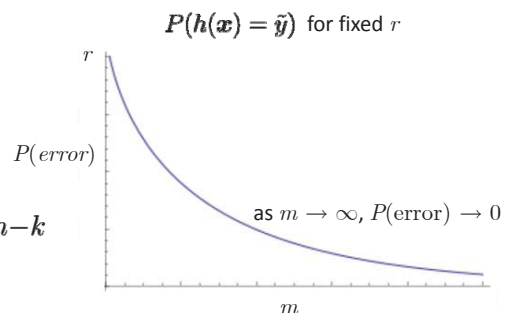
Let  $B = \sum_{b=1}^m \mathbb{I}[h^b(\mathbf{x}) = \tilde{y}]$  be # of “votes” for wrong class.

Then  $B \sim \text{binomial}(m, r)$ .

$$P(k; m, r) = \binom{m}{k} r^k (1-r)^{m-k}$$

$$\begin{aligned}
 P(h(\mathbf{x}) = \tilde{y}) &= P(k > \frac{m}{2}; m, r) \\
 &= \sum_{k=\frac{m+1}{2}}^m \binom{m}{k} r^k (1-r)^{m-k}
 \end{aligned}$$

[cumulative probability distribution for binomial]



# Bagging and Random Forests

## Learning Goals

- Describe bagging
  - How does bagging improve performance?
- Describe random forests
  - How is random forest related to DTs and bagging?

## Combining Classifiers

- **averaging**
  - final hypothesis is simple vote of members
- **weighted averaging**
  - coefficients of individual members trained using validation set
- **stacking**
  - predictions of one layer used as input to next layer

averaging reduce variance (without increasing bias)

$$\text{var}(\bar{X}) = \frac{\text{var}(X)}{m} \quad (\text{when predictions are independent})$$

But how do we get independent classifiers?

# Obtaining Independent Classifiers

Idea: Use different learning methods

## Pros

- Lots of existing classifiers
- Can work well for some problems

## Cons

- Often classifiers are not independent (they make same mistakes!)
  - E.g. many classifiers are linear models
  - Voting will not help if they make the same mistakes

Successful ensembles require **diversity!**

achieving diversity

cause of mistake	diversification strategy
difficult pattern	
overfitting	
noisy features	

Based on slides by David Kauchak and Eric Eaton



# Obtaining Independent Classifiers

Idea: Split up training data

(use same learning algorithm but train on different parts of the data)

## Pros

- Learning from different data so cannot overfit to same examples
- Easy to implement
- Fast

## Cons

- Each classifier only trained on small amount (e.g. 10%) of data
- Not clear why this would do better than training on full data and using good regularization

Based on slide by David Kauchak

# Obtaining Independent Classifiers

Idea: **Bagging** (Bootstrap Aggregation)

## Bootstrap Sampling

- Use training data as proxy for data-generating distribution
- Given  $S_n$  with  $n$  training examples, create  $S_n'$  by sampling with replacement  $n$  examples

## Bagging

- Create  $m$  bootstrap samples  $S_n^{(1)}, \dots, S_n^{(m)}$
- Train distinct classifier on each  $S_n^{(i)}$
- Classify new example by majority vote / averaging

Based on notes and slides by Eric Eaton and David Sontag

## Bagging Best Case Scenario

$$\text{var}(\text{bagging}(L(h, S_n))) = \frac{\text{var}(L(h, S_n))}{m}$$

In practice:

- models correlated so reduction smaller than  $1/m$
- model trained on fewer training samples so variance usually somewhat larger

Based on slide by David Sontag

# Bagging Concerns

Will bootstrap samples all be basically the same?

For data set of size  $n$ , what is the probability that a given example will not be selected in a bootstrap sample?

probability that example is not chosen the first time = \_\_\_\_\_

probability that example is not chosen any of  $n$  times = \_\_\_\_\_

for large  $n$ ,  $\exp(x) = \lim_{n \rightarrow \infty} \left(1 + \frac{x}{n}\right)^n$

so \_\_\_\_\_ converges to \_\_\_\_\_

probability that example is chosen in any of  $n$  times = \_\_\_\_\_

on average,

a bootstrap sample contains \_\_\_\_\_ of training examples

Based on notes and slides by Jenna Wiens and David Kauchak



## When does Bagging work?

- Bagging tends to **reduce the variance** of the classifier
  - By voting, the ensemble classifier is more robust to noisy examples
- Bagging is most useful for classifiers that are
  - Unstable
    - small changes in training set produce very different models
  - Prone to overfitting
- Often has similar effect to regularization

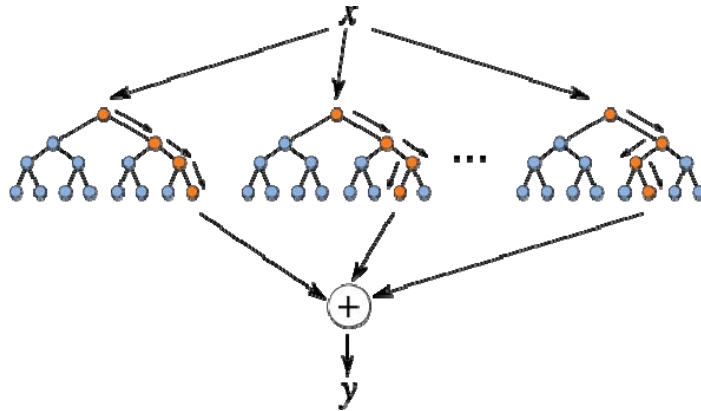
What classifiers have we seen so far with these properties?

Based on slide by David Kauchak

# Random Forests

Introduces two sources of randomness

- bagging
- random feature subset
  - at each node, best split is chosen from random subset of  $k < d$  features



Based on notes by Jenna Wiens [Image by Léon Bottou]

## Random Forest Procedure

for  $b = 1, \dots, m$

draw bootstrap sample  $S_n^{(b)}$  of size  $n$  from  $S_n$

grow random forest  $DT^{(b)}$

output ensemble

[subprocedure for growing  $DT^{(b)}$ ]

until stopping criteria are met, recursively repeat following steps for each node of tree

- select  $k$  features at random from  $d$  features
- pick best feature to split on using info gain
- split node into children

Based on notes by Jenna Wiens